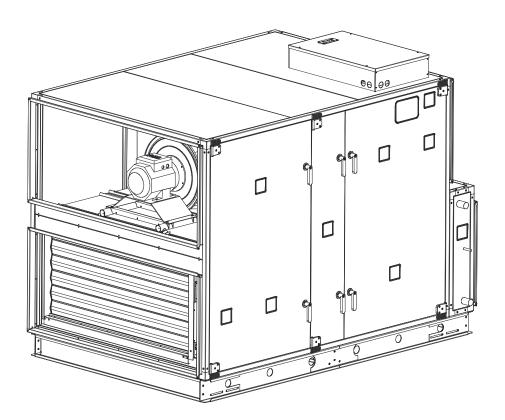
Air Handling Units Danvent DV

With control system



GB User Manual

Transport, installation, start-up and maintenance

Version 1.01.06

Master version for translated User Manuals

Original version for this air handling unit

This manual has part number 90925372

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a. Manufacturer

This User Manual covers all air handling units with control system delivered by Systemair A/S.

Manufacturer and supplier data:

Systemair A/S Ved Milepælen 7 DK-8361 Hasselager

Responsible for documentation: Ulf Bang

b. Name of machines

This manual is about Systemair air handling units with control systems called DANVENT DV10, DANVENT DV15, DANVENT DV20, DANVENT DV25, DANVENT DV30, DANVENT DV40, DANVENT DV50, DANVENT DV50, DANVENT DV100, DANVENT DV120, DANVENT DV150, DANVENT DV190 og DANVENT DV240.

c. Declaration of Conformity - example

The manufacturer:

Systemair A/S Ved Milepælen 7 DK - 8361 Hasselager



Hereby declares that, air handling units of the flowing types:

Delivered with control system

DANVENT DV10, DANVENT DV15, DANVENT DV20, DANVENT DV25, DANVENT DV30, DANVENT DV40, DANVENT DV50, DANVENT DV60, DANVENT DV80, DANVENT DV100, DANVENT DV120, DANVENT DV150, DANVENT DV190 and DANVENT DV240.

TIMEec 10, TIMEec 15, TIMEec 20, TIMEec 25, TIMEec 30, TIMEec 40

Serial No: "YYMM-71800-X"

are manufactured and delivered in accordance with following directives:

Machinery directive 2006/42/EC

EMC – directive 2004/108/EC

Low voltage directive 2006/95/EC

Pressure equipment directive 97/23/EC

European Standard EN378

Equipment type: **DVU-series**

Consisting of: Compressor, evaporator and condenser

Verification and Assessment by:

Notified Body Bureau VERITAS CE0041 for PED N

Bureau VERITAS UK, "Parklands", Wilmslow Road C

Didsbury, Manchester M20 2RE

Module: A1

Certificate no: CE-0041-PED-

A1-SYA-001-10-DNK

The declaration is only valid, if the installation of the air handling unit is carried out according to the instructions delivered with the unit. The installer will be responsible for the CE marking and documentation, if any construction or functional changes are applied to the air handling unit.

Hasselager 24. June 2013



d. General descriptions, dangers and warnings

TIME and DV air handling units are order specific machines available in thousands of different configurations. Only a few examples of machine configurations are described below.

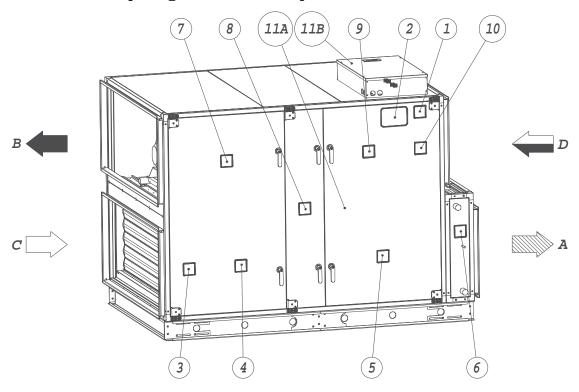
The air handling units are intended for the transport and treatment of air between -40 $^{\circ}$ C and + 40 $^{\circ}$ C The units are exclusively for comfort ventilation.

Maintenance of the units must be carried out by skilled technicians.

On the drawing below, a right hand unit is shown because the inspection doors are mounted on the right hand side of the unit when looked in direction of <u>SUPPLY</u> airflow. The unit below is with rotary heat exchanger.

Position	Description	Symbol
А	Connection, supply air (to the rooms)	
В	Connection, exhaust air	
С	Connection, outdoor air in	
D	Connection, extract air (from the rooms)	

d.1 Overview via pictograms on the inspection side of the unit



This is a right hand unit because the inspection doors are mounted on the right hand side of the unit when looked in direction of <u>SUPPLY</u> airflow.

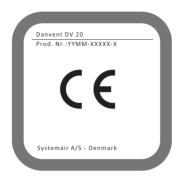
d.1.1 Where are pictograms placed on the units

Example (Symbols and descriptions of functions for fast identification)

Position	Description	Symbol
1	The CE label and the unique production number of this machine	CE
2	Machine card	
3	Damper - supply air	
4	Filter - supply air	\mathbb{M}
5	Fan- supply air	
6	Heating battery - supply air	\oplus
7	Fan - extract air	
8	Rotary heat exchanger	
9	Filter – extract air	\mathbb{M}
10	Damper – extract air	
11A	3 labels. One label with Flowchart, one label with terminal plan for external components and one label listing data about the cabinet. The labels are placed behind inspection doors, if the cabinet with control system is inside the unit.	
11B	3 labels. One label with Flowchart, one label with terminal plan for external components and one label listing data about the cabinet. The labels are placed on the cover of the cabinet, if the cabinet with control system is placed on the top of or on the front of the unit.	

d.1.2 CE label - example for DV unit

This is the mandatory informations for the CE marking with; Product name (in this example Danvent DV 20, where 20 informs about the size of the unit), Production number for the complete unit (in this example YYMM-xxxxx-x, where YYMM informs about year and month for the manufacture), xxxxx-x is the unique production number.



d.1.3 CE label - example for TIME unit

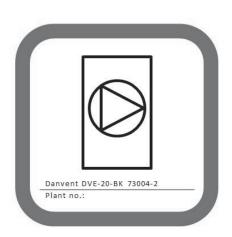
This is the mandatory informations for the CE marking with;

Product name (in this example TIME 40, where 40 informs about the size of the unit), Production number for the complete unit (in this example YYMM-xxxxx-1, where YYMM informs about year and month for the manufacture), xxxxx-1 is the unique production number.



d.1.4 Pictogram on a door for a fan in a DV unit

Example of the pictogram with the symbol for the function - fan, Systemair product name is DVE-20-BK where 20 informs about the size of the unit and BK is Backward Curved fan blades, production number for the complete unit (in this example 73004-2) and the customer's name for the unit, always written after – Plant no:______



d.1.5 Pictogram on a door for a fan in a TIME unit

Example of the pictogram with the symbol for the function - fan, Systemair product name is this example is - Fan Supply, production number for the complete unit (in this example xxxxx-1) and the customer's name for the unit, always written after - Plant no:______



d.1.6 Pictograms for all available functions in the units

Id	Description	Symbol
DVA	Damper	
DVB	Damper	
DVM	Damper for mixing	
DVP	Damper for mixing	
DVG	Panel filter	$\overline{\mathbb{M}}$
DVF	Bag filter	$\overline{\mathbb{M}}$
DVC	Rotary heat exchanger	
DVQ	Plate heat exchanger (cross flow and counter flow)	\Diamond
DVR	Run around heat exchanger	⊝⊕
DVH	Heating battery	⊕

DVK	Cooling battery	Θ
DVU	Integrated cooling with compressor unit	(H)
DVE	Plug fan	
DVD	Silencer	
DVX	Humidifier	F

d.1.7 Pictograms about warnings and dangers on the units

Pictograms according to EN1886 about



Warning about danger by rotating parts



Warning about danger by electricity



Warning about danger by heat

d.2 Data about the unit according to cards and labels in and on the unit

d.2.1 Machine card with unique data on every unit

An example of a machine card is shown below.

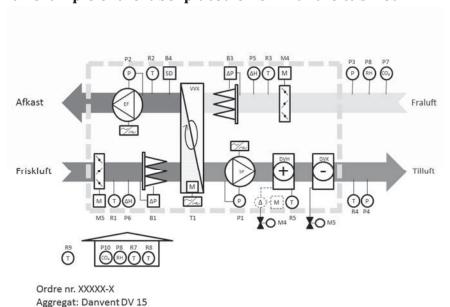
Type Order number	DV-YY XXXXXX-X		Systemair A/S Ved Milepælen 7 DK-8361 Hasselager	
Airflow Total pressure drop Heating Cooling Heatrecovery Heatrecovery Capacity	Supply 10000 m3/h 686 Pa 31.00 kW 57.14 kW 82.7 % 142.8 kW	Extract 10000 m3/h 639 Pa	Tel. +45 87 38 75 00 Email: mail@system	
Fan Fan type K-factor (p=1,2 kg/m3) Fan speed Maximum fan speed Motor type Motor norm size Motor speed Power Voltage	Supply M-RH56Cpro 308 1415 RPM 1460 RPM IE2 ABB-100LD 1445 RPM 3.0 kW 3x400 V	Extract M-RH56Cpro 308 1385 RPM 1460 RPM IE2 ABB-100LD 1445 RPM 3.0 KW 3x400 V	Data for cabinet Ground for unit Current type Frequency Mains supply Ikmax Ikmin Max fuse Min fuse	TN-S AC 50 Hz 3*400+N+PE VAC 16 kA 650 A 25 A 10 A
Filter Filter class Dimensioning pressure drop Initial pressure drop Final pressure drop	Supply F7 130 Pa 71 Pa 189 Pa	Extract F7 130 Pa 71 Pa 189 Pa	Sales agent: Systemair Fans & Spare 72 Cheston Road, Birm England Tel: +44 (0) 121 322 02 http://www.systemair.	ingham, B7 5EJ 200

d.2.2 Label with data about the cabinet

An example of the label that is always placed on or with the cabinet

Systemair A/S Systemair declares hereby that the cabinet is in conformity with: SBB Low voltage N60439-1 panels: Electrical material on EN60204-1 machines: **EMC-directive** 89/336/EOF environment: DV ver. 2.11 Diagram version Systemair order 72800-1 number DV 10-150 Unit size Cabinet data: System ground TN-S Current type AC 50 HZ Frequence 3*400 Rated voltage V+N+PE VAC Control voltage 24 VDC IK max 6 kA IK min 650 A Max fuse 25 10 Min fuse Cable colors: Protection circuit Green/yellow 230 VAC phase Black 0 VAC neutral Blue 24 VDC Grey 0 VDC Grey Analog/digital Grey

d.2.3 Flowchart - example of the label placed on or with the cabinet



d.2.4 Symbols in the flowchart and explanation about the symbols.

Id	Description	Symbol
RX	Temperature sensor - PT1000	(T)
MX	Damper motor - on/off	M
MX	Damper motor – 0-10V	
ВХ	Filter guard - digital	(M)
PX	Pressure transmitter – 0-10V	ΔΡ
		P
PX	Sensor for relative humidity – 0-10V	RH
PX	Sensor for CO ₂ = 0-10V	CO ₂
T110	Controller for rotary heat exchanger – 0-10V	M

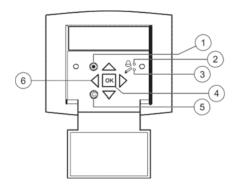
d.2.5 Example of label placed on or with the cabinet – Terminal plan for external components

Product Description	Product Terminal	Cable	Wire	Switchboard Terminal
Main power		W1000	L1 L2 L3 N G/G	X1:L1 X1:L2 X1:L3 X1:N X1:PE
M15	L N PE	W100	1 2 G/G	X2:3 X2:4 PE
Reduced speed / Stop unit		W380	1 2	X3:10 X3:11
Normal speed / Start unit		W381	1 2	X3:12 X3:13
Ext. Fire signal				X3:13 X3:15
R4		W311	1 2	X3:20 X3:21
R9		W363	1 2	X3:22 X3:23
R5		W314	1 2	X3:23 X3:24
P4	24V 0-10V ANG	W340	1 2 3	X3:25 X3:26 X3:27
P8	24V 0-10V ANG	W354	1 2 3	X3:29 X3:30 X3:31
Р3	24V 0-10V ANG	W341	1 2 3	X3:32 X3:30 X3:31

Product Description	Product Terminal	Cable	Wire	Switchboard Terminal
	ANG		1	X3:42
M6	24V	W320	2	X3:43
	0-10V		3	X3:41
	ANG		1	X3:42
M7	24V	W321	2	X3:43
	0-10V		3	X3:44
Repeater	EO-R 1G	W90	1	X3:45
repeater	EO-R 2GO	*****	2	X3:46
Heating active	"NO"			X3:48
				X3:49
Alarm signal	"NO"			K4:11
71141111 0191141				K4:14
Operating signal	"NO"			K8:21
				K8:24
Changeover	"NO"			X5:11
signal				X5:12
Rec. Signal	"NO"			X5:13
				X5:14
	24V		1	X5:14
P9	0-10V	W353	2	X5:16
	ANG		3	X5:15
R7		W360	1	X5:21
			2	X5:22
R8		W361	1	X5:23
			2	X5:24
Circulation pump				X5:32
start				X5:34

d.3 Hand terminal (optional for DV units - always standard for TIME units)

The hand terminal is delivered in a cardboard box containing the other external components. This cardboard box is usually, but not always, placed in the section with the supply air fan. The Operator's Guide for the hand terminal is the annex 17 attached to this – User Manual.



- 1. ALARM: Press for alarm list
- 2. Alarm LED red light for alarm
- 3. LED indicating change of parameters
- 4. OK/ENTER
- 5. Press for clear
- 6. Press for move of curser in menu

Important! All LEDs on the hand terminal must be off before startup of the unit.

d.4 Dimensions of the units - selected examples.

* DV 10-150 : Height excl. base frame DVZ. DV 190-240 : Height incl. base frame.

Examples on dimensions of selected configurations below. Other configurations have other dimensions.

Rotary Heat Exchange	Unit size														
7		10	15	20	25	30	40	50	60	80	100	120	150	190	240
Standard	Width	970	1120	1270	1420	1570	1720	2020	2170	2170	2370	2590	2890	3190	3490
Rotary Heat Exchanger	Width	-		-	100	=	-	-	3=	2320	2520	2890	3040	3720	4020
Single height unit	Height*	520	595	670	745	820	895	1045	1120	1270	1420	1570	1720	2170	2470
Double height unit	Height*	970	1120	1270	1420	1570	1720	2020	2240	2540	2840	3140	3440	4340	494
* CEN EE *	Length	2160	2160	2460	2460	2760	3060	2910	3280	3210	3960	4260	4560	5010	5530
C1E →	Weight kg	430	520	660	760	920	1100	1470	1980	2140	2630	3250	3990	6290	7610
# G	Length	2910	2910	3210	3210	3510	3810	3660	4030	4030	4930	5230	5530	5980	643
C2E → □□□□□ →	Weight kg	500	610	770	870	1080	1270	1690	2250	2470	3050	3890	4690	7220	8600
+ CANDS +	Length	2680	2680	3130	3130	3430	3880	4030	4400	4400	5450	5900	6200	6430	710
C3E → D00 →	Weight kg	480	580	730	810	1010	1220	1700	2230	2480	3160	3870	4660	6870	828
# CAN DE #	Length	3430	3430	3880	3880	4180	4630	4780	5220	5220	6420	7020	7170	7400	800
C4E →	Weight kg	560	660	840	930	1180	1390	1930	2560	2830	3610	4560	5320	7790	9180
*	Length	2680	2680	3130	3130	3430	3880	3730	4100	4100	5080	5380	5680	6430	7100
C5E → 1 100 →	Weight kg	480	570	720	800	1010	1220	1630	2120	2330	2970	3620	4390	6860	8280
* I	Length	3430	3430	3880	3880	4180	4630	4480	4850	4850	6050	6350	6650	7400	8000
C6E → 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	Weight kg	550	660	840	920	1180	1380	1850	2410	2670	3370	4280	5060	7790	9170

Plate Heat Exchanger		Unit size													
		10	15	20	25	30	40	50	60	80	100	120	150	190	240
	Width	970	1120	1270	1420	1570	1720	2020	2170	2170	2370	2590	2890	2	
Single height unit	Height*	520	595	670	745	820	895	1045	1120	1270	1420	1570	1720	-	
Double height unit	Height*	970	1120	1270	1420	1570	1720	2020	2240	2540	2840	3140	3440		ı ö .
Q1E *	Length	3210	3580	4030	4330	4780	5080	5230	5460	5230	5910	6960	7260	ĕ	-
♦	Weight kg	570	760	940	1130	1370	1640	2300	2550	2610	3210	4200	5130	-	-
Q2E + C C C C C C C C C C	Length	3960	4330	4780	5080	5530	5830	5980	6210	5980	6880	7930	8230	=	-
	Weight kg	660	850	1060	1260	1540	1810	2520	2880	2910	3660	4870	5790	-	-
*	Length	3800	4100	4700	5000	5450	5900	6050	6280	6280	7330	8380	8680	ä	-
Q3E ← CE	Weight kg	650	820	1030	1140	1470	1760	2480	2720	2840	3620	4600	5550	-	-
→	Length	4550	4850	5450	5750	6200	6650	6800	7030	6800	8000	9050	9350	-	-
Q4E + 01 1000 +	Weight kg	720	900	1140	1310	1630	1930	2720	3030	3130	3980	5150	6130	-	-
*	Length	3800	4100	4700	5000	5450	5900	6050	6280	6130	7030	8080	8680	-	-
Q5E + 3 - 1 - 0 - >	Weight kg	640	810	1020	1170	1480	1750	2460	2700	2890	3690	4690	5840	-	-
*	Length	4550	4850	5450	5750	6200	6650	6800	7100	6800	8000	9050	9350	2	
Q6E + 1000	Weight kg	720	900	1140	1300	1620	1920	2700	3030	3200	4120	5320	6380	-	2

d.5 Ordinary automatically operation – only manual operation by new parameters.

The unit is operating fully automatically and manual operation includes only selection of new parameters via the buttons on the hand terminal. The hand terminal is connected by a cable to the controller in the cabinet. 10 meters of cable is delivered with the unit and the customer has the possibility to replace this cable with an identical type of cable that is up to 100 meters long. The alternative is that the controller is connected to a BMS system with the ability to select new parameters via PC, tablet, SmartPhone or mobile phone.

d.6 Warnings about dangers

Pictograms are according to EN1886 about;



Warning about danger by rotating parts



Warning about danger by electricity



Warning about danger by heat



Disregards of instructions shown on warning signs are connected by risk for injury or damage on material.

e. Drawings, diagrams, guides and instructions for the use, maintenance and repair

All DV units with integrated control system and TIME units are manufactured in compliance with the EC Declaration of Conformity and they are CE marked as machines. Unique Declaration with production number of the machine is an integral part of the machine – enclosed as annex 1 to this manual. If the buyer carries out changes or adds components in or on the machine, the buyer must issue a new EC Declaration of Conformity and a new CE marking of the machine. To promote correct use of the machines, the below-mentioned instructions are an integral part of the machine:

- Unique drawings, data and description of functions for the delivered unit annex 2
- Wiring diagrams annex 16
- Operator's Guide annex 17

- Instructions for use of the machine section k in this manual
- Instructions about adjustment and maintenance section r in this manual
- Safety during adjustment and maintenance section s

f. Employees in charge of operation/control/maintenance

The unit is able to operate fully automatically when the installer has started, adjusted and handed over the faultless unit to the staff that takes care of operation, control and maintenance.

f1. Employees that take care of ordinary operation

Indications of operation status as well as indication of faults are visible in the display and on the LED's of the hand terminal. The employees can enter new parameters in the controller via the buttons on the hand terminal. The alternative is that the controller is connected to a BMS system with the ability to select new parameters via PC, tablet, SmartPhone or mobile phone.

g. Intended use and range of applications

The air handling units are intended for the transport and treatment of air between -40 °C and + 40 °C The units are exclusively for comfort ventilation and not for air that causes severe corrosion to galvanized steel and to copper and aluminum. The units are not for environments that exceed the corrosion class C4 according to EN ISO 12944-2.

Intended applications for the units are:

Offices, teaching rooms, hotels, shops, homes and similar comfort zones.

h. Unintended use and misuse – inappropriate applications for the machine

The air handling units are not suitable for transport of air with risk of explosion and with Ex-Classification. Do not install the units in Ex-areas at all.

Do not install units outdoors unless the units are constructed for outdoor installation. Units not suitable for outdoor installation are units without roof and units with cabinet installed on the unit (the cabinet is installed inside the unit for outdoor installation).

The units are not for environments that exceed the corrosion class C4 according to EN ISO 12944-2, and the units are not for transport of solid particles.

Not intended applications for the units are:

Kitchen extraction, swimming pools, off-shore, Ex-areas, drying of washed clothes.

Do not use the unit with partly finished duct systems. Do not use the unit for ventilation of the building site until the unit is properly provided with guards.

h.1 Air handling unit in operation

The pressure difference between interior and exterior of the unit must not exceed 2000 Pa for the DV 10 and up to DV 150 (including DV 150), and 1500 Pa for DV 190 and DV 240.

Before start-up of the unit all ducts, guards and all protective devices must be mounted to prevent any access to rotating fan impellers. All inspection doors must be closed and locked when the unit is in operation.

Do not use the unit without filters.

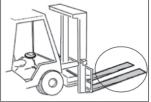
i. Instructions for unloading on the site as well as installation and connection

i.1. Unloading on the site

The air handling unit – AHU - is delivered as one section or in several sections, which are to be assembled on site. The AHU is delivered on transport pallets, legs or on a base frame. Loading and unloading as well as transport on the site is possible by fork-lift truck or by crane using suitable lifting straps.

i.1.1 Unloading by fork-lift truck

The forks of the truck must be sufficiently long to avoid any damage to the AHU underside.



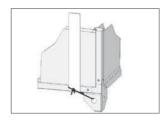


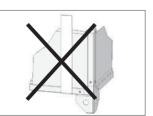
i.1.2 Unloading by crane

AHU delivered on transport pallet must be lifted by straps as shown in the illustration.



AHU delivered with legs must be lifted by straps secured to the legs as shown in the illustration.





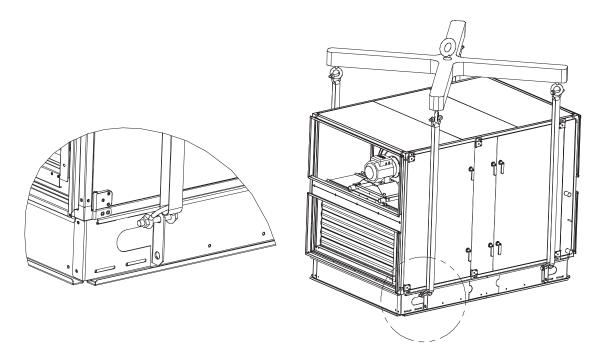
i.1.3 Transport of unit without base frame on the site

Units without base frame are always delivered in sections with each section on a pallet. Sections can be transported on the site by hand manual forklifts.

i.1.4 Lifting a unit with straps

Use an appropriate lifting beam with a sufficient span to avoid that the straps touch and damage the drip nose profiles and the inspection side with handles, pipes and accessories – for example manometers, cabinets, tabs for measuring the pressure.

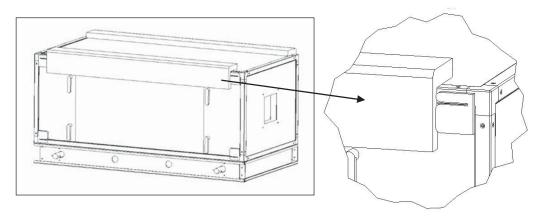
i.1.5 Lifting a unit with preinstalled brackets on the base frame for lifting.



Lifting beam and straps are not included in the delivery.

i.1.6 Roof unit with bitumen roof

Avoid damaging the drip nose profiles along the bitumen roof. Keep the protection profiles of Styrofoam on the unit until the installation has been completed. If the unit is lifted by straps, the straps must be kept away from the drip nose profiles by bars to avoid damage to roofing profiles.



i.1.7 Roof unit with steel roof

For units with steel plate roof, the steel plates are delivered uninstalled on a separate pallet. Do **not** step or walk on the plates.



i.1.8 Pre-assembly storage

The AHU must be protected from the weather and accidental impact. Plastic packaging **must** be removed and the unit covered with tarpaulin or similar materials. In order to minimize condensation, sufficient air circulation must be ensured between the covering and the unit.

i.1.9 Tilt less than 30° during transportation of the section with cooling compressor – DVU or DVU-C

During transportation, the unit section - DVU or DVU-C- <u>must</u> always be in the upright position or tilted less than 30°. If it is necessary to tilt the unit more than 30°, the suction pipe of the compressor must point upwards to prevent the escape of oil from the compressor sump.

i.2. Installation - mechanical

i.2.1 Free area in front of and above the unit

Important! When positioning the unit on the site, it must be ensured that an area with the same width as the unit is kept free for service and inspection and also for replacement of fans and exchanger, if needed. The width of the free area must be at least 900 mm.

Important! For safe access to the cabinet with electrical components, if the cabinet is placed on top of the unit, the free area from the upper edge of the cabinet to the ceiling must be at least 700 mm.

i.2.2 Supporting surface

The surface beneath the unit must be level, horizontal and vibration-free. The surface must be able to withstand the load of the AHU. Weights of the sections are written in Annex 2.

Remember! Duct work must be sound insulated and must not be mounted directly on beams, trusses or other critical building parts.

i.2.3 Adjustable feet under legs or base frame and transport of sections

Adjustable feet are provided in a carton box placed inside the unit. Adjustable feet are delivered for indoor units and not for outdoor units.



Sections can be transported on the site by hand manual forklifts or similar. The frame profiles in the edges of the sections have carrying capacity for lifting by the hand manual forklifts.

i.2.4 Base frame assembly

The base frame is delivered unassembled and has to be assembled on the site before it is possible to position and assemble the various sections of the AHU. Assembly of the base frame is illustrated on 4 pages in a manual that is always in a plastic folder and is attached to one of the large base frame parts. This manual is available on the site among the base frame parts.

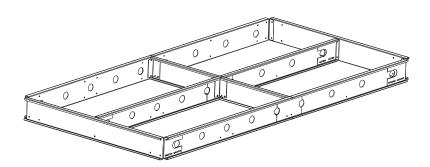
There are two types of base frames:

- 1. 150 mm high base frames
- 2. 250 mm high base frames

There are 4 different manuals and each of them illustrates the assembly of the 4 different types of base frames:

- 1. Manual about the 150 mm high base frames for AHUs in the sizes from DV 10 to DV 40. The name of this manual is **Base frame 150 DVZ 10 40**
- 2. Manual about the 150 mm high base frames for AHUs in the sizes from DV 50 to DV 150. The name of the manual is **Base frame 150 DVZ 50 150**
- 3. Manual about the 250 mm high base frames for AHUs in the sizes from DV 10 to DV 40. The name of the manual is **Base frame 250 DVZ 10 40**
- 4. Manual about the 250 mm high base frames for AHUs in the sizes from DV 50 to DV 150. The name of the manual is **Base frame 250 DVZ 50 150**

Example of 150 mm high base frame for AHUs in the size from DV 50 to DV 150



Mount adjustable feet with a distance of maximum 1500 mm between each foot under the base frame. The base frame can now be levelled by the adjustable feet. The next step is to place and assemble AHU sections on the base frame.

i.2.5 Base frames for outdoor units

Outdoor units must be installed on 250 mm high base frames and are always fitted to the AHU sections. Hot-dip galvanized base frames are recommended for outdoor units. Systemair delivers these base frames without the above mentioned adjustable feet.

i.2.6 Installation on the site of unit sections at the base frame when sections are delivered on pallets.

Lift up the section by hand manual forklifts to the level where the underside of the section is even with the overside of the base frame.

1. Pull the section to the correct position on the base frame by lifting straps – it is maybe necessary to support the section by heavy duty furniture trolleys (see the photos below)



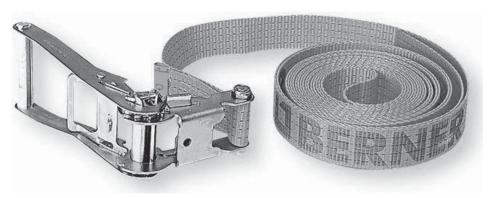
Example of heavy duty furniture trolley turned with the wheels upwards. Placed in this way on the forks of the hand manual forklifts the heavy duty furniture trolleys are suitable for safe and careful rolling of the unit sections over to the base frames.



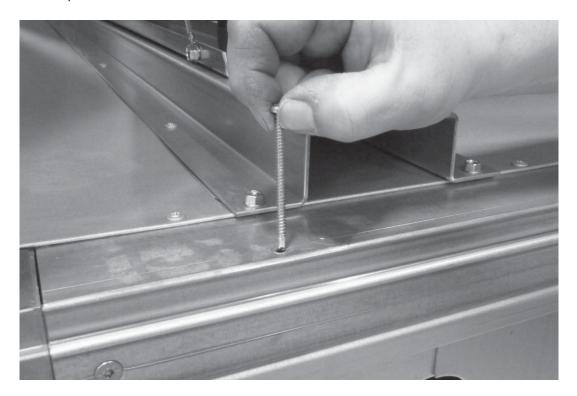
Example of very heavy duty furniture trolleys. Turned with the wheels upwards and placed on the forks of hand manual forklifts these heavy duty furniture trolleys are very suitable for safe and careful rolling of the unit sections over to the base frames.

2. Pull sections together with lifting straps. We recommend the below shown type of brackets because this type is not damaging the frame profiles of the units. An example of lifting straps is shown below.





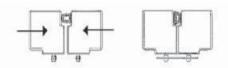
3. Sections are mounted to base frames with long self-drilling screws. The frame profile under the inspection doors is placed over the horizontal profile of the base frame. See the example on the photo below.



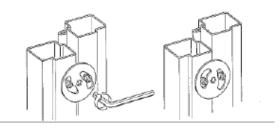
i.2.7 Joining the AHU sections

The sections must be placed on the base frame and if the unit is delivered with 100 mm legs, the sections must be positioned directly opposite each other.

- 1. Ensure that the internal factory-fitted rubber sealing is undamaged
- 2. The sections are then to be positioned directly opposite each other. If the sections are built with legs, the adjustable feet can be used to get the sections parallel and at the same height.
- 3. Press the sections hard together so that the rubber profiles are so flat that the iron frames of the two sections are joined. Straps with tensioner as shown below are suitable for pressing the sections hard together.



4. The sections are then to be locked permanently together with the black plastic-coated Systemair Disc-Locks. The Disc-Locks are delivered in a carton box placed inside the unit. Place each Disc-Lock over the 2 factory fitted locking pins. The discs and locking pins are not reliable for pulling the sections together. They are only sufficient for keeping the sections well together, so just turn each disc gently with the supplied Allen key. Use a sequence where each disc is tightened with only one click at a time. If the unit is placed too close to a wall with no space left for the mounting of Systemair Disc-Locks, brackets must be placed inside the unit to keep the sections permanently together (brackets for this purpose are not delivered by Systemair)



i.2.8 Fitting the ductwork

Flexible duct connections between AHU and ductwork must always be installed. Be sure that flexible duct connections are almost fully stretched. (Flexible connections are ordered as accessories and they are placed inside the unit). At the fan outlet on a centrifugal fan, the duct size should be as close to the outlet size as possible. Avoid blockage and turbulence at the fan outlet.

i.2.9 Risk of stack effect by vertical ducts and wind pressure on louvers

On special occasions stack effect – also called chimney effect – in the ducts create airflows that drives the impellers by turned off motors.

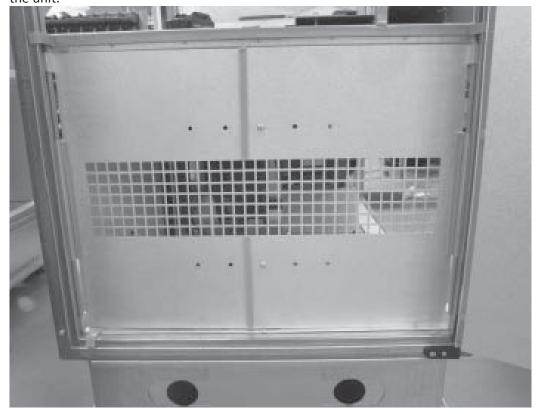
A rotating impeller is a potential hazard during cleaning and maintenance of the unit.

Eliminate this airflow by dampers with spring return motors for automatic closing of the dampers - even by power failure.

Important! The Systemair air handling units can be ordered and delivered without dampers, and the installer/user must check that duct systems with the described risk of stack effect (chimney effect) will be provided with dampers and spring return motors.

i.2.10 Refitting of guards

The guard is a safety guard installed inside the door. Tools are necessary for the removal of the guard. If the guard has been demounted during the installation on the site, the guard must be refitted before startup of the unit.



Insert the edges of the guard in the frame profile in the groove that is in the frame profile, and connect both parts of the guard at the middle with 2 screws.

Replace the vibration damping foam rubber list if it is damaged.

i.3. Installation - electrical

i.3.1 Description

The position of components is shown and described in annex 2.

Connections to terminals are shown in the wiring diagram – annex 16.

When control of constant pressure in the ducts (also called demand controlled capacity) is required, the pressure transmitters must measure in the duct system at places where all pressure changes can be registered accurately for reliable pressure control. This placement is left to the customer's free choice. It is important to achieve a constant pressure – also for the most faraway diffusers.

i.3.2 Wiring diagrams

The wiring diagrams are printed in separate manuals delivered with the units as annex 16.

The wiring diagrams are not unique for the order specific units, but it is standard wiring diagrams with data about all configurations of the units. Hereby the wiring diagrams will inform about components that are not ordered and delivered. See the order confirmation and annex 2 with exact information about the accessory components that are ordered and delivered.

The wiring diagram includes:

General description, Circuit diagrams, Cabinet layout, Terminal matrix and Cable plan.

The wiring diagrams are on the DVD delivered with every unit.

i.3.2.1 TIME units - labels on the cabinet next to the supply fan

- Label with data about the cabinet including data about fuses see section d.2.2
- Flowchart see section d.2.3 standard and not unique for the order specific unit
- Label with terminal plan for external components see section d.2.5 standard, and not unique for the order specific unit

i.3.2.2 DV units - labels on or with the cabinet

- Label with data about the cabinet including data about fuses see section d.2.2
- Flowchart see section d.2.3 unique for the order specific unit printed with the unique production number of the unit
- Label with terminal plan for external components see section d.2.5 standard, and not unique for the order specific unit

i.3.3 Installation of mains power supply

An AC/DC residual current device must be installed in the power supply. The power supply for the units is 3*400 V + N + PE - 50 Hz. Protection of the units in accordance with the local statutory requirements for the additional protection of systems with frequency converters.

i.3.3.1 Necessary mains power supply for TIME units with ec motors and without DVU

Necessary mains power supply in the table below and in the wiring diagram in annex 16. This information is also printed on the unique machine card placed on the front of every unit (see example of a machine card in section d.2.1).

Unit	Motor	Fuse	Fuse	Maximum
		Minimum	Maximum	Short-circuit current
TIME 10	2*0.94 kW	10A	16A	16kA
	2*0.99 kW			
TIME 15	2*0.99 kW	10A	25A	16kA
	2*1.7 kW	13A		
TIME 20	2*1.7 kW	13A	25A	16kA
	2*3.0 kW			
TIME 25	2*3.0 kW	13A	25A	16kA
	2*2.73 kW	13A		
TIME 30	2*2.73 kW	20A	32A	16kA
	2*5.18 kW			
TIME 40	2*5.18 kW	20A	32A	16kA
	2*4.7 kW	20A		

i.3.3.2 Necessary mains power supply for DV units with cabinet/control system

Necessary mains power supply is printed on the unique machine card placed on the front of every unit (see example of a machine card in section d.2.1).

i.3.3.3 Necessary overvoltage protection device, that leads lightning overvoltage to an earth lead on a safe way.

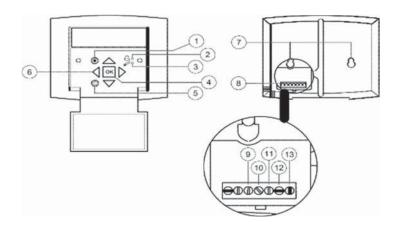
The Installer and user must be aware of the fact that lightning strikes make a risk that requires installation of overvoltage protection devices to lead the lightning overvoltage to an earth lead in a safe way. Installer and user must take care of this according to local statutory requirements.

i.3.4 Electrical connection of components and functions

External components and functions are delivered according to the order confirmation. Cable number's are written on the cables, on the label with terminal plan on or with the cabinet – see section d.2.5 and in the wiring diagrams – annex 16.

i.3.4.1 Connection of the Systemair Control Panel to the Corrigo E28 controller – software version 3.3

The SCP panel – part number S-208997 for software version 3.3 - is provided with 10 metres of cable and a socket for connection with the controller inside the cabinet. The cable is not pulled through the cable entry in the cabinet, so demount the cable at the back of the Systemair Control Panel - pull the cable through the cable entry in the cabinet - adjust the length of the cable and remount the cable in the panel, or add more cable – up to 100 m of cable between the Systemair Control Panel and the controller is possible. Place the Systemair Control Panel on the outer side of the unit or on a wall.



Position	Description
1	Alarm button: Press for alarm list.
2	Alarm indicator: Flashing for unacknowledged alarm.
3	Write enable LED: Slow flashing indicates parameters can be changed.
4	OK button: Press to activate a selected menu/setting, if possible.
5	Button for clear: Abort a parameter setting or – if possible - restore the original value.
6	Right/left – and up/down buttons: Used for navigation up and down and to the right and left in the menu tree. Up/down buttons are also used for increasing or decreasing values of parameters.
7	Holes for mounting
8	Terminal block
9	No cable on terminal 5 for software version 3.3 (illustrated with number 9 on the above drawing)
10	Brown cable on terminal 4 for software version 3.3 (illustrated with number 10 on the above drawing)
11	Yellow cable on terminal 3 for software version 3.3 (illustrated with number 11 on the above drawing)
12	White cable on terminal 2 for software version 3.3 (illustrated with number 12 on the above drawing)
13	Black cable on terminal 1 for software version 3.3 (illustrated with number 13 on the above drawing)

i.4 Installation - Pipes for water - hot and chilled, valves and drains

i.4.1 Description

If ordered with the unit, the valves and valve motors are stored in a carton box placed inside the unit. Water trap(s) – standard or optional - is (are) necessary to ensure escape of water from the tray under plate heat exchanger and (or) cooling coil. Water trap(s) is (are) stored in a carton box placed inside the unit.

i.4.2 Pipe connections

Connection pipes on heating- and cooling coils are provided with external thread. Drainage outlets on drip trays are provided with external thread.

i.4.3 Possibility of extracting components from the unit

Pipes and cables must not obstruct the inspection doors and components which can be extracted from the unit. Potential components for extraction are filters, fans and rotary heat exchanger.

i.4.4 Pipe connections to batteries

i.4.4.1 Heating coils

Pipes for hot water must be protected by insulation against frost and loss of heat. Further protection against frost can be obtained by installing electrical heating wires around the pipes and under the insulation combined with temperature sensors and a control system. Pipes, insulation, electrical heating wires, control system for heating wires and circulation pump are not delivered by Systemair.

i.4.4.2 Cooling coils

If ordered with the unit, the valves and valve motors are stored in a carton box placed inside the unit. Pipes for cooling must be protected by insulation against condensation on the pipes and loss of cooling in the summer. Pipes and insulation are not delivered by Systemair.

i.4.4.3 Rigid pipe mounting brackets for valves, circulation pumps and pipe system

The coil and pipes from the coil are not constructed to withstand the weight and stress from valves, circulation pumps, long pipes and insulation of pipes. The system must be supported carefully in rigid pipe mounting brackets to roof, floor and walls.

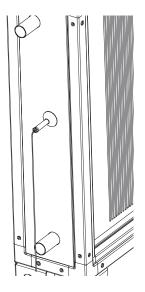
i.4.4.3.1 Pipe connection to heating coils

The heating capacity of the coil with only 2 rows is independent of the connection of the hot water in equal flow or in counter flow to the direction of the air, but connection of the hot water to the pipe marked for inlet and the return water to the pipe marked for outlet is very important to ensure that the sensor for transmission of the water temperature really will be placed in a return circuit of the coil (Screw-joint for the water temperature sensor is welded in the main collection pipe for return water).

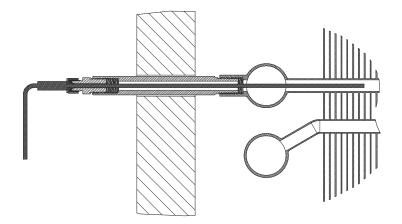
For the frost protection of heating coil, the water temperature in the coil is transmitted to the controller The controller always generates a signal to the valve motor that keeps a sufficient flow of hot water to protect the coil against frost. This frost protection is also activated when the running mode is "off". Coils with 3 rows or more must always be connected in counter flow to the airflow.

NOTE: If glycol is added, the glycol must be without additives and auto glycol must not be used. Automatic bleeding has to be installed at the highest point of the 2 pipes — supply or return pipe.

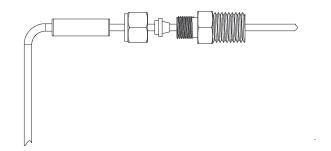
If the heating battery is built with 3 or more rows, the water flow must be in counter flow to the direction of the air.



To protect against frost a temperature sensor for the transmission of an analog signal to the controller is placed in a pipe on the collection pipe for return water. The sensor must be fitted water tight with a cap in the pipe before water under pressure is in the battery. The pipe for the sensor is soldered on the collection pipe and it is important to hold contra on the pipe, when the cap is tightened.



Battery seen from above. The sensor measures the water temperature of the water inside one of the small pipes for return water in the battery. The sensor reduces the area in this pipe and hereby also the flow of warm water in this pipe. The temperature in this pipe is reduced more than the temperature in all other pipes by the airflow through the battery. Because the lowest temperature in the battery probably is measured here, this system creates early and safe warning of frost.



It is important that the cap is tightened sufficient to keep the sensor system fully water tight.

i.4.4.3.2 Pipe connection to cooling coils for chilled water

Coils with 3 rows or more must always be connected in counter flow to the airflow. **NOTE:** The glycol must be without additives and auto glycol must not be used.

Automatic bleeding has to be installed at the highest point of the 2 pipes — supply or return pipe.

i.4.4.3.3 Valve motor and valve for heating

The valve and valve motor are not installed. 2-way or 3-way valve is available.

i.4.4.3.4 Valve motor and valve for cooling

TThe valve and valve motor are not installed. 2-way or 3-way valve is available.

i.4.5 Draining condensate water

Drip trays for collection of condensate water are installed under plate heat exchanger and cooling coil. Each drip tray is provided with a drainage outlet. A water trap is always necessary. To avoid freeze ups and frost bursts of water trap and pipes, sufficient insulation is recommended and installation of heating between the insulation and water trap/pipes could even be necessary (insulation, heating and controller for the heating are not delivered by Systemair).

i.4.6 Draining condensate water from plate heat exchanger

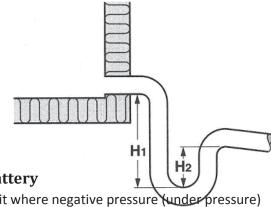
Heavy negative pressure where the condensate from the plate heat exchanger is collected in the drip tray allows air to flow through the drainage pipe into the unit and prevents condensate water from flowing out of the unit through the drainage pipe. A water trap with sufficient closing level of the water is extremely necessary to ensure that condensate water flows out of the unit. The pipe diameter of the water trap and sewage system must be identical to the pipe diameter of the drainage outlet from the tray.

The closing level of the water trap must be estimated correctly to ensure safe escape of the water (see the illustration and estimate the minimum closing level according to the table).

A water trap is optional and installation of the water trap is not included.

Negative pressure P (Pa)

Р	H1 Minimum	H2
500 Pa	100 mm	40 mm
750 Pa	150 mm	55 mm
1.000 Pa	190 mm	70 mm



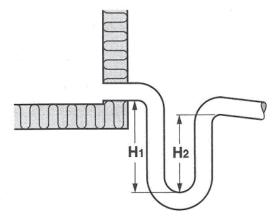
i.4.7 Draining condensate water from cooling battery

If the cooling battery and the drip tray are placed in the unit where negative pressure (under pressure) occurs, the closing level of the water trap must be estimated correctly. See the above-mentioned information in section i.4.6 – Draining condensate water from the plate heat exchanger.

If the cooling battery and the drip tray are placed in the unit where positive pressure (over pressure) occurs, the closing level of the water trap must be estimated correctly as shown on the illustration. A water trap is optional and installation of the water trap is not included.

Positive pressure P (Pa)

Р	H1 Minimum	H2
500 Pa	90 mm	65 mm
750 Pa	120 mm	90 mm
1.000 Pa	150 mm	120 mm



j. Installation and assembly instructions for reduction of noise and vibration emissions

Due to the design and construction of the units the (A) weighed sound pressure level from fans and other components do not exceed 70 dB (A) outside the units.

Data about sound in annex 2.

Installation of the units on springs will reduce the transmission of noise and vibrations to the building. Systemair does not deliver springs for this purpose.

Flexible connections between the units and the ducts are available as accessories.

k. Instructions for putting into service, adjustments, use and commissioning.

k.1 Print-outs on paper

The documents listed below are always printed on paper and delivered together with the units according to the Machinery Directive and the related national laws

This User Manual with;

- Declaration of incorporation annex 1
- The unique technical data for this unit annex 2
- Installation instructions including instructions for the Danfoss frequency converter annex 4-12
- Printed form for Commissioning protocol annex 13
- Test report annex 14
- Short description about the main components in the control system annex 15
- Wiring diagrams annex 16
- Operator's guide for the Systemair control panel annex 17

k.2 Electronic media

A DVD is delivered with every unit. The below-mentioned documents are available on every DVD and this means that every DVD is provided with information about many components that are not delivered with every unit. The documents on the DVD:

Common

- This User Manual
- Operator's Guide
- Commissioning Protocol as a Word-file for modification by the installer

Components in the control system

- Danfoss frequency converter
- Corrigo controller manuals
- Information about Building Management Systems
- Damper motors
- Filter guards
- Temperature sensors
- Fire thermostats
- Smoke detectors
- Pressure transmitters
- Valves
- Valve motors
- Humidity sensors
- CO2 sensor
- Humidity sensor
- Humidifier
- E-Tool software for fast communication with the Corrigo controller
- Other

k.3 Documentation is available for download from https://techdoc.systemair.dk

Your local Systemair company is able to provide the data.

k.4 Start-up by installer

All protection and safety measures must be met before start-up of the unit. The mains supply voltage must also be checked too. The mains supply voltage must be measured at the supply terminals in the cabinet.

k.4.1 Checklist, relevant values

k.4.1.1 Checklist prior to start-up

- Is the unit assembled correctly with its functions in the correct order? See annex 2.
- Are the sections and ducts assembled correct? See annex i.
- Check that fans and anti-vibration mounts are not damaged after transportation and installation.
- Is the rotary exchanger turning freely?
- Are safety guards installed correctly?
- If the unit includes integrated cooling (DVU), check whether it is installed and supervised by qualified service personnel.
- If the unit contains Electric air heater, make sure that the supply isolator disconnects with the unit.
- Ducts are all ducts installed?
- External components are the valve and valve motor installed correctly?
- Is the circulation pump installed correctly?
- Is water under pressure in the coil and circulation pump?
- Are the pressure transmitters installed and connected correctly? (If this is a system with pressure transmitters in the ducts)
- Main power supply:
 - Connected correctly? (3x400 V + N + PE)
 - Test of supply voltage for actuators and control signal!
 - Are control signals for actuators connected correctly?

k.4.1.2 Switch on power

Do not start until all safety procedures have been completed and ensure that inspection doors are closed and locked.

Switch on power and the unit should be ready for the start-up.

For start-up see the Operator's guide for the Systemair control panel - annex 17 (this manual is delivered with the unit – printed on paper and also available on the delivered DVD).

K.5 Adjustments and use

Adjust the factory set values for parameters on the Systemair Control Panel or via the software E-Tool on a PC. See the Operator's guide for the Systemair control panel - annex 17 (this manual is delivered with the unit – printed on paper and also available on the delivered DVD. Further information about the controller is available on the 100 pages in the Corrigo E28 User Manual that is available on the delivered DVD. E-Tool software is also available on the delivered DVD and for download from a homepage.

K.6 Description of functions

K.6.1 Remote control

k.6.1.1 Communication WEB-master (TCP/IP Exoline) to PC and Android telephone

The controller has been prepared with a WEB-master interface (WEB side integrated) available when connected to a LAN network. It is possible via the LAN network to read values and to change some parameters – for example set-point temperatures, schedules, air flow capacity. It is possible to read and reset present alarms. There are 2 levels of login.

k.6.1.2 Communication to BMS systems with MODBUS

The controller has been prepared for communication via RS485 communication port to a MODBUS based BMS system (Building Management System).

The controller can work as a stand-alone system without any support from other controllers. Special setup of the controller for communication with the BMS system is not included in the delivery from Systemair.

k.6.1.3 Communication to BMS systems with LON

The controller has been prepared for communication via LON communication port to BMS systems (Building Management Systems). The port uses LonWorks according to the LonMark-guidelines. The LON-interface variables are available from Systemair. The controller can work as a stand-alone system without any support from other controllers. Special set-up of the controller for communication with the BMS system is not included in the delivery from Systemair.

k.6.1.4 Communication to BMS systems via BACnet

The controller has been prepared for BACnet TCP/IP interface. This can be used for communication with a BMS system (Building Management System).

The controller can work as a stand-alone system without any support from other controllers. Special set-up of the controller for communication with the BMS system is not included in the delivery from Systemair.

K.6.2 Extended operation and external start/stop (for example by presence detectors)

When the unit is running at reduced speed or is in shutdown mode, it can be forced up one step by using a Push button (impulse). The required number of minutes for the extended operation must be selected on the Systemair Control Panel. Button and cable are not delivered by Systemair. Furthermore when the unit is in shutdown mode it is possible to start/stop the unit by presence detectors. Presence detectors and cable are not delivered by Systemair.

k.6.3 Valve and valve motor for heating coil

The supply voltage for the water valve actuator is 24V AC, the control signal is 0-10 V. The sensor for water temperature has to be installed in the heating coil and the sensor is provided with cable but not connected to the terminals in the cabinet. The cable between valve motor and terminals in the cabinet is not delivered by Systemair. Standard valves are available for 2 or 3-way connection.

k.6.4 Valve and valve motor for cooling coil

The supply voltage for the water valve actuator is 24V AC, the control signal is 0-10 V. Cables between valve motor and terminals in the cabinet are not delivered by Systemair. Standard valves are available for 2 or 3-way connection.

k.6.5 DX cooling

A DX-cooler can be connected to the controller. Input and output are available for: Start cooling – Alarm cooling – Cooling Y3. Cables are not delivered by Systemair

k.6.6 Circulation pump, heating

Circulation pump is not included in the delivery from Systemair. If the pump has not been activated for 24 hours, the pump is exercised once daily for 1 minute to keep the pump in a good condition. Cables are not delivered by Systemair.

k.6.7 Fire alarm function

k.6.7.1 External fire signal that indicate block or run

The unit is available without components for this function. The controller is as standard configured for ordinary running when the contact is closed (NC). By open contacts the fans stop and the dampers close. If disconnected, fire is indicated and the unit will stop until the signal is re-connected. On the site qualified technicians are able to change the configuration.

k.6.7.2 External fire signal

The unit is delivered without components for this function. The controller is as standard configured for ordinary running when the contact is closed (NC). By open contacts the fans stop and the dampers close. When the unit has been shut down by a fire signal, the unit has to be restarted on the control panel. On the site qualified technicians are able to change the configuration.

k.6.7.3 Two fire thermostats

The unit is available with 2 thermostats installed in the unit -1 in the extract air and 1 in the supply air. The cut-off temperature in the thermostats is adjustable between 40 and 70°C. At the factory supply is set at 70°C and extract is set at 40°C. The controller is as standard configured to stop the fans and close the dampers if a thermostat is released. On the site qualified technicians are able to change the configuration.

k.6.7.4 One smoke detector in extract air

The smoke detector has been installed in extract air next to the fan. The controller is as standard configured to stop the fans and close the dampers if the detector is released by smoke. When the unit has been shut down by a fire signal, the unit has to be restarted on the control panel. On the site qualified technicians are able to change the configuration.

k.6.8 E tool - configuration tool

The installer can download the PC software called E tool from www.regincontrols.com and this software enables the installer to configure and supervise the function of the system via a graphic interface. This software displays all the parameters to be written in a commissioning report (the commissioning report is

available as a Word-file on the CD delivered with the unit). The TCP/IP port in the Corrigo E28 controller is prepared for communication with the E tool software.

k.6.9 Electrical heater battery

k.6.9.1 Control of heating capacity connected to unit with Systemair control system

Electrical heater installed with separate controller beside the heater. The separate controller is designed for capacity conversion of the 0-10 V control signal from the main control system. The electric heater is not supplied from the air handling unit cabinet as the cabinet is not designed to supply the heater with power. No power supply cables are connected to the electric heater. The separate controller is without supply disconnecting device

k.6.9.2 Control of heating capacity connected to unit without Systemair control system

Electrical heater installed with separate controller beside the heater. The separate controller is designed for capacity conversion of the 0-10 V control signal from the main control system. The heating capacity is adapted in steps.

The electric heater is not supplied from the air handling unit cabinet as the cabinet is not designed to supply the heater with power. No power supply cables are connected to the electric heater. The separate controller is without supply disconnecting device.

k.6.10 Speed control of fans

k.6.10.1 TIME control system – EC motors

Fan motor revolutions are controlled by the EC motors. The EC motors are configured and tested to comply with the data of the unit.

k.6.10.2 DV control system - frequency converters inside the unit are IP 20

Fan motor revolutions are controlled by frequency converters, and they are configured and tested to comply with the data for the unit. The frequency converter for each fan motor is installed inside the unit beside the fan motor with cables between motor and converter. In units with complete control system the frequency converters are delivered with system parameters adapted to the motors and the project.

k.6.10.3 Pressure transmitters

Separate control of the air flow or duct pressure for supply fan and for extract fan. The required air flow or duct pressures with normal as well as reduced capacity are selected on the Systemair Control Panel. The actual pressure is measured by pressure transmitters. PI calculation in the controller continuously transmits the necessary revolutions for the fans to the frequency converters to achieve the required pressure.

k.6.10.4 CO2-dependent air flow

The air flow is controlled by a CO_2 sensor. High CO_2 concentration is equal to higher air flow. Low CO_2 concentration is equal to lower air flow. Based on the actual CO_2 level and a min/max level, the needed airflow is calculated. The speed of each fan is adjusted via frequency converter. Terminals in the cabinet are available for connection of the sensor.

k.6.10.5 Humidity dependent air flow

The air flow is controlled by the humidity sensor. High humidity is equal to higher air flow. Low humidity is equal to lower air flow. Based on the actual humidity level and a min/max level the needed airflow is calculated. The speed of each fan is adjusted via frequency converter. Terminals in the cabinet are available for connection of the sensor.

k.6.11 Cabinet

k.6.11.1 Integrated cabinets in TIME units

TIME units are delivered with 2 integrated cabinets. One cabinet in the supply fan section and one cabinet in exhaust fan section. Both cabinets are installed behind inspection doors. External components must be connected to terminals in the cabinet in the supply fan section.

k.6.11.2 Integrated cabinet in DV units with control system

Cabinet is integrated in the unit behind an inspection door. Terminals are installed in the cabinet for all external components. The number of terminals is always adapted to the individual order.

k.6.11.3 Cabinet placed on the DV unit with control system

The models with the cabinet on the unit are exclusively for indoor installation. Terminals are installed in the cabinet for all external components. The number of terminals is always adapted to the individual order.

k.6.12 Temperature sensors

Four sensors are always delivered with each unit. See below where the sensors are placed;

- 1 sensor in the extract air, installed inside the unit
- 1 sensor in the outdoor air, installed inside the unit before the supply air filter on the cold side of the heat exchanger
- 1 sensor in the supply air to be placed in the supply air duct by the installer
- 1 sensor in the exhaust, installed inside the unit

k.6.13 Damper motors

Four different types of damper motors are available;

- On/off damper motor, not modulating, without spring function. Torque is 20 Nm and run time is 150 seconds
- On/off damper motor, modulating, without spring function. Torque is 20 Nm and run time is 150 seconds
- Spring-return damper motor, not modulating, with spring function. Torque is 20 Nm and run time is 150/16 seconds
- Spring-return damper motor, modulating, with spring function. Torque is 20 Nm and run time is 150/16 seconds

k.6.14 Filter guards

Filter guard over pre-filter and primary filter installed and connected to the controller for display of alarm when the mechanically set limit is exceeded. Filter alarm will be displayed on the Systemair Control Panel.

k.6.15 Room temperature sensors

One or two external room temperature sensors are available. The cabinet has been prepared with additional terminals for connection of the room temperature sensors. The sensors are delivered without cable. The controller calculates an average of the value from the 2 sensors as input for the control.

k.6.16 Frost protection

For the frost protection of the heating coil, the water temperature in the coil is transmitted to the controller by a temperature sensor in a water return circuit of the coil. The controller always generates a signal to the valve motor that keeps a sufficient flow of hot water to protect the coil against frost. This frost protection is also activated when the running mode is "off".

If the water temperature falls below the set point temperature the fans stop, the dampers close, and an alarm is activated.

From Systemair every heating coil for hot water is provided with a little pipe at the collection pipe for the return water. This little pipe is prepared for the installation of the above mentioned temperature sensor for the transmission of the return water temperature to the controller.

k.6.17 Systemair Control Panel - SCP

The separate cable-connected (10m) hand terminal with display and buttons – the Systemair Control Panel is always necessary for the normal handling and programming, because the main Systemair E28 controller is without display and buttons.

k.6.18 Cooling recovery

If the extract air temperature is lower than the outdoor air temperature, and there is a cooling demand in the rooms, the cooling recovery will be activated by reversing the heat exchanger signal. The signal is increased to the cooling recovery by increasing cooling demand.

k.6.19 Free cooling

A temperature sensor has been installed inside the unit in the outdoor air entrance. If the outdoor temperature after midnight is below the room temperature set point and the actual average room temperature is above the set point temperature, the fans start during the summer to cool down the building during night hours.

k.6.20 Alarm signal

By alarm there are 24 V DC on terminals in the cabinet. Lamps and cables are not available from Systemair.

k.6.21 Heat recovery

The heat recovery capacity is controlled by modulating speed of the rotor

k.6.22 Frost protection - plate heat exchanger

To prevent the plate heat exchanger from being blocked and damaged by ice when the outdoor air temperature is very low, the exhaust air temperature from the coldest area after the heat exchanger is transmitted to the controller by a temperature sensor. The dampers are controlled by modulating damper motor or damper motors to reduce the flow of outdoor air through the exchanger and to increase the flow of outdoor air through the bypass duct. By this sequence the risk of ice blocking of the exchanger is reduced and please note the capacity of the heating battery is sufficient for heating this mixture of preheated and not preheated supply air.

k.7 Commissioning

When the installer has completed the installation and wants to hand over the finished installation to his customer for payment the commissioning protocol can be the written receipt for the full ended job. Fill in the blank spaces and sign the proposed commissioning protocol that is annex 13, or fill in the Word-file with a Commissioning Protocol that is included on the DVD delivered with the unit.

l. Information about the <u>residual risks</u> that remain despite the inherent safe design measures, safeguarding and complementary protective measures adopted.

1.1 Unit casing.

1.1.1. Design of the machine to make transport safe

Hazards/dangerous area:

Incorrect handling during transportation may cause that the unit is dropped.

Dangerous incident:

If a person is hit by a unit that is dropped, this could in unfortunate circumstances lead to irreversible injury or death.

Claim for reduction of danger:

Correct handling during transportation is described in this manual. If lifted by fork-lift truck the forks of the truck must be sufficiently long. Safety measures are also described in this manual by use of crane. Information about weight of each section is also visible.

1.2 Common for all unit sections

1.2.1 Risk caused by surfaces, edges and corners

Hazards/dangerous area:

Sharp edges on plates might occur inside the machines as well as sharp edges on frames of dampers. No sharp edges on the outside of the units.

Dangerous incident:

Cut fingers/hands.

Claim for reduction of danger:

Risk only exists during maintenance and cleaning. This takes place at least once every year. Use of gloves and helmet is described in this manual. Cut-resistant gloves for protection against injury from sharp metal plate edges. Use CE-marked gloves for this purpose. Lamps mounted inside the unit with sufficient lighting reduce the risk of injury.

1.3 Common for all unit sections by insufficient lighting

1.3.1 Risk caused by insufficient lighting inside sections

Hazards/dangerous area:

On the floors of the units there are handles to hold filters, profiles for the carrying of fan motors. Cables are between fan motors and frequency converters.

Dangerous incident:

By insufficient lighting, the above-mentioned obstacles are not visible with the risk of stumbling that becomes a fall, leading in unfortunate circumstances to irreversible injury or death.

Claim for reduction of danger:

Risk only exists during maintenance and cleaning. This takes place at least once every year. According to this manual and in the SystemairCAD software for configuration and selection of accessories, lamps for sufficient lighting inside the units are mandatory according to the latest interpretations of the Machinery Directive by the authorities. Use of helmets reduces the risk of injury.

1.4 Dampers type DVA - DVB - DVM - DVP - Bypass dampers in DVQ

1.4.1 Risk caused by maintenance and cleaning of dampers

Hazards/dangerous area:

Are between the damper blades and the system of bars and links between motor and damper blades.

Dangerous incident:

Crushing of fingers.

Claim for reduction of danger:

Examination is still under preparation in our own laboratory. Still no voluntary test persons are available.

1.5 Attenuators type DVD

1.5.1 Risk caused by maintenance and cleaning of attenuators

Hazards/dangerous area:

High concentration of dust on the surface of the baffles might be harmful to the health.

Dangerous incident:

To breathe in particles that is harmful to the health.

Claim for reduction of danger:

Risk only exists during maintenance and cleaning. This takes place at least one time every year. Use of particulate respirator is described in this manual. Particulate respirator – maintenance free including foam face-seal and adjustable pre-threaded headbands (same particulate respirator as recommended for change of filters).

1.6 Filters type DVG - DVF

1.6.1 Risk caused by missing change of filters

Hazards/dangerous area:

Missing change of filters and missing maintenance decrease the capacity and final consequence will be breakdown.

Dangerous incident:

By extensive lack of of filter change and maintenance the machine can break down.

Claim for reduction of danger:

In the manual is the method and schedule for change of filters and maintenance specified.

1.6.2 Risk caused by the execution of filter change

Hazards/dangerous area:

Filter panels and filter bags

Dangerous incident:

To breathe in particles that is harmful to the health.

Claim for reduction of danger:

Use of particulate respirator – maintenance free including foam face-seal and adjustable pre-threaded headbands (same particulate respirator as recommended for cleaning of attenuators.

1.7 Plug fans type DVE

1.7.1 Risk caused by lightning strike

Hazards/dangerous area:

Lightning strike close to the machine.

Dangerous incident:

Lightning strike can create flash over between phases and conductive parts. This can cause fire or the overvoltage can make injury on persons

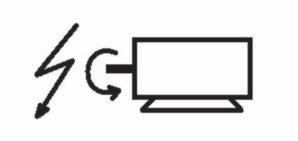
Claim for reduction of danger:

Installer and user must be aware of the fact that lightning makes a risk that requires installation of overvoltage protection devices to lead the lightning overvoltage to an earth lead on a safe way. The need for overvoltage protection devices depend on where the unit is placed in and on the building. Installer and user must take care of this according to local statutory requirements. Overvoltage protection devices are also described in section i.3.3.3 of this manual.

1.7.2. Risk caused by permanent magnet motor

Hazards/dangerous area:

Rotation of the shaft generates electricity. This danger is always visualized by a yellow warning label on the inspection door where permanent magnet motors are installed.



Dangerous incident:

Persons touching conductive parts get electric shock, burns, heart flicker and so on.

Claim for reduction of danger:

By installation or repairs of conductive components, the shaft must be blocked to prevent any rotation.

1.7.3 Risk of rotating impeller caused by stack effect (chimney effect).

Hazards/dangerous area:

On special occasions stack effect – also called chimney effect – in the ducts create airflows that drives the impellers by turned off motors.

Dangerous incident:

Injury of fingers, hands and arms.

Claim for reduction of danger:

Eliminate this airflow for supply air and exhaust air by dampers with spring return motors for automatic closing of the dampers by turned off fan motors and by power failure.

1.8 Batteries for heating and cooling type DVR - DVH - DVK, cooling compressor

1.8.1 Extreme temperatures - heating

Hazards/dangerous area:

Electrical heating elements can achieve surface temperature of 500 degree Celsius.

Batteries and pipes for hot water can achieve 95 degree Celsius.

Dangerous incident:

According to ISO 13732-1:2006, here is no direct risk of burns. (short-time contact – lesser than 2,5 sec).

Claim for reduction of danger:

No.

1.8.2 Extreme temperatures - cooling

Hazards/dangerous area:

Evaporator batteries and pipes connected to cooling compressor can achieve minus 10 degrees Celsius.

Dangerous incident:

According to ISO 13732-1:2006, here is no direct risk of burns. (short-time contact – lesser than 2,5 sec).

Claim for reduction of danger:

No.

1.9 Cooling compressor units type DVU - DVU-C

1.9.1 Risk of high temperature

Hazards/dangerous area:

Condenser batteries and pipes can achieve temperature of 60 degree Celsius.

Dangerous incident:

Vurderet ud fra ISO 13732-1:2006, der er umiddelbart ikke risiko for forbrændinger. (berøringstid 2,5 sek).

Claim for reduction of danger:

No.

1.9.2 Risk caused by lightning strike

Hazards/dangerous area:

Lightning strike close to the machine.

Dangerous incident:

Lightning strike can create flash over between phases and conductive parts. This can cause fire or the overvoltage can make injury on persons

Claim for reduction of danger:

Installer and user must be aware of the fact that lightning makes a risk that requires installation of overvoltage protection devices to lead the lightning overvoltage to an earth lead on a safe way. The need for overvoltage protection devices depend on where the unit is placed in and on the building. Installer and user must take care of this according to local statutory requirements. Overvoltage protection devices are also described in section i.3.3.3 of this manual

m. Instructions on the protective measures to be taken by all service technicians during repair and maintenance

Use the below-mentioned personal protective equipment for maintenance:

- Cut-resistant gloves for protection against injury from sharp metal plate edges. Use CE-marked gloves for this purpose.
- Helmet
- Particulate respirator maintenance free including foam face-seal and adjustable pre-threaded headbands for replacing filters.
- Padlock for locking the automatic circuit breakers in off position
- Permanent magnet motor. The shaft must be blocked during repairs and maintenance of the electric system (the motor generates electricity by rotation for example that the wind and thermic drives the fan/motor).
- Lighting inside the units. According to the latest interpretations of the Machinery Directive by the authorities sufficient lighting inside the units is mandatory.
- Tools to block the impeller during repairs and maintenance if stack effect also called chimney effect – in the ducts create airflows that drives the impellers by turned off motors

n. The essential characteristics of tools which may be fitted to the machinery

The subject in the Machinery Directive about tools on the machine does not exist for the TIME and DV air handling units, because those tools does not exist.

o. The conditions of stability during use, transportation, assembly, dismantling when out of service

The unit must always be handled in an upright position. Never tilt any section more than 15 degrees. If sections must be tilted more than 15 degrees, sections with fans or rotating exchangers that can be drawn out for service must be secured carefully.

During transportation, installation, dismantling or other handling, it must be secured that all components in the unit are properly fastened and with additional attention to the control of anti-vibration mounts under

the fans that they are undamaged. The mounting and smooth running of the fans must be controlled and handled with great care.

o.1 Installed reliable to avoid units to be tilted or moved by the any storm.

Units installed on roofs and other places with the risk of heavy winds must be installed reliable to avoid that they can be tilted or moved by the any storm. The base frame is provided with holes that are intended for fastening by sufficient bolts and fittings supplied by the installer.

o.2 Transport of section with cooling compressor unit

During transportation, the unit section – DVU and DVU-C - <u>must</u> always be in the upright position or tilted less than 30°. If it is necessary to tilt the unit more than 30°, the suction pipe of the compressor must point upwards to prevent the escape of oil from the compressor sump.

o.3 Disposal of the cooling compressor system - type DVU and DVU-C

Prior to the disposal of the DVU or DVU-C unit section, the refrigerant in the cooling system must be drained off by a skilled technician from a certified company. After correct evacuation of the refrigerant, the disposal of the DVU or DVU-C unit section is similar to the disposal of the rest of the air handling unit.

o.4 Generel disassembly - sharp edges

Pay attention to several sharp edges during dismantling and disposal of the unit. To avoid injury, CE-marked cut-resistant gloves as well as helmet must be used. The measures are described further in the Maintenance, Dismantling and Disposal Manual.

p. Instructions for machinery where these are regularly to be transported

The subject in the Machinery Directive about machinery that are regularly to be transported does not exist for the TIME and DV air handling units, because those units are for specially made for one intended application.

q. The operating method to be followed in the event of breakdown. Safe restart.

Use the below mentioned procedure in the event of breakdown or blockage:

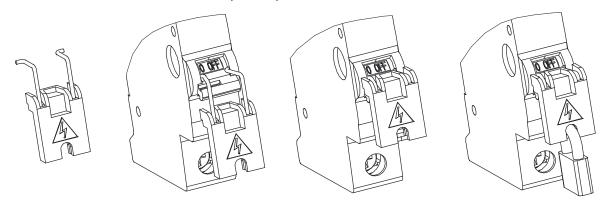
- Switch off the power and lock the supply disconnecting device in the off position.
- Remove the reason for breakdown or blockage.
- Follow the start-up procedure described in section k.

r. Adjustment and maintenance operations

Must be performed by skilled technicians.

r.1 Shutdown of the unit to a safe state.

Switch the unit to OFF on the Systemair Control Panel. See the - Operator's Guide – Annex 17.Switch off the automatic circuit breakers and block them by padlocks. The automatic circuit breakers are marked F1 to F4. See the illustration below about how to place a padlock on each automatic circuit breaker.



Check that the automatic circuit breaker marked F5 is still switched on because the lamps inside the unit, and only those lamps, are connected to this switch. Switch on the lamps for light during the maintenance activities.

Use the start-up procedure described in section k, when the maintenance activities are completed.

r.2 Recommended maintenance intervals

Function	Maintenance		
Unit casing	Cleaning of the unit casing.	1	
	Control of rubber seals on doors and between sections.	1	
Filters	Change on demand by alarm and always minimum twice a year.	2	
	Control of rubber seals. Control of the system with lateral	2	
	locking rails and handles on TIME and DV10 – DV150. Control of		
	the filter bank frames with fasteners on DV190 and DV240.		
Fans	Cleaning of all parts.	1	
	Check motors and bearings	1	
	Check that the impellers are rotating without dissonance.	1	
	Check that anti-vibration mounts are intact.	1	
	Check that the unit is operation without vibrations after the	1	
	cleaning, overhaul and maintenance.		
Rotary heat	Check that leakage and dirt accumulation is insignificant	1	
exchanger	Check that the rotor can turn freely and easily manually with a	1	
	hand when the belt is removed from the drive		
Plate heat	Check bypass function and sequence for de-icing	1	
exchanger	,, ,		
Run-around heat	Check the exchanger function and test the frost protection. The		
exchanger	glycol must be without additives and auto glycol must not be		
•	used.		
Dampers	Test the operation.	1	
-	Visual inspection of seals and tightness when closed.	1	
Hot water battery	Check the dirt accumulation and clean, if needed.	1	
•	Bleeding, if needed.	1	
	Test of frost protection sequence	1	
	Test of cirkulation pump	1	
Electric heating	Check dirt accumulation and clean, if needed.	1	
battery	Test the function of the system with the fuses for the safety.	1	
Cooling battery	Check dirt accumulation and clean, if needed.	1	
6 7	Test the frost protection (glycol)	1	
Cooling compressor	Mandatory annual control of the compressor system. Must be	1	
unit	done by certified technician from a certified company.	_	
Condensate drain	Cleaning of tray, water trap and outlet. Check the electrical	1	
condensate drain	heating between insulation and pipes, if installed.	_	
Saving- and comfort	Test of CO2 sensor, humidity sensor, motion sensor, pressure	1	
functions	transmitters for air capacity control, extended operation via	_	
	button, cooling recovery, free cooling		
Fire alarm	Test of thermostats, smoke detectors and fire detection	1	
c alarm	systems	_	
Battery in controller	Change the battery on demand by alarm in the display and	1	
battery in controller	always change the battery as a minimum every 5. Year.		
Remote control	Test of Communications.	1	
remote control	rest of Collinations.	1	

r.3. Filters - sizes and numbers

Filters in supply air and in extract air are always the same sizes and the same numbers. See the filters in supply or extract air below. REMEMBER to order filters for supply as well as for extract.

Size of unit	Numbers and sizes of frames for bag filters (WxH)
10	1x[792x392]
15	2x[490x392]
20	1x[490x490] + 1x[592x490]
25	2x[592x592]
30	1x[592x592]+ 1x[490x592] + 1x[287x592]
40	3x[490x742]
50	3x[592x490] + 3x[592x287]
60	8x[490x490]
80	4x[490x592] + 4x[490x490]
100	4x[592x592] + 4x[490x592]
120	4x[592x592] + 4x[592x490] + 4x[592x287]
150	9x[592x490] + 6x[490x490]
190	15x[592x592]
240	15x[592x592] + 3x[287x592] + 5x[592x287]

Size of unit	Numbers and sizes of frames for panel filters (WxHxD)
10	2x[376x376x44]
15	2x[448x448x44]
20	1x[241x495x44] + 1x[495x495x44] + 1x[391x495x44]
25	2x[445x622x44] + 1x[391x622x44]
30	3x[445x622x44]
40	6x[495x368x44]
50	6x[622x391x44]
60	8x[495x495x44]
80	4x[495x495x44] 4x[495x597x44]
100	10x[445x622x44]
120	15x[495x445x44]
150	21x[391x495x44]
190	15x[592x592x25]
240	15x[592x592x25] + 3x[287x592x25] + 5x[592x287x25]

NOTE that special sizes of filters are available by Camfil.

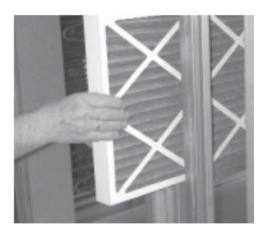
r.3.1 Bag filters

Release the bag filter cells by activating the handles and pull out the filter cells of the unit casing. The frame profiles are to be cleaned and all seals checked for damage. The handles and locking guide rails are also to

be checked to ensure that they can operate unobstructed. The new filter bags must be pushed carefully into the unit in order to ensure that they are sealed properly. The various filter sizes should be placed in an order corresponding to the way in which the unit is designed, and the filters must have vertical bags.

r.3.2 Panel filters

The filter cell guide rails are to be cleaned before fitting the new filters.





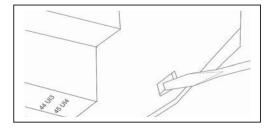
r.4. Changing the Internal Battery in the controller

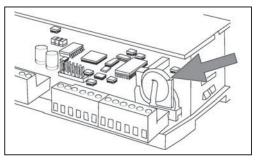
Note: This procedure requires knowledge of proper ESD protection; i.e. an earthed wristband must be used! When the alarm "Internal Battery" is activated and the battery LED lights up red, the battery for backup of program memory and real-time clock has become too weak. The battery is replaced as described below. A backup capacitor saves the memory and keeps the clock running for at least 10 minutes after the power supply is removed. Therefore, if the battery replacement takes less than 10 minutes, there will be no need to reload the program, and the clock will continue to run normally.

The replacement battery must be of the type CR2032.

Remove the cover by pressing down the locking torques at the edge of the cover using a small screwdriver, and at the same time pulling the edges outwards.

Grip the battery firmly with your fingers and lift it upwards until it rises from its holder. Press the new battery firmly down into place. Note that to preserve correct polarity; the battery can only be inserted the "right way round".





r.5 Other functions to maintain

r.5.1 The unit

The unit should be cleaned once a year when operating with normal air quality for comfort ventilation with no special hygiene requirements.

To clean the unit, dry it off with a dry cloth, or use water mixed with a non-corrosive cleaning medium. Any corrosion i.e. at the filters should be cleaned off immediately, and the surface treated.

In special operating conditions, where the air is aggressive or very humid, for example, or where there are special hygiene requirements, the unit shall be cleaned more frequently as required.

Cleaning medium and method should be adapted to the relevant conditions. Any corrosion should be cleaned off immediately, and the surface treated.

Closing mechanisms are to be lubricated at least once a year. Synthetic door hinges are service free. Seals around inspection doors are to be cleaned at least once a year and are to be checked for leakage. It is recommended to treat the seals with a moisture repellent agent. Connecting pieces for the unit sections, including the Disc-Lock types, are to be checked for tightness at least once a year. All seals are to be inspected at least once a year and are to be repaired if necessary.





Grilles for air intake and exhaust air outlet are to be cleaned at least once a year to prevent blockage.

r.5.2 Dampers

Rubber seals between the damper blades themselves and between the damper blades and the frame are to be checked once a year. These seals are not to be lubricated or treated in any other way. Each damper blade is connected by a pivoting system. The steel rods and brass bushes do not require lubrication.

The damper blades are fitted with synthetic bearings requiring no lubrication. Air-tightness of the damper, when the damper motor is in the closed position, must be visually checked once a year. The damper motor is to be adjusted if the damper does not close tightly.





r.5.3 Rotary heat exchanger DVC



r.5.3.1 Rotor

The rotor is to be checked at least once a year to ensure that it can turn freely and easily. This can be done by removing the belt drive at the motor and then turning the rotor manually with a hand on the peripheral rotor casing. At the same time the brush seals are to be checked for damage. The bearings are factory lubricated and do not require any service lubrication. During operation the rotor can become dirty. The rotor can be cleaned by blowing through with compressed air.

To ease inspection and service the rotor can be pulled out of the sizes 10, 15, 20, 25 og 30.

r.5.3.2 Motor and belt drive

The bearings are factory lubricated and do not require any service lubrication. The belt drive is to be checked for correct tightness and that it is undamaged. On smaller AHU, the rotor is fitted with an elastic belt drive and supplied with a reserve belt on the rotor. This belt drive does not require service and cannot be shortened. A new belt can be fitted using specialist tools. On larger heat exchangers the rotor has a V-belt with a belt connector. If the belt is no longer tight, it must be shortened to a length which enables the motor base frame tightening spring to hold the belt tight. If new screws are used for the belt connector, they must not have a length which exceeds the thickness of the belt and connector. Remove the excess, if any, with a file.

r.5.4 Cross flow and counter flow exchanger





Once a year the edges of the heat exchanger plates are to be checked for cleanliness and damage. If there is dust on the edges of the plates, remove it with a soft brush. If grease or other such substances are present, then the edges must be washed using grease dissolving detergents.

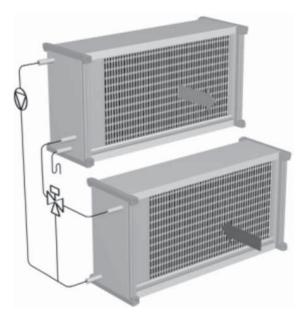
r.5.4.1 By-pass damper

The damper blades are fitted with synthetic bearings requiring no lubrication. Each damper blade is connected by a pivoting system. The steel rods and brass bushes do not require lubrication. Air-tightness of the dampers, when the damper motor is in the closed position, must be visually checked once a year. The damper motor is to be adjusted if the damper does not close tightly.

r.5.4.2 Condensate water drain

Once a year clean the drip tray beneath the heat exchanger, as well as the drain and the water trap. Take care that that there is sufficient water in the water trap. If a droplet eliminator has been fitted, this must be checked once a year and cleaned if necessary.

r.5.5 Run-around heat exchanger DVR



A heat recovery system of this type consists of a heating coil in the supply air- flow and a cooling coil in the exhaust air- flow. After an extended running period (normally a few years) dust particles can accumulate on the surface of the coils. This can reduce the efficiency of the coils. Cleaning must be carried out with the utmost care to ensure that the coil fins are not damaged.

The piping system must be vented once a year as air in the system can significantly reduce the capacity of the coils.

r.5.5.1 Pump and pressure expansion

The service instructions issued by the pump manufacturer must be followed. The pressure expansion system must be checked once a year. If necessary, the pressure must be increased to the correct level.

r.5.5.2 Condensate water drain

Once a year clean the drip tray beneath the heat exchanger, as well as the drain and the water trap. Take care that that there is sufficient water in the water trap. If a droplet eliminator has been fitted to the cooling coil, this must be checked once a year and cleaned if necessary.

r.5.6 Heating coil DVH, cooling coil DVK and change over coil DVHK

After an extended running period (normally a few years) dust particles can accumulate on the surface of the coil. This can reduce the efficiency of the coil. Cleaning must be carried out with the utmost care to ensure

that the coil fins are not damaged. The piping system must be vented once a year as air in the system can significantly reduce the capacity of the coil.

r.5.6.1 Heating battery

Check that the frost protection system is fully operational. A battery may burst due to frost if the frost protection system is not operational.

r.5.6.2 Cooling battery

Once a year clean the drip tray beneath the cooling coil, as well as the drain and the water trap. Take care that that there is sufficient water in the water trap. If a droplet eliminator has been fitted to the cooling coil, this must be checked once a year and cleaned if necessary.

r.5.6.3 Electeric heating battery

Check that the built-in safety thermostat with an automatic reset function and the overheat thermostat with manual resetting are fully operational.



r.5.7 Plug fans DVE

Dust can accumulate on the fan impeller which can cause imbalance and vibrations. The fan impeller must therefore be checked once a year and cleaned, if necessary. Anti-vibration mounts and flexible connections should be checked at the same time. If the anti-vibration mounts are damaged in any way they must be replaced.

r.5.7.1 Motor

The motor are usually fitted with factory lubricated bearings which require no further lubrication. Larger motors can be fitted with greasing nipples and bearings which require regular lubrication. Lubricating these types of bearings must be carried out according to the manufacturer's instructions.

r.5.8 Silencer DVD



During operation dust particles can accumulate on the surface of the baffles. Silencers that are designed for dry and wet cleaning are fitted with baffles that can be extracted from the unit casing. Large inspection doors give access to easily extraction of the baffles. Baffles designed for dry cleaning can be cleaned using a soft brush or they can be vacuum cleaned. Baffles designed for wet cleaning can be washed down using a soft brush and soapy water. The detergent used must be non-aggressive. After washing, the baffles must be wiped dry with a cloth. Remember to clean the inside surface of the unit casing before refitting the baffles.

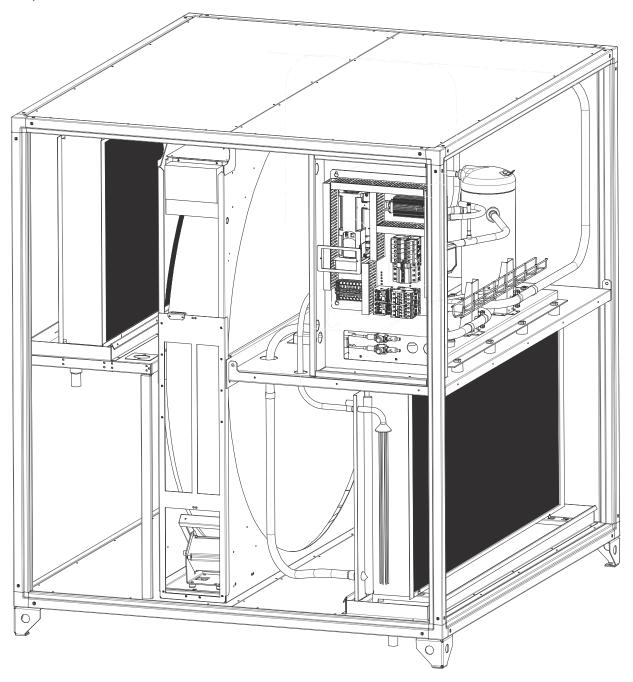
r.5.9 Outdoor air section DVY



Dust and dirt can accumulate in this section. Large inspection doors give access for cleaning.

r.5.10 Heat pump unit – DVU-HP

Mandatory annual control must be done by certified technicians from a certified company. See further description in annex 10 and 11.



s. Instructions designed to enable adjustment and maintenance to be carried out safely, including the protective measures that should be taken during these operations

s.1. Protective measures and additional protective measures

Adjustment and maintenance must be done by skilled technicians – usually based on service contracts for some years or long-term ESCO contracts.

The units are provided with guards to avoid unintended hazards and injury because of rotating parts in the unit. The potential sources of harm are the fans with fast rotating impellers. Hazards from the impellers are obvious during operation, but when power is cut-off, the impellers are still potential hazards due to after-run for at least 20 seconds. Notice that even cut-off the impellers are still potential hazards. The fan guard's are the inspection doors and the doors are provided with locks. Inside the doors are additional protection installed – guards that only can be removed by use of tools.

Other motor-driven parts are dampers with damper motors and rotary heat exchangers, but the movement is so slow that guard measures are not necessary. Just keep your hands away from places with risk of injury. Use particulate respirator when filters are replaced.

s.1.1 Necessary protection measures prior to start-up.

Ensure that all protection measures are installed correct before start-up.

s.1.1.1 Design of protection measures

Inside the doors are additional protection installed – guards that only can be removed by use of tools.

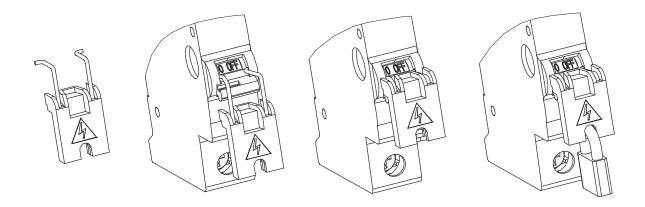
s.1.1.2 Configuration of frequency converters with installed guard

A frequency converter is mounted beside the fan in some units. If the configuration of frequency is carried out with the fan in operation, the guard must be installed for safety reasons and a long cable must be installed between the frequency converter inside the unit and the control panel outside the unit.

s.1.2 Safe adjustment and maintenance

Before maintenance and repair, the unit must be switched off by switching off the automatic circuit breakers and block them by padlocks. The automatic circuit breakers are marked F1 to F4. See the illustration below about how to place a padlock on each automatic circuit breaker. Check that the automatic circuit breaker marked F5 is still switched on because the lamps inside the unit, and only those lamps, are connected to this switch. Switch on the lamps for light during the maintenance activities (note that the lamps are an accessory — only installed, if ordered).

Use cut-resistant gloves for protection against injury from sharp metal plate edges. Use CE-marked gloves for this purpose. Use helmet during maintenance work in the unit.



s.1.3 Personal protective equipment for maintenance staff - health and safety

Use the below-mentioned personal protective equipment for maintenance:

- Cut-resistant gloves for protection against injury from sharp metal plate edges. Use CE-marked gloves for this purpose.
- Helmet
- Particulate respirator maintenance free including foam face-seal and adjustable pre-threaded headbands for replacing filters.
- Padlock for locking the above mentioned automatic circuit breakers.
- Permanent magnet motor. The shaft must be blocked during repairs and maintenance of the electric system (the motor generates electricity by rotation for example that the wind and thermic drives the fan/motor).

t. The specifications of the spare parts to be used, when these affect the health and safety of operators

DV and TIME units are operating automatically. Operators can control the unit by the Systemair control panel.

t.1 Spare parts - Mechanical

Annexe 3 - available on demand

t.2 Spare parts - Electrical

Annexe 3 - available on demand

u. Information on airborne noise emissions exceeding 70 dB(A)

Due to the design and construction of the units the (A) weighed sound pressure level from fans and other components do not exceed 70 dB (A) outside the units.

Overview of annexes

Annexes 1, 2, 3, 13 and 14 are enclosed in a separate cover.

Annex 1 Declaration of conformity with unique production number.

Printed on separate page and delivered with every unit. Enclosed in separate cover.

Annex 2 Technical data - unique data for every unit

Printed on separate pages and delivered with every unit. Enclosed in separate cover.

Annex 3 spare part lists

Printed on separate pages but <u>not</u> delivered with every unit. Available on demand.

Annex 4 Assemble base frames - height 150 mm for units in the sizes 10-40

Annex 5 Assemble base frames - height 150 mm for units in the sizes 50-150

Annex 6 Assemble base frames - height 250 mm for units in the sizes 10-40

Annex 7 Assemble base frames – height 250 mm for units in the sizes 50-150

Annex 8 Installation of steel roof in the sizes 10-150

Annex 9 Rotary exchanger - speed control and assembly of divided rotor

Annex 10 Heat pump unit - DVU-HP

Annex 11 Menu for internal controller in the heat pump unit

Annex 12 Connection of fan motor and set-up manual for Danfoss VLT FC101 frequency converter

Annex 13 Commissioning protocol – proposal (receipt for hand-over)

Printed on separate pages and delivered with every unit. Enclosed in separate cover

Annex 14 Report with data from the final functional test on the Systemair factory Printed on separate pages and delivered with every unit. Enclosed in separate cover.

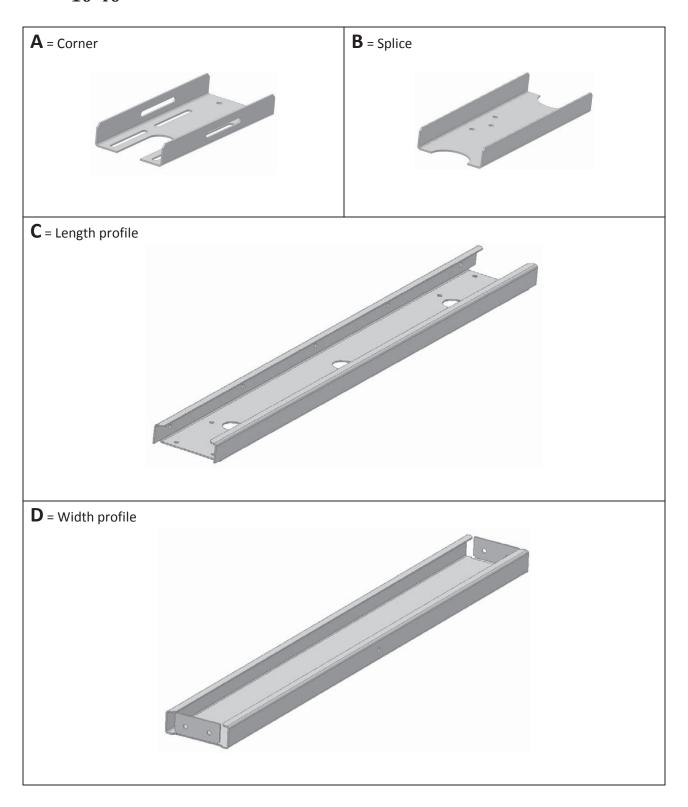
Annex 15 Short description of main components in control system

Annex 16 Wiring diagram

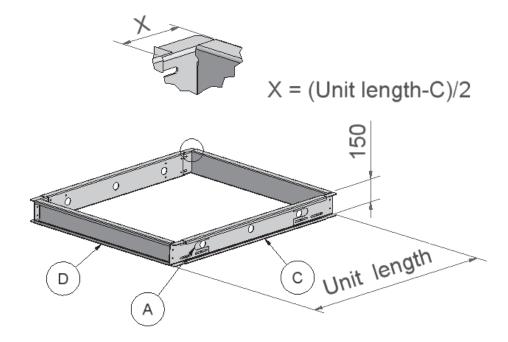
Annex 17 Operator's guide (how to use the Systemair control panel)

A separate manual on 12 pages delivered with every unit. This manual assists the everyday user/operator about how to control the unit by navigating the menus by the buttons and the display. Enclosed in separate cover.

Annex 4. Assemble base frames – height 150 mm for units sizes 10-40



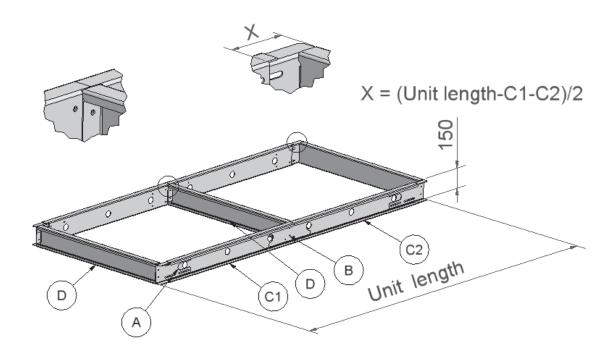
4.1 Base frame length 720 – 2420 [mm] Unit size 10-40



Width profile type D					
Unit size	Quantity	Length [mm]			
DV-10	2	876			
DV-15	2	1026			
DV-20	2	1176			
DV-25	2	1326			
DV-30	2	1476			
DV-40	2	1626			

		С	Α
Frame length [mm]	Quantity	Length [mm]	Quantity
700-770	2	520	4
770-920	2	670	4
920-1070	2	820	4
1070-1220	2	970	4
1220-1370	2	1120	4
1370-1520	2	1270	4
1520-1670	2	1420	4
1670-1820	2	1570	4
1820-1970	2	1720	4
1970-2120	2	1870	4
2120-2270	2	2020	4
2270-2420	2	2170	4

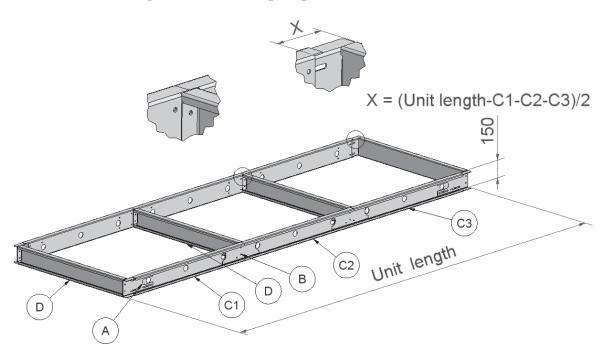
4.2 Base frame length 2420 – 4590 [mm] Unit size 10-40



Width profile type D					
Unit size	Quantity	Length [mm]			
DV-10	3	876			
DV-15	3	1026			
DV-20	3	1176			
DV-25	3	1326			
DV-30	3	1476			
DV-40	3	1626			

		C1		C2	Α	В
Frame length [mm]	Quantity	Length [mm]	Quantity	Length [mm]	Quantity	Quantity
2420-2570	2	1120	2	1200	4	2
2570-2640	2	1270	2	1200	4	2
2640-2790	2	1270	2	1270	4	2
2790-2940	2	1270	2	1420	4	2
2940-3090	2	1420	2	1420	4	2
3090-3240	2	1420	2	1570	4	2
3240-3390	2	1570	2	1570	4	2
3390-3540	2	1570	2	1720	4	2
3540-3690	2	1720	2	1720	4	2
3690-3840	2	1720	2	1870	4	2
3840-3990	2	1870	2	1870	4	2
3990-4140	2	1870	2	2020	4	2
4140-4290	2	2020	2	2020	4	2
4290-4440	2	2020	2	2170	4	2
4440-4590	2	2170	2	2170	4	2

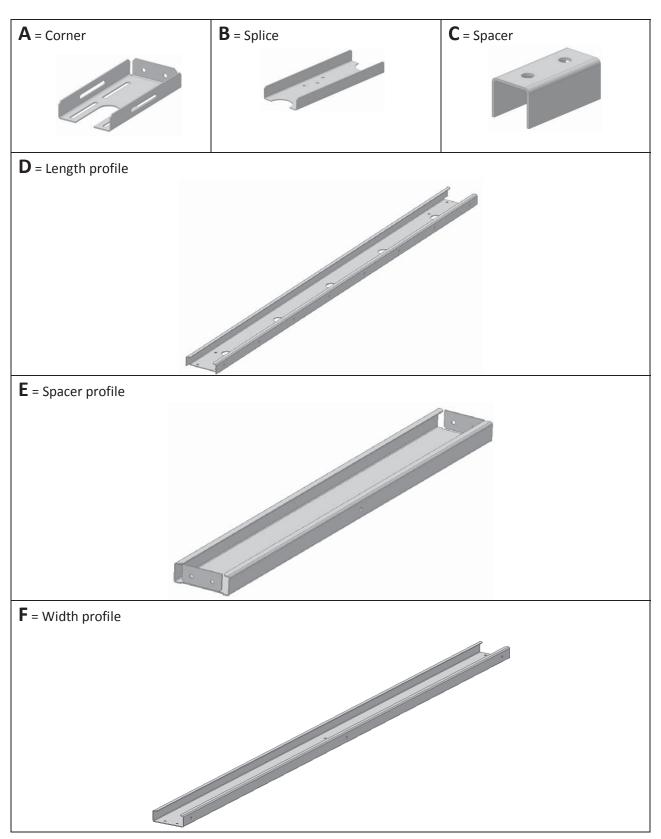
4.3 Base frame length 4590 – 6200 [mm] Unit size 10-40



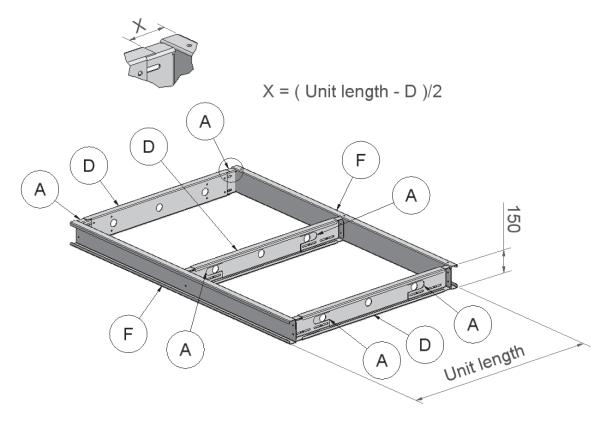
Width profile type D					
Unit size	Quantity	Length [mm]			
DV-10	4	876			
DV-15	4	1026			
DV-20	4	1176			
DV-25	4	1326			
DV-30	4	1476			
DV-40	4	1626			

	C	1	C	2	(C3	Α	В
Frame length [mm]	Quantity	Length [mm]	Quantity	Length [mm]	Number	Length [mm]	Qty	Qty
4590-4740	2	1420	2	1500	2	1570	4	4
4740-4890	2	1570	2	1570	2	1500	4	4
4890-5040	2	1720	2	1500	2	1570	4	4
5040-5110	2	1720	2	1720	2	1500	4	4
5110-5260	2	1720	2	1720	2	1570	4	4
5260-5410	2	1720	2	1720	2	1720	4	4
5410-5560	2	1870	2	1720	2	1720	4	4
5560-5710	2	1870	2	1870	2	1720	4	4
5710-5860	2	1870	2	1870	2	1870	4	4
5860-6010	2	2020	2	1870	2	1870	4	4
6010-6160	2	2020	2	2020	2	1870	4	4
6160-6200	2	2020	2	2020	2	2020	4	4

Annex 5. Assemble base frames – height 150 mm for units sizes 50-150



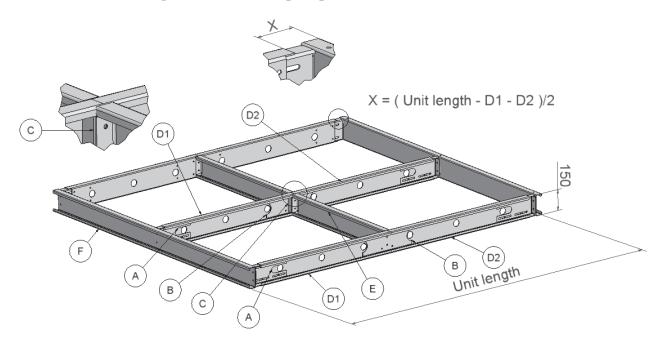
5.1 Base frame length **720 – 2420** [mm] Unit size **50-DV150**



Width profile type F					
Unit size	Quantity	Length [mm]			
DV-50	2	2020			
DV-60	2	2170			
DV-80	2	2170			
DV-100	2	2370			
DV-120	2	2590			
DV-150	2	2890			

		D	Α	
Frame length [mm]	Quantity	Length [mm]	Quantity	
700-770	3	520	6	
770-920	3	670	6	
920-1070	3	820	6	
1070-1220	3	970	6	
1220-1370	3	1120	6	
1370-1520	3	1270	6	
1520-1670	3	1420	6	
1670-1820	3	1570	6	
1820-1970	3	1720	6	
1970-2120	3	1870	6	
2120-2270	3	2020	6	
2270-2420	3	2170	6	

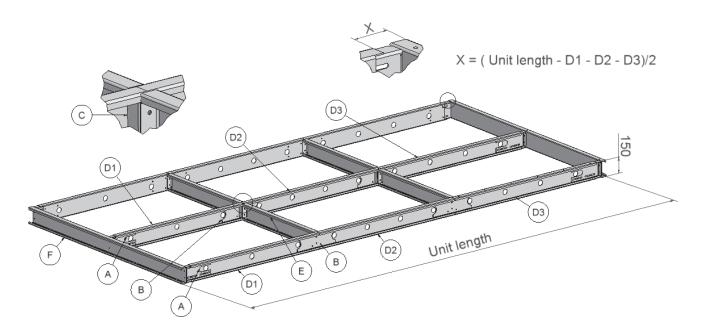
5.2 Base frame length 2420 - 4590 [mm] Unit size 50-150



	Width profile type F		Width profile type E
Unit size	Quantity	Length [mm]	Length [mm]
DV-50	2	2020	940
DV-60	2	2170	1015
DV-80	2	2170	1015
DV-100	2	2370	1115
DV-120	2	2590	1225
DV-150	2	2890	1375

	D:	1	D	2	Α	В	С	E
Frame length [mm]	Quantity	Length [mm]	Quantity	Length [mm]	Quantity	Quantity	Quantity	Quantity
2420-2570	3	1120	3	1200	6	3	1	2
2570-2640	3	1270	3	1200	6	3	1	2
2640-2790	3	1270	3	1270	6	3	1	2
2790-2940	3	1270	3	1420	6	3	1	2
2940-3090	3	1420	3	1420	6	3	1	2
3090-3240	3	1420	3	1570	6	3	1	2
3240-3390	3	1570	3	1570	6	3	1	2
3390-3540	3	1570	3	1720	6	3	1	2
3540-3690	3	1720	3	1720	6	3	1	2
3690-3840	3	1720	3	1870	6	3	1	2
3840-3990	3	1870	3	1870	6	3	1	2
3990-4140	3	1870	3	2020	6	3	1	2
4140-4290	3	2020	3	2020	6	3	1	2
4290-4440	3	2020	3	2170	6	3	1	2
4440-4590	3	2170	3	2170	6	3	1	2

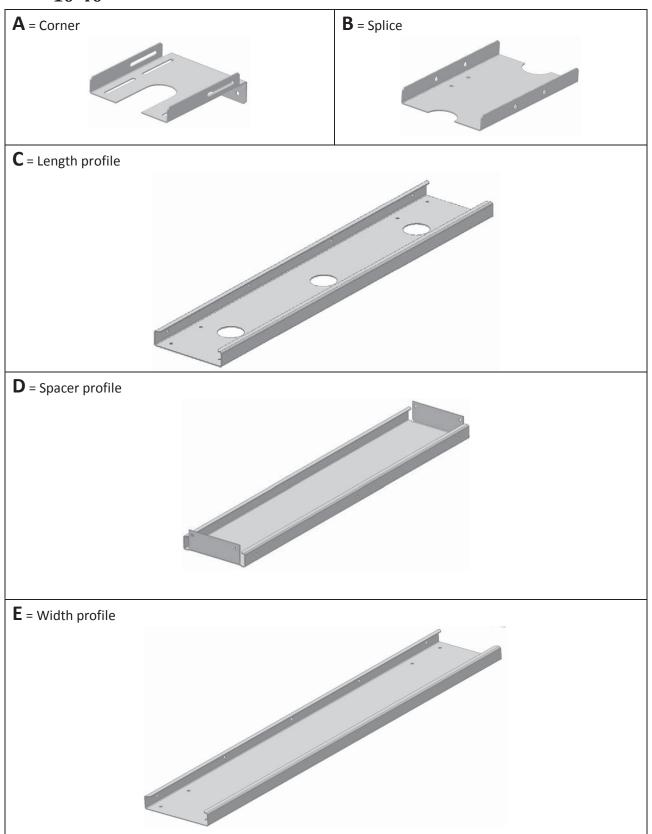
5.3 Base frame length 4590 – 6200 [mm] Unit size 50-150



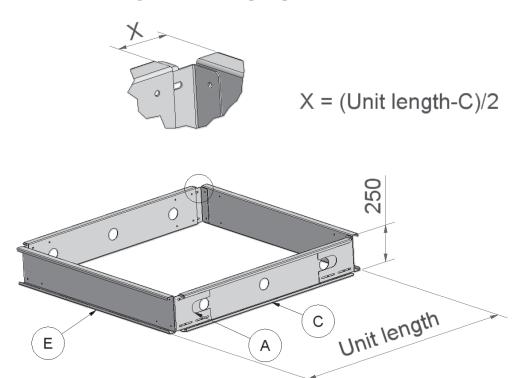
	Width profile type F		Width profile type E
Unit size	Quantity	Length [mm]	Length [mm]
DV-50	2	2020	940
DV-60	2	2170	1015
DV-80	2	2170	1015
DV-100	2	2370	1115
DV-120	2	2590	1225
DV-150	2	2890	1375

		D1		D2		D3	Α	В	С	Е
Frame length [mm]	Qty	Length [mm]	Qty	Length [mm]	Qty	Length [mm]	Qty	Qtyl	Qty	Qty
4590-4740	3	1420	3	1500	3	1570	6	6	2	4
4740-4890	3	1570	3	1570	3	1500	6	6	2	4
4890-5040	3	1720	3	1500	3	1570	6	6	2	4
5040-5110	3	1720	3	1720	3	1500	6	6	2	4
5110-5260	3	1720	3	1720	3	1570	6	6	2	4
5260-5410	3	1720	3	1720	3	1720	6	6	2	4
5410-5560	3	1870	3	1720	3	1720	6	6	2	4
5560-5710	3	1870	3	1870	3	1720	6	6	2	4
5710-5860	3	1870	3	1870	3	1870	6	6	2	4
5860-6010	3	2020	3	1870	3	1870	6	6	2	4
6010-6160	3	2020	3	2020	3	1870	6	6	2	4
6160-6200	3	2020	3	2020	3	2020	6	6	2	4

Annex 6. Assemble base frames – height 250 mm for units sizes 10-40



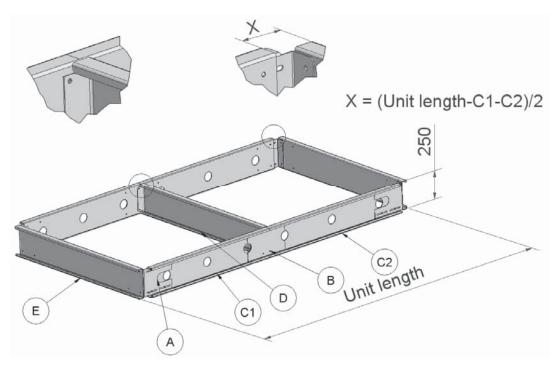
6.1 Base frame length 720 – 2420 [mm] Unit size 10-40



	Width profile type E	
Unit size	Quantity	Length [mm]
DV-10	2	870
DV-15	2	1020
DV-20	2	1170
DV-25	2	1320
DV-30	2	1470
DV-40	2	1620

		С	Α
Frame length [mm]	Quantity	Length [mm]	Quantity
700-770	2	520	4
770-920	2	670	4
920-1070	2	820	4
1070-1220	2	970	4
1220-1370	2	1120	4
1370-1520	2	1270	4
1520-1670	2	1420	4
1670-1820	2	1570	4
1820-1970	2	1720	4
1970-2120	2	1870	4
2120-2270	2	2020	4
2270-2420	2	2170	4

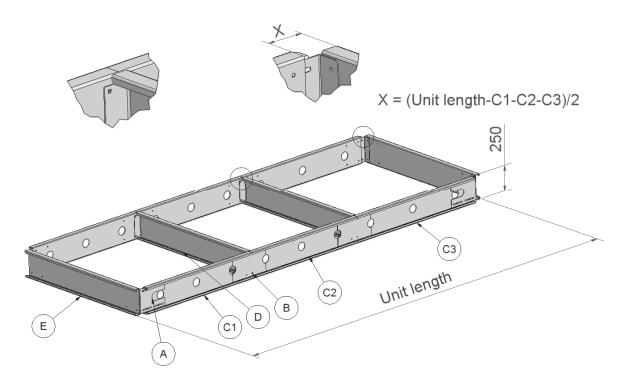
6.2 Base frame length 2420 – 4590 [mm] Unit size 10-40



	Width profile type E		Spacer profile type D
Unit size	Quantity	Length [mm]	Length [mm]
DV-10	2	870	870
DV-15	2	1020	1020
DV-20	2	1170	1170
DV-25	2	1320	1320
DV-30	2	1470	1470
DV-40	2	1620	1620

		C1		C2	Α	В	D
Frame length [mm]	Quantity	Length [mm]	Quantity	Length [mm]	Qty	Qty	Qty
2420-2570	2	1120	2	1200	4	2	1
2570-2640	2	1270	2	1200	4	2	1
2640-2790	2	1270	2	1270	4	2	1
2790-2940	2	1270	2	1420	4	2	1
2940-3090	2	1420	2	1420	4	2	1
3090-3240	2	1420	2	1570	4	2	1
3240-3390	2	1570	2	1570	4	2	1
3390-3540	2	1570	2	1720	4	2	1
3540-3690	2	1720	2	1720	4	2	1
3690-3840	2	1720	2	1870	4	2	1
3840-3990	2	1870	2	1870	4	2	1
3990-4140	2	1870	2	2020	4	2	1
4140-4290	2	2020	2	2020	4	2	1
4290-4440	2	2020	2	2170	4	2	1
4440-4590	2	2170	2	2170	4	2	1

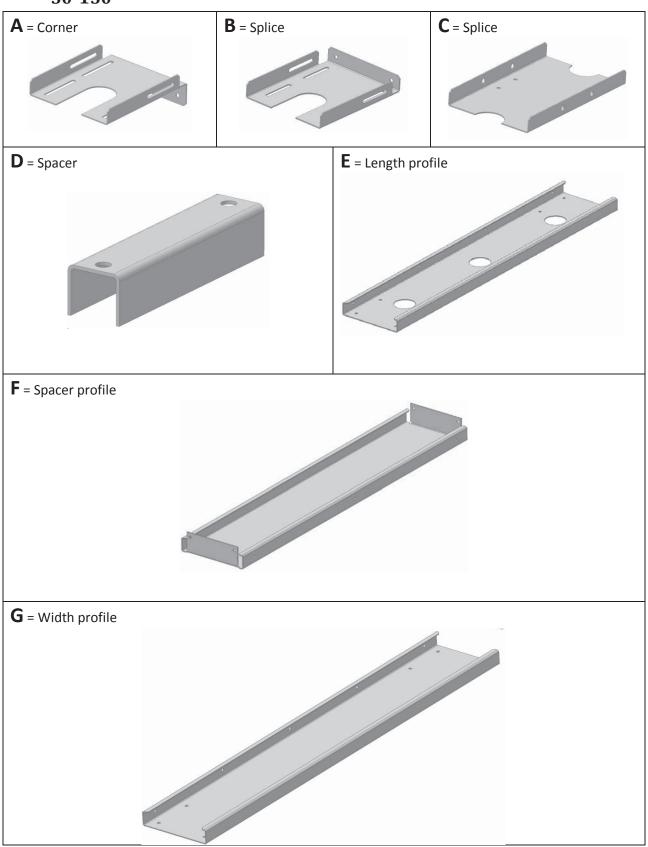
6.3 Base frame length 4590 – 6200 [mm] Unit size 10-40



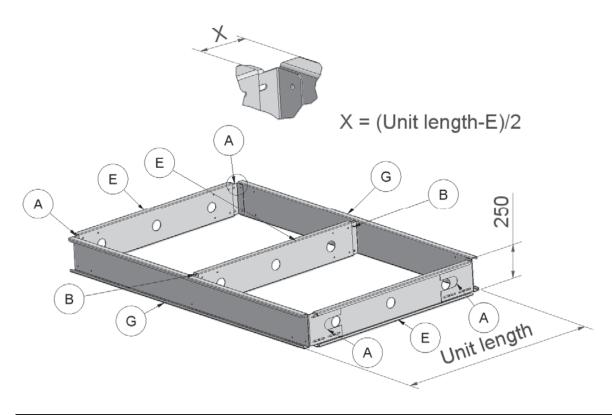
	Width profile type E		Spacer profile type D
Unit size	Quantity	Length [mm]	Length [mm]
DV-10	2	870	870
DV-15	2	1020	1020
DV-20	2	1170	1170
DV-25	2	1320	1320
DV-30	2	1470	1470
DV-40	2	1620	1620

		C1		C2		C3	Α	В	D
Frame length [mm]	Qty	Qty	Qty						
4590-4740	2	1420	2	1500	2	1570	4	4	2
4740-4890	2	1570	2	1570	2	1500	4	4	2
4890-5040	2	1720	2	1500	2	1570	4	4	2
5040-5110	2	1720	2	1720	2	1500	4	4	2
5110-5260	2	1720	2	1720	2	1570	4	4	2
5260-5410	2	1720	2	1720	2	1720	4	4	2
5410-5560	2	1870	2	1720	2	1720	4	4	2
5560-5710	2	1870	2	1870	2	1720	4	4	2
5710-5860	2	1870	2	1870	2	1870	4	4	2
5860-6010	2	2020	2	1870	2	1870	4	4	2
6010-6160	2	2020	2	2020	2	1870	4	4	2
6160-6200	2	2020	2	2020	2	2020	4	4	2

Annex 7. Assemble base frames – height 250 mm for units sizes 50-150



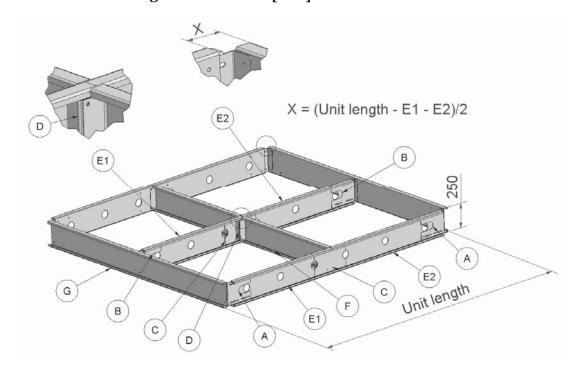
7.1 Base frame length 720 – 2420 [mm] Unit size 50-150



	Width profile type G									
Unit size	Quantity	Length [mm]								
DV-50	2	1920								
DV-60	2	2070								
DV-80	2	2070								
DV-100	2	2270								
DV-120	2	2490								
DV-150	2	2790								

		E	Α	В
Frame length [mm]	Quantity	Length [mm]	Quantity	Quantity
700-770	3	520	4	2
770-920	3	670	4	2
920-1070	3	820	4	2
1070-1220	3	970	4	2
1220-1370	3	1120	4	2
1370-1520	3	1270	4	2
1520-1670	3	1420	4	2
1670-1820	3	1570	4	2
1820-1970	3	1720	4	2
1970-2120	3	1870	4	2
2120-2270	3	2020	4	2
2270-2420	3	2170	4	2

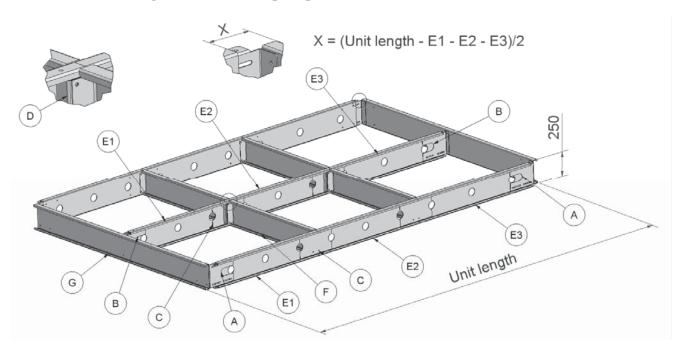
7.2 Base frame length 2420 – 4590 [mm] Unit size 50-150



	Width profile type G		Spacer profile type F
Unit size	Quantity	Length [mm]	Length [mm]
DV-50	2	1920	935
DV-60	2	2070	1010
DV-80	2	2070	1010
DV-100	2	2270	1110
DV-120	2	2490	1220
DV-150	2	2790	1370

		C1		C2	Α	В	С	D	F
Frame length [mm]	Qty	Length [mm]	Qty	Length [mm]	Qty	Qty	Qty	Qty	Qty
2420-2570	3	1120	3	1200	4	2	3	1	2
2570-2640	3	1270	3	1200	4	2	3	1	2
2640-2790	3	1270	3	1270	4	2	3	1	2
2790-2940	3	1270	3	1420	4	2	3	1	2
2940-3090	3	1420	3	1420	4	2	3	1	2
3090-3240	3	1420	3	1570	4	2	3	1	2
3240-3390	3	1570	3	1570	4	2	3	1	2
3390-3540	3	1570	3	1720	4	2	3	1	2
3540-3690	3	1720	3	1720	4	2	3	1	2
3690-3840	3	1720	3	1870	4	2	3	1	2
3840-3990	3	1870	3	1870	4	2	3	1	2
3990-4140	3	1870	3	2020	4	2	3	1	2
4140-4290	3	2020	3	2020	4	2	3	1	2
4290-4440	3	2020	3	2170	4	2	3	1	2
4440-4590	3	2170	3	2170	4	2	3	1	2

7.3 Base frame length 4590 – 6200 [mm] Unit size 50-150



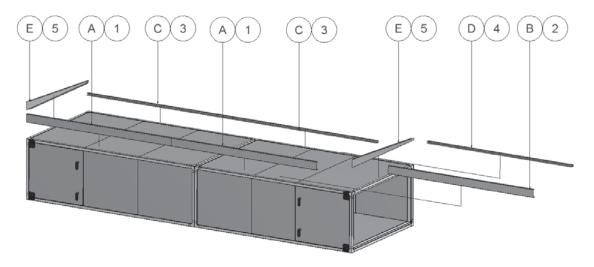
	Width profile type G		Spacer profile type F
Unit size	Quantity	Length [mm]	Length [mm]
DV-50	2	1920	935
DV-60	2	2070	1010
DV-80	2	2070	1010
DV-100	2	2270	1110
DV-120	2	2490	1220
DV-150	2	2790	1370

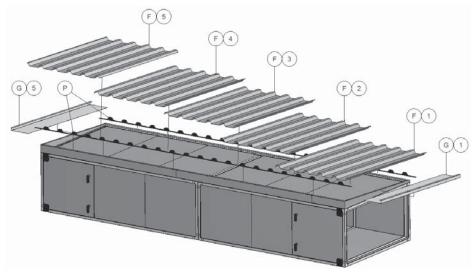
		E1		E2		E3	Α	В	С	D	F
Frame length [mm]	Qty	Length [mm]	Qty	Length [mm]	Qty	Length [mm]	Qty	Qty	Qty	Qty	Qty
4590-4740	3	1420	3	1500	3	1570	4	2	6	2	4
4740-4890	3	1570	3	1570	3	1500	4	2	6	2	4
4890-5040	3	1720	3	1500	3	1570	4	2	6	2	4
5040-5110	3	1720	3	1720	3	1500	4	2	6	2	4
5110-5260	3	1720	3	1720	3	1570	4	2	6	2	4
5260-5410	3	1720	3	1720	3	1720	4	2	6	2	4
5410-5560	3	1870	3	1720	3	1720	4	2	6	2	4
5560-5710	3	1870	3	1870	3	1720	4	2	6	2	4
5710-5860	3	1870	3	1870	3	1870	4	2	6	2	4
5860-6010	3	2020	3	1870	3	1870	4	2	6	2	4
6010-6160	3	2020	3	2020	3	1870	4	2	6	2	4
6160-6200	3	2020	3	2020	3	2020	4	2	6	2	4

Annex 8. Installation of steel roof in the sizes 10-150

8.1 Overview

- Mount rails A1, B2, C3, D4, E5 on the unit for support of trapezoidal roof plates (mount also rails Y and Z on units of the size 30 and on units that are larger than size 30 longitudinally at the centreline of the units).
- Place foam bands P on the horizontal rails A1, B2, C3 and D4 for support of roof plates.
- Calculate overhang of the roof at both ends of the unit and mount roof overhang profile G1 on the first trapezoidal roof plate F1 before the roof plate is mounted.
- Place and mount roof plates F1, F2, F3 and so on.
- Remember foam bands on the side laps between roof plates to prevent rainwater from passing through.
- Place roof overhang profile G5 at the other end of the unit before the last roof plate is mounted.
- Mount sides and corners on the roof.
- Apply sealing where plates are joined to ensure water resistance even in stormy weather.





8.2 Mount rails. Units of size 10, 15, 20, and 25

Squeeze sealant in sufficient quantity between the underside of the rails A1, B2, C3, D4, E5 and the horizontal top side of the unit before the rails are mounted. This means that the rails are standing on

sealant to achieve the tightest connection between rails and unit to prevent rainwater from passing under the rails and into the unit. Mount the rails A1 and B2 on the front side (the side with the inspection doors) – use the simple self-drilling screws without the sealing washer – see the illustration of the screw below.



Note: Rail B2 fits into the rail A1, and this offers the advantage that the rail B2 can be slid inside the rail A1 to adjust the length of rail B2 accurately to the length of the unit. In this way it is not necessary to spend time and effort cutting the rail B2.

Mount the lower rails C3 and D4 on the back side of the unit.

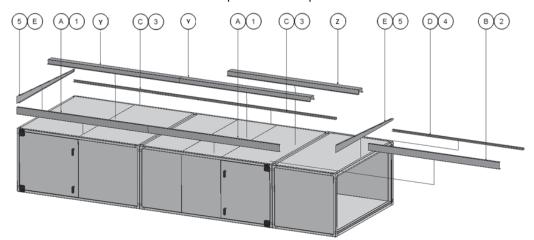
Note: Rail D4 fits into the rail C3, and this offers the advantage that the rail D4 can be slid inside the rail C3 to adjust the length of rail D4 accurately to the length of the unit. In this way it is not necessary to spend time and effort on cutting the rail D4.

Mount vertical rail – E5 - with the roof slope at each end of the unit

It is important to place a screw in each hole – even though the number of holes for screws seems to be very large, a screw in each hole is necessary as the stress on the roof during stormy weather is extremely high.

8.3 Mount rails. Units of size 30 and units larger than size 30.

On units of size 30 and on units that are larger than size 30, rails A1, B2, C3, D4, E5 must be mounted on the unit for support of trapezoidal roof plates, but also rails Y and Z must be mounted longitudinally at the centre-line of the units to hold the trapezoidal roof plates.



Squeeze sealant in sufficient quantity between the underside of the rails A1, B2, C3, D4, E5 and the horizontal top side of the unit before the rails are mounted. This means that the rails are standing on sealant to achieve the tightest connection between rails and unit to prevent rainwater from passing under the rails and into the unit. Mount the rails A1 and B2 on the front side (the side with the inspection doors) – use the simple self drilling screws without the sealing washer – see the illustration of the screw below.



Note: Rail B2 fits into the rail A1, and this offers the advantage that the rail B2 can be slid inside the rail A1 to adjust the length of rail B2 accurately to the length of the unit. In this way it is not necessary to spend time and effort cutting the rail B2.

Mount the lower rails C3 and D4 on the back side of the unit.

Note: Rail D4 fits into the rail C3, and this offers the advantage that the rail D4 can be slid inside the rail C3 to adjust the length of rail D4 accurately to the length of the unit. In this way it is not necessary to spend time and effort cutting the rail D4.

Mount vertical rail – E5 - with the roof slope at each end of the unit.

Mount the rails Y and Z on the unit with the centre-line of the rails exactly over the centre-line of the unit. It is longitudinal on the middle of the units to hold the trapezoidal roof plates.

Notice, that rail Z fits over the lower rail Y, and this offers the advantage that the rail Z can be slided on the rail Y to adjust the length of rail Z accurately to the length of the unit. In this way it is not necessary to spent time and effort on cutting the rail Z.

It is important to place a screw in each hole – even though the number of holes for screws seems to be very large, a screw in each hole is necessary as the stress on the roof during stormy weather is extremely high.

8.4 Roof overhang along the long sides of the unit

The roof plates are longer than the width of the unit to ensure sufficient overhang along the sides of the unit.

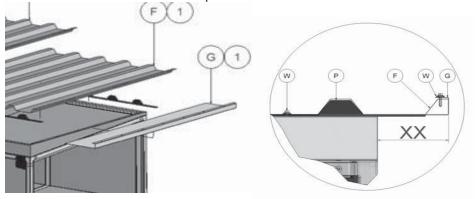
The overhang is 100 mm along each side of the smallest unit – size 10.

The overhang is 150 mm along each side of the units – size 15, 20, 25.

The overhang is 175 mm along each side of the biggest units – including size 30.

8.5 Calculation of the overhang at the ends of the unit. Mount overhang profile - G1.

The roof must be between 200 and 400 mm longer than the length of the unit to secure a roof overhang between 100 mm and 200 mm at the each of the 2 ends of the unit, and the length of this overhang must be calculated before the first roof plate is mounted.



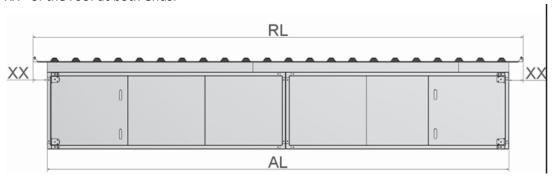
The unit is delivered with 2 similar overhang profiles - G1 and G5 - one for each end of the roof. Mount one of the 2 roof overhang profiles – G on a trapezoidal roof plate. Use the self drilling, painted screws with sealing washers - W - see the illustration.

Note: Foam bands - P – are necessary between the overhang profile G1 and the roof plate F1. See the illustration.



Self-drilling, painted screws supplied with sealing washer for the mounting of the trapezoidal plate to the roof overhang profile.

The total cover width of the trapezoidal roof plates always changes with the pitch of 207 mm between the trapezoidal ribs, making up a total length of the complete roof of - for example 2070 mm, 2277 mm, 2484 mm and so on. We call this length of the total roof for RL and we call the total length of the complete unit for AL. The trapezoidal roof must always be longer than the unit, to obtain a reasonable overhang called – XX - of the roof at both ends.



In the table below you will find 40 different lengths of roofs (always changing with the 207 mm) and the lengths of units that are ideal for each of the 39 alternative roof lengths.

Measure the total length – AL of the unit – for example 5 metres between the 4982 and 5182 mm mentioned in the table below.

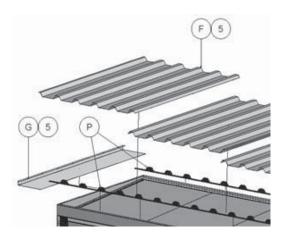
AHU length	Roof		AHU length	Roof		AHU length	Roof
AL	length		AL	length		AL	length
	RL			RL			RL
]]		
1670 –	2100		4568 – 4768	4970		7466 – 7666	8045
1870							
1877 –	2305		4775 – 4975	5175		7673 – 7873	8250
2077							

2084 –	2510	4982 – 5182	5380	7880 – 8080	8455
2284	2510	4302 - 3102	3380	7860 - 8080	6433
2291 – 2491	2715	5189 – 5389	5585	8087 – 8287	8660
2498 – 2698	2920	5396 – 5596	5790	8294 – 8494	8865
2705 – 2905	3125	5603 – 5803	5995	8501 – 8701	9070
2912 – 3112	3330	5810 - 6010	6200	8708 – 8908	9275
3119 – 3319	3535	6017 – 6217	6405	8915 – 9115	9480
3326 – 3526	3740	6224 – 6424	6610	9122 – 9322	9685
3533 – 3733	3945	6431 – 6631	6815	9329 – 9529	9890
3740 – 3940	4150	6638 – 6838	7020	9536 – 9736	10095
3947 – 4147	4355	6845 – 7045	7430	9743 – 9943	10143
4154 – 4354	4560	7052 – 7252	7635		
4361 - 4561	4765	7259 - 7459	7840		

The mentioned length of roof - RL - for this length of unit is 5380 mm (the delivered trapezoidal plates can be combined to this length - RL = 5380 mm). 5380 mm minus 5000 mm is 380 mm overhang for both ends, and 380/2 mm = 190 mm is the overhang for each end. Place the trapezoidal roof plate F1 with the roof overhang profile G1 on rail E with an overhang of 190 mm.

8.6 Foam bands between rails and roof plates - mount roof plates.

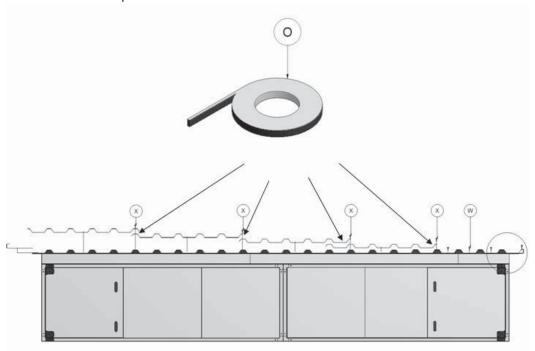
Place foam bands P between profiles A1, B2, C3, D4 and roof plates.



The trapezoidal roof plates are mounted with the self-drilling, painted screws supplied with sealing washer.

8.7 Foam bands between roof plates

Mount the self-adhesive foam band - O - on the underlapping rib for water resistant and effective sealing due to the small slope of the roof.

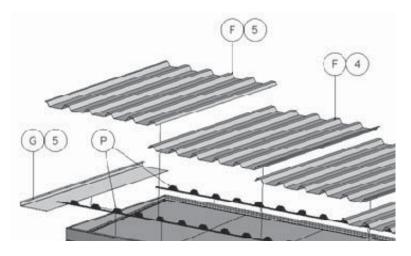


8.8 Mount roof plates – some of them are overlapping by 2 ribs

The width of each plate is always 1.035 mm and some of the plates have to overlap by 2 ribs to achieve the optimal total length of the whole roof — see the illustration above.

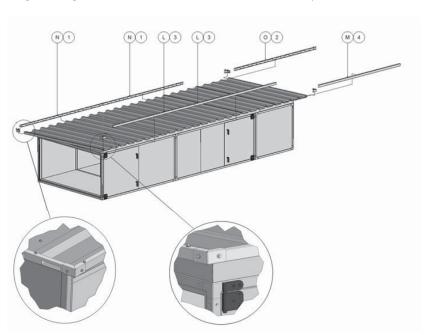
8.9 Mount overhang profile - G5 on the other end of the unit.

When the last trapezoidal plate (in this example F5) has been placed on the unit, the second roof overhang profile G5 must be pushed under the trapezoidal roof plate and mounted with the self-drilling, painted screw with sealing washer. Mounting must be similar to the mounting of roof overhang profile under the trapezoidal roof plate at the other end of the unit.



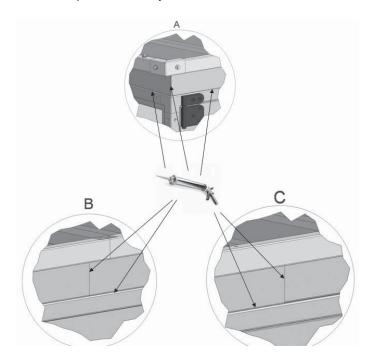
8.10 Mount side profiles and corners along the edges of the roof to protect persons

Profiles N and O with the rectangular holes are for the long and lower side of the roof because rain can escape through the holes. Mount the profiles type N first and the profile O last because the profile O goes over the profile N. Mounted in this order, the profile O can match the end of the roof and the surplus length of the profile O will just cover part of the previous profile N. Mount the profiles L and M along the long and higher front side of the roof. Mount the 4 protection corners.



8.11 Apply sealing on plate joints to ensure water resistance.

Finish installation of the steel roof by sealing all plate joints with silicone to prevent rainwater from passing into the unit. See examples below of joints to be sealed.



Annex 9. Speed control for rotor and assembly of divided rotor

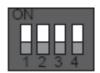
9.1 Speed control

The cabinet with the speed control system for the rotor is installed behind the inspection door in the rotor section.

The cabinet contains the speed controller with all components, terminal blocks, LED displaying the operation mode, the dual position DIP switch with 4 sliding levers for programming the rotor motor signal and a button for the activation of the test mode.

Through the different combinations of the 4 sliding levers of this dual position DIP switch, the correct signal is available for the 3 different motors used for the 14 sizes of air handling units. The sliding levers are set and the function is checked at the factory. The positions of the levers appear from the tables below.

9.1.1 Selection of correct signal via the 4 DIP switch levers



The 4 DIP switch levers

Position	Function	Code
Up	Active = ON	1
Down	Deactivated = OFF	0

The factory sets the positions of the 4 DIP switch levers for the maximum of 10 revolutions per minute for standard temperature exchangers and for hygroscopic exchangers. The position of each DIP switch lever is shown below.

DV	Diameter of pulley	DIP switch position	Motor	
10	50			
15	50	0000		
20	50	0000	90TYD-S214-M 2.8Nm	
25	65		901YD-5214-W 2.8Nm	
30	65			
40	65	1000		
50	71			
60	80			
80	85	0100	120TYD-S214-M 5.5Nm	
100	95			
120	106			
150	112			
190	132	0010	120TVD C214 L 7 FN	
240	140	0010	120TYD-S214-L 7.5Nm	

The factory sets the positions of the 4 DIP switch levers for the maximum of 20 revolutions per minute for sorption exchangers. The position of each DIP switch lever is shown below.

DV	Diameter of	DIP switch position	Motor
	pulley		
10	50	1000	90TYD-S214-M 2.8Nm
15	87		
20	87	0100	
25	107		120TYD-S214-M 5.5Nm
30	107		120110-3214-1015.510111
40	107	1100	
50	118	1100	
60	118		
80	140	1010	
100	150		
120	150		120TYD-S214-L 7.5Nm
150	160	0110	
190	160		
240	160		

9.1.2 Indication of operation mode via red and green LED as well as test of motor

The LED is in the cover of the cabinet.

LED indication	Value
No indication	Power off
Green	Ordinary operation
Green – flashes	Ready for operation
Constant green and red indication for activated rotor	Magnet on the rotor has activated rotor guard
guard	
Constant green and fast red flashes	Restart sequence active
Red	Rotor guard has not been activated

Number of red flashes in series	Value
1	Output current limit
2	Over voltage
3	Under voltage
4	Failure in the controller
5	Communication failure

Restart of rotor:

- Switch off power and switch on power again or
- Press the test button inside the cabinet

Test of motor by checking the resistance in all 3 vindings

Motor sizes	Ohm
90TYD-S214-M	40Ω
120TYD-S214-M	18Ω
120TYD-S214-L	10Ω

Setting of constant speed:

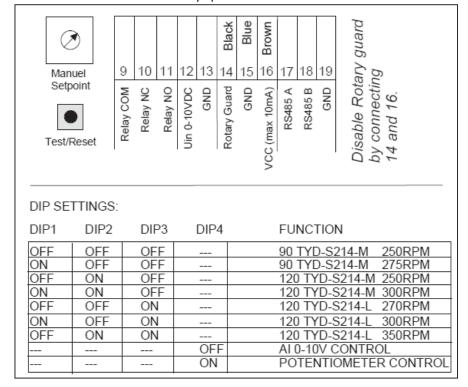
- Set fourth DIP switch lever in position - ON

Test:

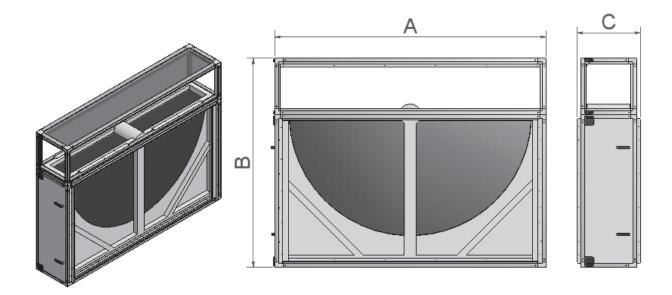
- Set fourth DIP switch lever in position ON
- Press the test button

9.1.3 Copy of the label with information about connection of cables

This self-adhesive label is always placed on the cover of the cabinet. The text is always in English.



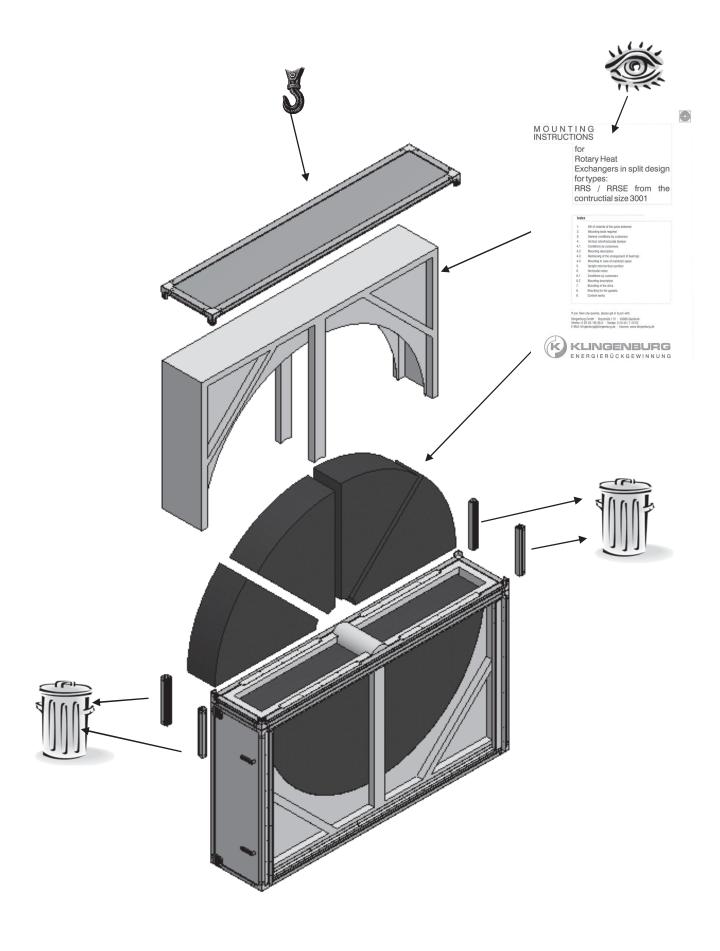
9.2 Assemble the Systemair casing for DV60, DV80, DV100, DV120 og DV150

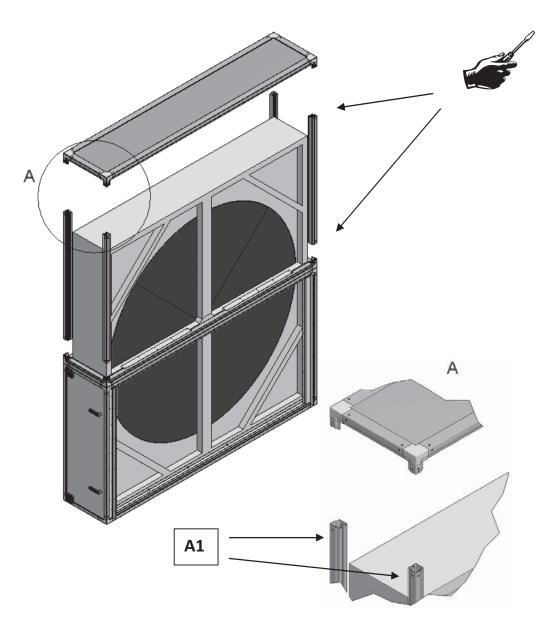




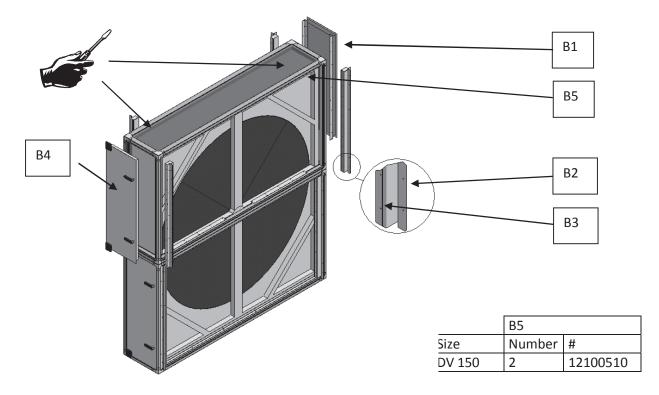
Size	А	В	С
DV 60	2170	1640	520
DV 80	2320	1790	588
DV 100	2520	1940	588
DV 120	2890	2090	558
DV 150	3040	2240	558



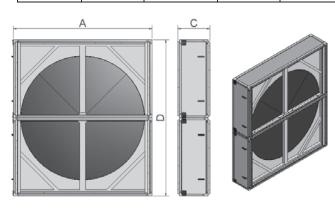




	A1	
Size	Quantity	Length (mm)
DV 60	4	1014
DV 80	4	1164
DV 100	4	1314
DV 120	4	1464
DV 150	4	1614



	B1		B2		В3		B4	
Size	Quantity	#	Quantity	#	Quantity	#	Quantity	#
DV 60	1	10122310	-	-	-	-	1	10722310
DV 80	1	10122610	4	11200400	4	21000200	1	10722610
DV 100	1	10122710	4	11200410	4	21000210	1	10722710
DV 120	1	10122810	4	12100410	4	21000230	1	10722810
DV 150	1	10122910	4	11200420	4	21000220	1	10722910



Size	Α	С	D
DV 60	2170	520	2240
DV 80	2320	588	2540
DV 100	2520	588	2840
DV 120	2890	558	3140
DV 150	3040	558	3440

9.3 Assemble divided rotor for DV 60, DV 80, DV 100, DV 120 og DV 150

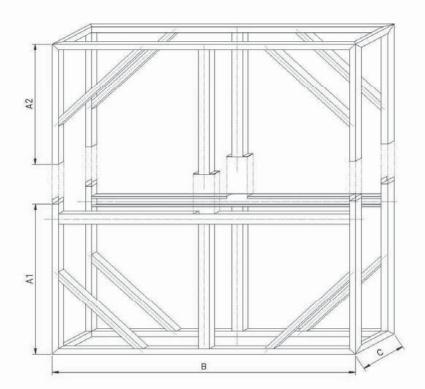


1. Bill of material of the parts delivered

As a standard the frames of the rotary heat exchangers of the constructional sizes RRS/RRSE up to 3000 are made of galvanized steel sheet

Frame dimensions of the split heat exchangers (without packing) as follows:

RRS / RRSE	Height A1 + A2 (mm)	Lower frame A1 (mm)	Upper frame A2 (mm)	Width (mm)	Depth (mm)
2500	2500	1350	1150	2500	440
2750	2750	1475	1275	2750	440
3000	3000	1600	1400	3000	440





2. Mounting tools required

In addition to the normally used mounting tools we'd recommend the use of:

- Hammer 1500 gr.
- plastic tip hammer
- hardwood
- 2 pieces round bars, d = 25 mm, l = 600 mm
- 2 pieces of spanners, respectively, with openings of 17, 19, 24 mm
- flexible reversible ratched handle with
 - socket for wrenches with openings of 7, 8, 17, 19 mm
 - hexagon insert socket driver 4, 6, 8, 10 mm
- electr. impact screwdriver
- engineer's pliers or side cutter
- double ladder
- screwdriver small 2,8 mm
- screwdriver big 10 mm
- 2 pieces drifts made of 12 mm round stock
- joint filling hand pistol, incl. permissable sealing materials

3. Gerneral conditions by customers

For stress-free positioning of the rotor the surface shall be flat. External forces of channel connections shall not be lead into the rotor frame. Observe that the rotor is evenly and straightly blown against. For inspection purposes the rotor shall be accessible within the installation.

4. Vertical rotor/horizontal division

4.1 Conditions by customers

A free space of at least 400 mm is required above the rotor because the upper part of the housing is placed after the mounting of the segments. In case this space is not available see details of item 4.3.

4.2 Mounting description

Alignement of the lower part of the rotor and fixing to the floor.

This work is not done by Klingenburg personnel.

Observe correct mounting direction of the rotor for in case of use of a scavenging chamber functioning is Important: no longer given!





Table of frames and storage mass weights as well as the storage mass segments valid for rotory heat exchangers

RRS / RRSE	Storage mass diameter (mm)	compl. weight exchanger (kg)	Weights frame weight (kg)	compl. Storage mass weight (kg)	Segments of storage mass
2500	2340	620	310	310	6
2750	2590	780	410	470	6
3000	2840	1000	600	400	6

Table of mounting accessories

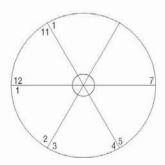
RRS	Mounting accessories of the lower part of the exchanger						
/ RRSE	nut M 16 (DIN 934)	Screw M 10 x 95 and nut (DIN 931 / 985)	Screw M 12 x 16 and nut (DIN 912 / 934)	Screw M 8 x 16 (DIN 912)	V-belt SPA incl. Lock (m)	Dust cover for bearing cover (Piece)	
2500 2750 3000	24 24 24	12 12 12	12 12 12	34 34 34	8,1 9,1 9,6	2 2 2	



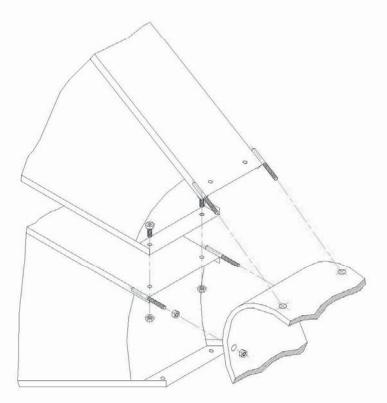


At delivery, half of the amount of the rotor segments is already assembled and pread-justed. The connection points of the individual segments are numbered continuously.

RRS / RRSE 2500 - 3000



- Block rotor against rotation with 2 pieces round bars, (d = 25 mm, I = 600 mm) between the root of the rotor, the welded threaded rods at the bordering sheet and the bearing frame.
- Insert segments according to numbering. The rotor surface shall be protected during these works. Do not use plain washers!

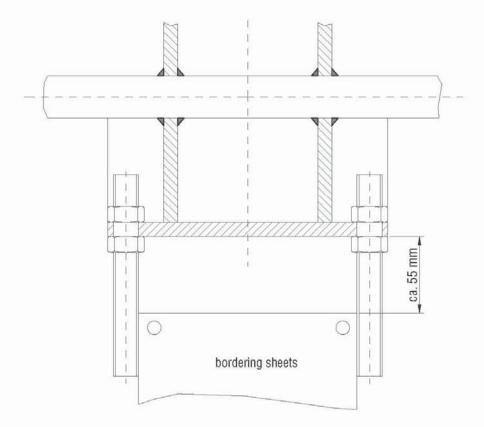


Fix nuts of the threaded rods by a locknut.



Attention:

The space between the outer edge of the root of the rotor and the bordering sheets shall be at about 55 mm. This measure is only for your orientation to insert all segments. If this measure is not kept it is difficult to insert the last Segment.



Install external screw fitting of the bordering sheets. Drive home screws.

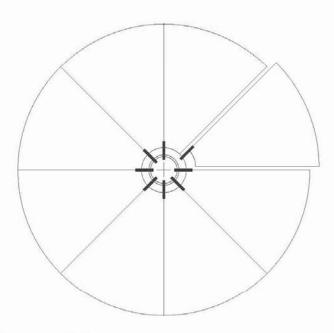
Important: The bordering sheets shall be contiguous without gap. In case of a gap the nuts at the threaded rods have to be adjusted accordingly.





In case of jamming of the final segment slightly loosen the neighbouring segments from the root. The final segment can be inserted into the root of the rotor with the threaded rods. In case the air gap of the last mounted segment is too big all segments have to be fetched about 2 to 4 mm closer to the root of the rotor.

Drive home all screws, otherwise depth impact! Important:



4.3 Redressing of the arrangement of bearings

The rotor bearing is basically adjusted by the manufacturer. In case of twisted assembly of the rotor, however, it maybe necessary to redress the bearing.

- Mark segment bordering
- Turn rotor to the position where marked border is upside down
- Meter the distance of segment borders to rotor frame
- Turn marked border upside
- Repeat metering
- Both dimensions have to correspond with an allowance of +2 mm
- Line bearing, if necessary
- Turn rotor to position where marked bordering is horizontal to rotor axle
- Meter distance of segment borderings to rotor frame
- Turn marked border to the other side
- Repeat metering
- Both dimensions have to correspond with an allowance of + 2 mm.
- Adjust one of the two bearings on the border frame, if necessary

Now, the rotor bearing is adjusted.



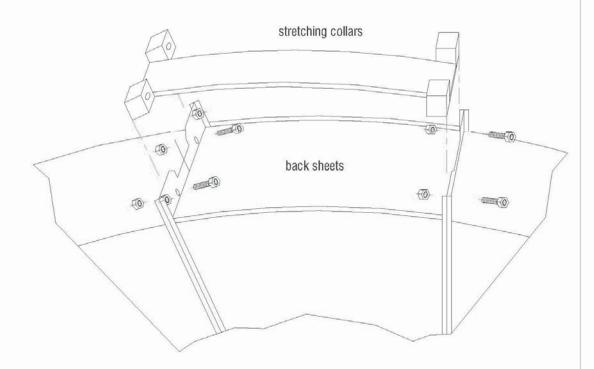


The individual segments are adjusted at the threaded rods of the root of the rotor. A side impact exceeding 3 mm shall not be permitted.

With rotors **up to the constructional size RRS/RRSE 3000**, now back sheets and allround-stretching collars are mounted and tensed. Check again rotor alignement before final fastening of the screw connections.

Important: Even screw down of the stretching collars (2 stages)

- Fasten screws until even tensioning of the segments is visible.
- ➤ Coining of the stretching collars along the entire circumferential by means of a plastic tip hammer or hard wood and hammer. Then, refastening of all screw connections.
- Check wobble and depth impact.



- Screw down tightly all screw connections.
- Place upper part of the housing and screw it down.

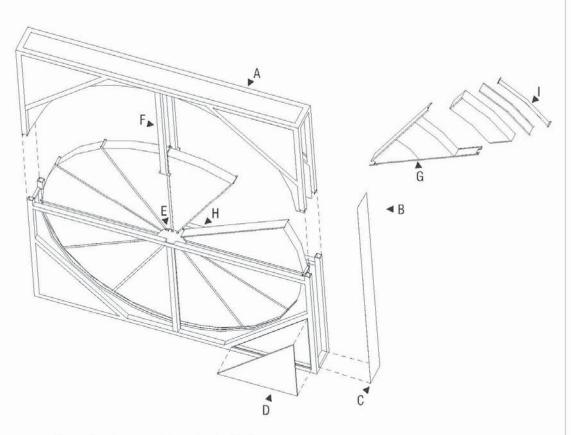




4.4 Mounting in case of restricted space

In case of insufficient space (400 mm) above the rotor the rotor housing can be assembled before inserting segments. According to the figure, the upper rotor edge can be removed. The unscrewable edge is always located above the driving motor. The rotor segments can be mounted through this opening.

about this see item 4.2.



- A) Housings are split from rotor size 2500 on
- B) The rotors are lined with removable sheets
- C) The motor is accessible from the front, from 2500 on by a triangular door
- D) Mounting edge always located above driving motor
- E) External bearings
- Bearing support stretcher F)
- G) Rotor sector
- H) Rotor cup
- I) Stretching collar





5. Upright rotor/vertical division

In some rare cases it may be necessary to vertically split the rotor housing. The housing, then basically, has to be completely assembled before inserting the segments. Mounting of the segments according to item 4.3.

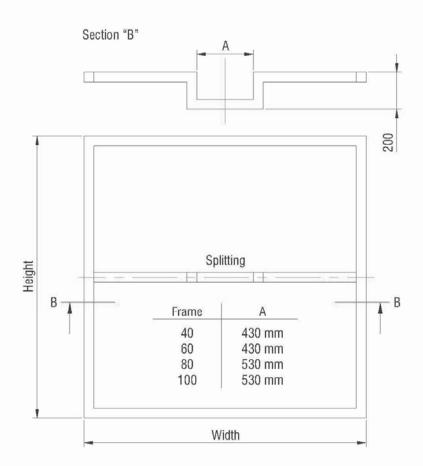
6. **Horizontal rotors**

6.1 Conditions by customers

For stress-free positioning of the rotor the surface shall be flat. External forces of channel connections shall not be lead into the rotor frame. Observe that the rotor is evenly and straightly blown against.

Important:

By customers, the point of support of the lower rotor bearing shall be solidly supported and easily accessible for maintenance purposes. The following describes our proposal for for a corresponding design.







6.2 Mounting description

- Place housing part containing the premounted half of the rotor mass onto the seat construction.
- Stick second part of the housing and fasten frame with supporting construcion.

Observe correct mounting direction of the rotor! Important:

Due to its dead weight the rotor settles about 5 mm as soon as the rotor is layed down. Therefore, the premounted rotor segments are pretensioned to this measure. Mounting of the segments is done analoguous to the mounting of the upright rotors. For this see item 4.2. and 4.4.

7. Mounting of the drive

The rotor drive is premounted by the manufacturer. It is fixed to a motor-driven rocker dolly switch, which itself is kept tensioned by a tension spring. The V-belt is loosely attached. The flex connector is premounted on one side.

- Fix one end of the V-belt to the rotor circumferential by means of an adhesive or a wire and draw it around the wheel by turning the rotor.
- Shorten belt which is delivered with overlength to necessary size.
- Connect ends with flex connector.
- Put belt on pulley.
- See that V-belt is sufficiently tensioned and does not abrade at the housing.
- V-belt stretchens during operation. Thus, if necessary, it needs to be shortened.

8. Mounting of the gaskets

Center and circumferential gaskets are premounted by manufacturer. Do not press gaskets against rotor mass because the motor is exceedingly retarded and may be damaged.

Push gaskets to final position during slow rotation of the rotor. Hint:

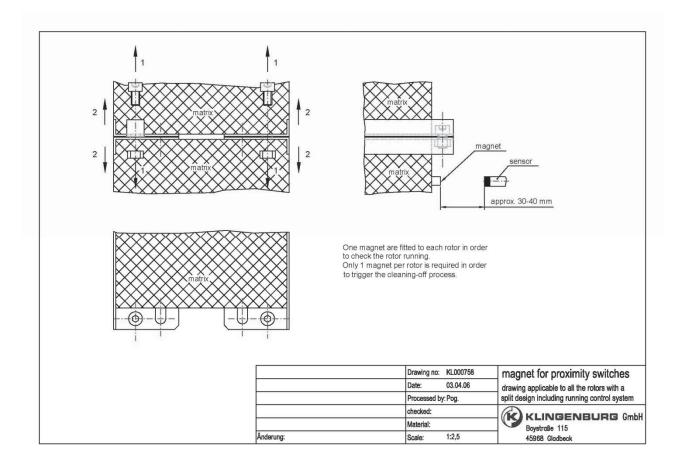
9. Controll works

After mounting of lateral sheet and doors the eventually existing leakages can be caulked with permanently elastic sealing material.

- Check wobble an height impact of the rotor.
- Check fastening of all screw connections.
- Check correct tensioning of the V-belt.

For informations about the connection of the driving motor see controller documentation. Fix air conduits with sheet metal screws to aluminum frame.





9.4 Assemble divided rotor for DV 190 og DV 240

1. Stückliste | 1. Bill of material

1. Stückliste der gelieferten Teile

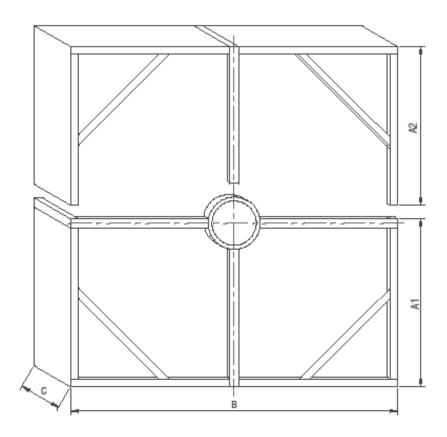
ab 3001 werden standardmäßig aus verzinktem Stahlblech pro-

Die Rahmen der Rotationswärmetauscher der Baugrößen RRS As a standard the frames of the rotary heat exchangers of the constructional sizes RRS from 3001 are made of galvanized steel

tauscher (ohne Verpackung):

Nachfolgend die Rahmenmaße der geteilten Rotationswarme- Frame dimensions of the split heat exchangers (without packing) as follows:

RRS	Höhe Heigh A1 + A2 (mm)	Unterrahmen Lower Frame A1 (mm)	Oberrahmen Upper frame A2 (mm)	Breite Width (mm)	Tiefe Depth (mm)
3500	3500	1800	1700	3500	550
4000	4000	2050	1950	4000	550
4500	4500	2300	2200	4500	550



2. Erforderliche Montagewerkzeuge

Zusätzlich zu normalen Montagewerkzeugen empfehlen wir:

- Hammer 1500 gr.
- Kunststoffhammer
- Hartholz
- 2 Stück Rundstangen D = 25 mm, L = 600 mm
- je 2 Stück Maulschlüssel 17, 19, 24 mm Schlüsselweite
- Gelenk-Umschaltknarre mit
 - Steckschlüsseleinsätze 7, 8, 17, 19 mm Schlüsselweite
 - Einsätze für Innensechskant 4, 6, 8, 10 mm
- elektr. Schlagschrauber
- Kombizange oder Seitenschneider
- Steh- oder Bockleiter
- Schraubendreher klein 2,8 mm
- Schraubendreher groß 10 mm
- 2 Stück Dorne aus 12 mm Rundmaterial
- Handfugenpistole incl. Kartuschen mit zulässigen Dichtungsmitteln

2. Mounting tools required

In addition to the normally used mounting tools we recommend the use of:

- Hammer 1500 gr.
- plastic tip hammer
- hardwood
- 2 pieces round bars, d = 25 mm, l = 600 mm
- 2 pieces of spanners, respectively, with openings of 17, 19, 24 mm
- flexible reversible ratched handle with
 - socket for wrenches with openings of 7, 8, 17, 19 mm
 - hexagon insert socket driver 4, 6, 8, 10 mm
- electrical impact screw driver
- engineer's pliers or side cutter
- double ladder
- screw driver small 2,8 mm
- screw driver big 10 mm
- 2 pieces drifts made of 12 mm round stock
- joint filing hand pistol, incl. permissable sealing materials

3. Allgemeine bauseitige Voraussetzungen

Der Untergrund muß eben sein, so daß der Rotor spannungsfrei aufsteht. Äußere Kräfte durch Kanalanschlüsse dürfen nicht in den Rotorrahmen eingeleitet werden. Es ist darauf zu achten, daß der Rotor gleichmäßig und gerade angeströmt wird. Der Rotor muß in der Anlage zugänglich sein, um Inspektionsarbeiten durchführen zu können.



3. Gerneral conditions by customers

For stress-free positioning of the rotor the surface shall be flat. External forces of channel connections shall not be lead into the rotor frame. Observe that the rotor is evenly and straightly blown against. For inspection purposes the rotor shall be accessible within the installation.



4. Stehender Rotor / waagerechte Teilung

会) 4. Vertical rotor/horizontal divisio

4.1 Bauseitige Voraussetzungen

Da das Gehäuseoberteil nach der Montage der Segmente aufgesetzt wird, ist oberhalb des Rotors ein freier Raum von mindestens 400 mm erforderlich. Steht dieser Raum nicht zur Verfügung, lesen Sie bitte die Ausführungen unter Punkt 4.4 auf Seite 10.

4.1 Conditions by customers

A free space of at least 400 mm is required above the rotor because the upper part of the housing is placed after the mounting of the segments. In case this space is not available see details of item 4.4 on page 10.

4.2 Montagebeschreibung

Ausrichten des Rotorunterteils und Befestigung am Boden. Diese Arbeit wird **nicht** durch Klingenburg-Monteure durchgeführt.



Wichtig:

Achten Sie darauf, daß der Rotor richtig herum montiert wird, da. ansonsten beim Einsatz einer Spülkammer die Funktion nicht mehr gegeben ist.

4.2 Mounting description

Alignement of the lower part of the rotor and fixing to the floor. This work is 110t done by Klingenburg personnel.



Important:

Observe correct mounting direction of the rotor for in case of use of a scavenging chamber functioning is no longer given!

Aufstellung der Rahmen und Speichermassengewichte sowie Anzahl der Speichermassenseg- as the storage mass segments valid for rotory mente gültig für geteilte Rotationswärmetauscher heat exchangers

Table of frames and storage mass weights as well

RRS	Speichermasse	Gewicht komplett Tauscher		Gewicht komplette Speichermasse	Segmente der Speichermasse
	Storage mass	complete weight exchanger	frame weight	compl. storage mass weight	Segments of storage mass
	Ø (mm)				[kg]
3500	3260	1170	630	540	8
4000	3760	1790	990	800	12
4500	4260	2120	1125	995	12

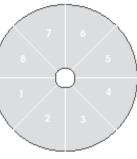
Aufstellung des Montagezubehörs

Table of mounting accessories

	Montagezubehör im Unterteil des Tauschers Mounting accessories of the lower part of the exchanger			
	Nut M16	Screw M10x95 and nut	Screw M12x16 and nut	Grub screw 4,8x19
			DIN 912/934	
3500	32	16	32	20
4000	48	24	48	20
4500	48	24	48	20

	V-belt SPA incl. Lock	Dust cover for bearing cover	Blind rivet steel 3x6 mm	Screw M12x30	Self locking nut M12
		Stück / Piece			
3500	11,2	2	20	8	8
4000	12,9	2	20	8	8
4500	14,6	2	20	8	8

Bei Anlieferung sind bereits die Hälfte der Rotorsegmentemontiert und vorgerichtet. Die Verbindungsstellen der einzelnen Segmente sind fortlaufend

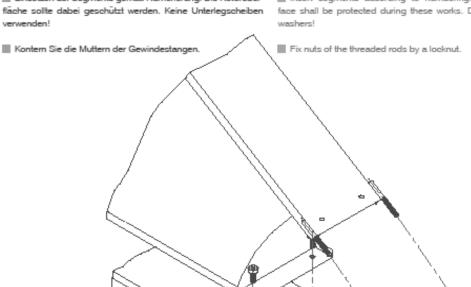


At delivery, half of the amount of the rotor segments is already assembled and preadjusted. The connection points of the individual segments are numbered continuously.

RRS D=2801 · 3759

RRS D=3760 · 4760

- Blockieren Sie den Rotor mit 2 Stück Rundstangen (D=25 mm, Länge=600 mm) zwischen Rotornabe, den angeschweißten Gewindestangen am Einfassungsblech und dem threaded rods at the bordering sheet and the bearing frame. Lagersteg gegen Drehung.
- Block rotor against rotation with 2 pieces round bars, (d=25 mm, l=600 mm) between the root of the rotor, the welded
- Einsetzen der Segmente gemäß Numerierung. Die Rotoroberfläche sollte dabei geschützt werden. Keine Unterlegscheiben
- Insert segments according to numbering. The rotor surface shall be protected during these works. Do not use plain



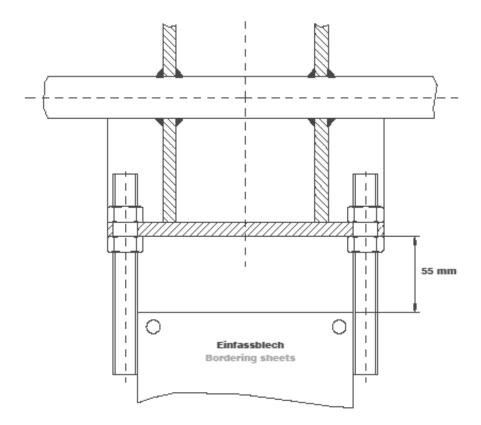


Achtung!

Der Abstand zwischen Außenkante Rotomabe und den Einfassblechen sollte ca. 55 mm betragen. Dieses Maß ist nur ein Anhaltswert, um alle Segmente einbringen zu können. Wird dieses Maß unterschritten, treten Schwierigkeiten beim Einbringen des letzten Segmentes auf.



The space between the outer edge of the root of the rotor and the bordering sheets shall be at about 55 mm. This measure is only for your orientation to insert all segments. If this measure is not kept it is difficult to insert the last segment.



Bringen Sie die Außenverschraubungen der Einfassungsbleche an. Schrauben festziehen.

Install external screw fitting of the bordering sheets. Drive home screws.



Wichtig

Die Einfassungsbleche der Segmente müssen ohne Spalt aneinanderliegen. Falls ein Spalt vorhanden ist, müssen die Muttern an den Gewindestangen verstellt werden.



.Important

The bordering sheets shall be contiguous without gap. In case of a gap the nuts at the threaded rods have to be adjusted accordingly. ■ Solite das letzte Segment klemmen, schrauben Sie bitte die
■ In case of jamming of the final segment slightly loosen the benachbarten Segmente etwas aus der Nabe heraus.

Mit den Gewindestangen in der Rotornabe können Sie das letzte The final segment can be inserted into the root of the rotor with Segment einbringen. Ist der Luftspalt des zuletzt montierten Segmentes zu groß, müssen sämtliche Segmente um ca. 2 bis 4 mm näher an die Rotornabe herangezogen werden.



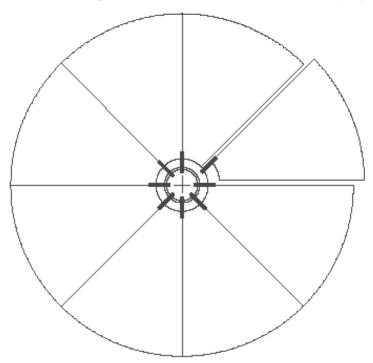
Alle Segmente nachziehen, sonst Tiefenschlag!

neighbouring segments from the root.

the threaded rods. In case the air gap of the last mounted segment is too big all segments have to be fetched about 2 to 4 mm closer to the root of the rotor.



Drive home all screws, otherwise depth impact!



4.3 Nachrichten der Rotorlagerung

Grundsätzlich ist die Rotorlagerung im Werk ausgerichtet. Sollte der Rotor jedoch verspannt eingebaut sein, kann ein Nachrichten erforderlich werden.

- Markieren Sie hierzu eine Segmenteinfassung
- Drehen Sie den Rotor, so daß die markierte Einfassung unten liegt.
- Messen Sie den Abstand der Segmenteinfassung zum Rotorrahmen

4.3 Redressing of the arrangement of bearings

The rotor bearing is basically adjusted by the manufacturer. In case of twisted assembly of the rotor, however, it maybe necessary to redress the bearing.

- Mark segment bordering
- Turn rotor to the position where marked border is upside down
- Meter the distance of segment borders to rotor frame

- Drehen Sie die markierte Einfassung nach oben
- Wiederholen Sie die Messung
- Beide Maße müssen mit einer Abweichung von + 2 mm über-
- Falls erforderlich, unterfüttern Sie die Lagerung
- Drehen Sie den Rotor, so daß die markierte Einfassung horizontal zur Rotorachse liegt
- Messen Sie den Abstand der Segmenteinfassung zum Rotorrahmen
- Drehen Sie die markierte Einfassung auf die andere Seite.
- Wiederholen Sie die Messung
- Beide Maße müssen mit einer Abweichung von + 2 mm übereinstimmen
- Falls erforderlich, verschieben Sie eines der beiden Lager auf dem Lagersteg

Turn marked border upside

Line bearing, if necessary Turn rotor to position where marked bordering is horizontal to

Both dimensions have to correspond with an allowance of +

- Meter distance of segment borderings to rotor frame
- Turn marked border to the other side
- Repeat metering

rotor axle

Repeat metering

- Both dimensions have to correspond with an allowance of + 2 mm.
- Adjust one of the two bearings on the border frame, if neces-

Die Rotorlagerung ist nun ausgerichtet.

Die einzelnen Segmente werden an den Gewindestangen in der Rotomabe ausgerichtet. Ein Seitenschlag von mehr als 3 mm sollte nicht erlaubt sein

Bei Rotoren ab der Baugröße RRS 3001 werden nun die Rückenbleche und Rundumspannreifen montiert und gespannt. Prüfen Sie vor dem endgültigen Anziehen der Verschraubungen noch einmal die Rotorausrichtung.

Wichtig: Gleichmäßiges Verschrauben der Spannreifen (2 Durchgänge):

- Schrauben anziehen, bis ein einheitliches Verspannen der Segmente zu sehen ist
- Mit einem Kunststoffhammer bzw. Hartholz und Handhammer die Spannreifen über den ganzen Umfang nachschlagen. Dann alle Verschraubungen nachziehen
- Seiten- und Tiefenschlag überprüfen
- Ziehen Sie sämtliche Verschraubungen fest an
- Setzen Sie das Gehäuseoberteil auf und verschrauben Sie es

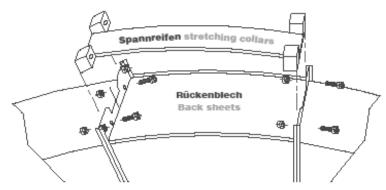
Now, the rotor bearing is adjusted.

The individual segments are adjusted at the threaded rods of the root of the rotor. A side impact exceeding 3 mm shall not be permitted.

With rotors from the constructional size RRS 3001. now back sheets and allround-stretching collars are mounted and tensed. Check again rotor alignement before final fastening of the screw connections.

Important: Even screw down of the stretching collars (2 stages):

- Fasten screws until even tensioning of the segments
- Coining of the stretching collars along the entire circumferential by means of a plastic tip hammer or hard wood and hammer. Then, refastening of all screw connections.
- Check wobble and depth impact.
- Screw down tightly all screw connections.
- Place upper part of the housing and screw it down.

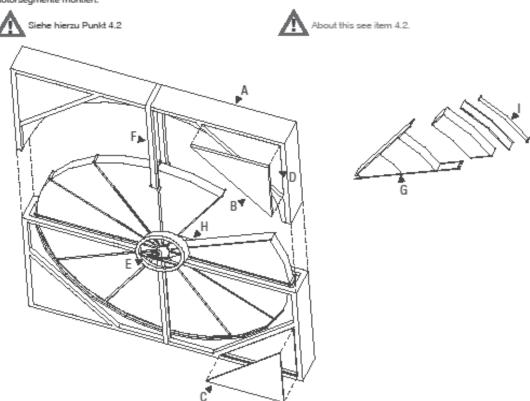


4.4 Montage unter beengten Platzverhältnissen

Steht Ihnen oberhalb des Rotors kein ausreichender Raum (ca. 400 mm) zur Verfügung, können Sie das Rotorgehäuse vor dem Einbringen der Segmente zusammensetzen. Wie in der Zeichnung ersichtlich, kann dann eine obere Rotorecke demontiert werden. Diese abschraubbare Ecke befindet sich immer überhalb des Antriebsmotors. Durch diese Öffnung werden dann die Rotorsegmente montiert.

4.4 Mounting in case of restricted space

In case of insufficient space (400 mm) above the rotor the rotor housing can be assembled before inserting segments. According to the figure, the upper rotor edge can be removed. The unscrewable edge is always located above the driving motor. The rotor segments can be mounted through this opening.



- A) Ab Rotorgröße 2500 sind die Gehäuse geteilt
- B) Die Rotoren sind mit abnehmbaren Dreiecksblechen ausgekleidet
- C) Der Motor ist durch Dreieckstür zugänglich
- D) Montageecke immer überhalb des Antriebsmotors.
- E) Außenliegende Lager
- F) Lagerstützstrebe
- G) Rotorsektor
- H) Rotortopf
- I) Spannreifen

- A) Housings are split from rotor size 2500 on
- B) The rotors are lined with removable sheets
- C) The motor is accessible by a triangular door
- D) Mounting edge always located above driving motor
- E) External bearings
- F) Bearing support stretcher
- G) Rotor sector
- HI) Rotor cup
- II) Stretching collar



5. Stehender Rotor / Senkrechte Teilung 5. Upright rotor / vertical division

In seltenen Fällen kann es erforderlich sein, das Rotorgehäuse senkrecht zu teilen. Das Gehäuse muß dann grundsätzlich vor dem Einbringen der Segmente komplett zusammengebaut werden. Die Montage der Segmente erfolgt dann wie unter Punkt 4.2 beschrieben.



In some rare cases it may be necessary to vertically split the rotor housing. The housing, then basically, has to be completely assembled before inserting the segments. Mounting of the segments according to item 4.2.



6. Liegende Rotoren

6. Horizontal rotors

6.1 Bauseitige Voraussetzung

Der Untergrund muß eben sein, so daß der Rotor spannungsfrei aufliegt. Äußere Kräfte durch Kanalanschlüsse dürfen nicht in den Rotorrahmen eingeleitet werden. Es ist darauf zu achten, daß der Rotor gleichmäßig und gerade angeströmt wird.



Wichtig:

Der Auflagepunkt des unteren Rotorlagers ist bauseits stabil zu unterstützen und zwecks Wartungszwecken leicht zugänglich sein. Hierzu unseren Vorschlag einer entsprechenden Konstruk-

6.1 Conditions by customers

For stress-free positioning of the rotor the surface shall be flat. External forces of channel connections shall not be lead into the rotor frame. Observe that the rotor is evenly and straightly blown against.

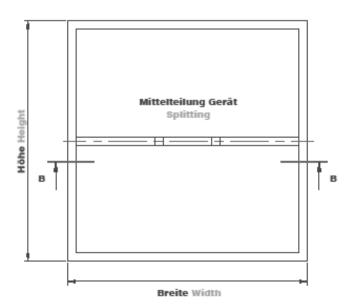


Important:

By customers, the point of support of the lower rotor bearing shall be solidly supported and easily accessible for maintenance purposes. The following describes our proposalfor for a corresponding design.

Schnitt B

Section B



6.2 Montagebeschreibung

Legen Sie die Gehäusehälfte, in der die halbe Rotormasse vormontiert ist, auf die Aufnahmekonstruktion.

Stecken Sie die andere Gehäusehälfte auf und befestigen Sie den Rahmen mit der Stützkonstruktion.



Wichtig:

Achten Sie darauf, daß der Rotor richtig herum montiert wird!

Die Rotorpakete setzen sich aufgrund ihres Eigengewichtes um ca. 5 mm, sobald der Rotor gelegt wird. Deshalb sind die vormontierten Rotorpakete um dieses Maß vorgespannt. Die Montage der Segmente verläuft analog zu der der stehenden Rotoren. Lesen Sie dazu bitte unter Punkt 4.2. und Punkt 4.4.

6.2 Mounting description

Place housing part containing the premounted half of the rotor mass onto the seat construction.

Stick second part of the housing and fasten frame with supporting construcion.



Important:

Observe correct mounting direction of the rotor!

Due to its dead weight the rotor settles about 5 mm as soon as the rotor is layed down. Therefore, the premounted rotor segments are pretensioned to this measure. Mounting of the segments is done analoguous to the mounting of the upright rotors. For this see item 4.2, and 4.4.

Der Rotorantrieb ist werkseitig vormontiert worden. Er ist auf einer Motorwippe befestigt, die durch eine Zugfeder unter Spannung gehalten wird. Der Keilriemen ist lose beigelegt. Der Gelenkverbinder ist einseitig vormontiert.

- Befestigen Sie ein Ende des Riemens mit einem Klebeband oder Draht am Rotorumfang und ziehen Sie es durch Drehung des Rotors um das Rad herum.
- Kurzen Sie den Riemen, der mit Überlänge geliefert wird, auf das erforderliche Maß.
- Verbinden Sie die Enden mit dem Gelenkverbinder
- Legen Sie ihn auf die Riemenscheibe auf
- Achten Sie darauf, daß der Keilriemen ausreichend gespannt ist und nicht am Gehäuse schleift
- Während des Betriebes verlängert sich der Keilriemen. Er muß gegebenenfalls gekürzt werden

7. Montage des Antriebs 7. Mounting of the drive

The rotor drive is premounted by the manufacturer. It is fixed to a motor-driven rocker dolly switch, which itself is kept tensioned by a tension spring. The V-belt is loosely attached. The flex connector is premounted on one side.

- Fix one end of the V-belt to the rotor circumferential by means of an adhesive or a wire and draw it around the wheel by turning the rotor.
- Shorten belt which is delivered with overlength to necessary size.
- Connect ends with flex connector.
- Put belt on pulley.
- See that V-belt is sufficiently tensioned and does not abrade at the housing.
- V-belt stretchens during operation. Thus, if necessary, it needs to be shortened.

8. Montage der Dichtungen

8. Mounting of the gaskets

Die Mittel- und Rundumdichtungen sind ab Werk vormontiert. Zu Center and eircumferential gaskets are premounted by manufstarkes Andrücken der Dichtungen gegen die Rotormasse ist zu acturer. Do not press gaskets against rotor mass because the vermeiden, da der Motor dadurch zu stark gebremst wird und motor is exceedingly retarded and may be damaged. beschädigt werden kann.



Tipp:



Schieben Sie die Dichtungen bei langsam drehendem Rotor in ihre endgültige Position.

Push gaskets to final position during slow rotation of the rotor.

9. Controll works

Nachdem Sie die Seitenbleche und Türen angebracht haben, können Sie eventuelle Undichtigkeiten mit dauerelastischem

- Dichtungs-material abdichten.
- Prüfen Sie den Seiten- und Höhenschlag des Rotors Prüfen Sie, ob sämtliche Verschraubungen angezogen sind Prüfen Sie, ob der Keilriemen ausreichend gespannt ist
- Informationen zum Anschluß des Antriebsmotors entnehmen Sie bitte den Reglerunterlagen.

Die Luftkanäle werden mit Blechtreibschrauben am Aluminium- Fix air conduits with sheet metal screws to aluminium frame. rahmen befestigt.

After mounting of lateral sheet and doors the eventually existing leakages can be caulked with permanently elastic sealing material.

- Check wobble an height impact of the rotor.
- Check fastening of all screw connections.
- Check correct tensioning of the V-belt.

For informations about the connection of the driving motor see controller documentation.

Wir hoffen Ihnen mit dieser Anleitung geholfen zu haben. Sollten We hope to be of assistance to you with this information. If there jedoch einmal Probleme oder Fragen auftauchen, so kontaktieren Sie uns:

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are any further questions, please do not hesitate to contact us anytime.

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9.5 Installation of motor that turns rotor and sensor for rotation

<u>Installation of rotor motor and sensor for control of rotation in DVC module after assembly of divided rotor</u>

Fig. 1



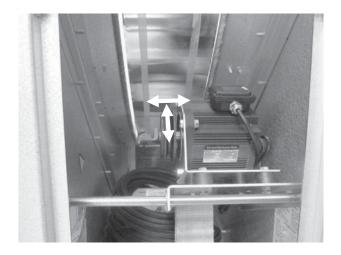


Fig. 2

By delivery of a DVC module with divided rotor, the motor is installed before delivery to the customer

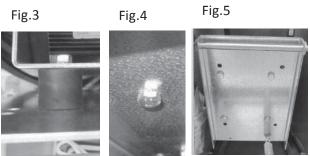


Fig. 3, 4 and 5

The motor and console is secured to the motor plate by 4 shock absorbers mounted by M8 bolts.

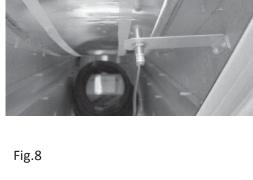




Fig. 2 og 6

The drive belt must be placed around the rotor and in the center position of the rotor. Observe brackets for assembly of the rotor segments.





1 - 4mm



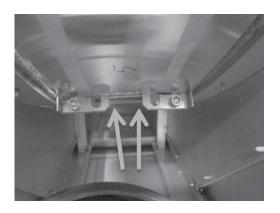


Fig. 7 and 8

. Sensor for control of rotation must be installed by the installer. The distance must be 1-4 mm from the outmost brackets used for the assembly of the rotor segments.

Fig. 9

Please be aware of the height of the brackets that are used for the assembly of the rotor segments. Please turn the rotor to check the sensor do not touch any of the brackets.

Annex 10. Reversible heat pump unit for cooling and heating

10.1 DVU-HP section (reversible heat pump unit)

The air handling unit section – DVU-HP – is a separate section in the air handling unit, containing a complete stand-alone reversible heat pump system (heating and cooling). The system has been tested and optimized before delivery. The refrigerant is evaporated and condensed directly in the integrated batteries and the capacity is controlled automatically and steplessly between 5 and 100 %.

The system is delivered with the refrigerant R-410a in the circuit. In the section an internal controller - pCOOEM - and a complete system control all safety functions as well as the capacity of the digital scroll compressor (digital compressor and additional on/off compressor in the larger units DV 20 – DV 80). The system creates exactly the capacity requested by the main air handling unit controller via a 0-10V DC control signal. When a demand for heating or cooling occurs, the main air handling unit controller sends a start signal for heating or a start signal for cooling as well as a capacity signal 0-10V DC to the internal controller in this section. When the signal exceeds 1.6 V DC, the digital compressor starts. After start-up the capacity is regulated between 5 and 50 % by the digital scroll compressor - C1 and Q6 - in the illustration below. When more than 50 % of the capacity is demanded, the control signal exceeds 5.0 V DC and the second compressor, C2 starts. Then the capacity of the digital compressor is reduced to the minimum and with increasing demand gradually increased to 100% capacity. The reverse sequences are activated by declining demand until the demand is less than 5 %. If the control signal is below 0.5V DC, the system will stop.

A full envelope control system in the internal control system prevents operation that exceeds safe conditions for any of the components. Signals from the high and low pressure transmitters, K3 and K4, contribute with information to ensure maximum performance without exceeding the set value and thereby prevent safety switches for the HP and LP, K1 and K2 from disconnecting cooling or heating. This system ensures maximum performance under the given flows and temperatures of supply air and exhaust air.

The system includes 2 electronic expansion valves. One for heating mode - Q3, and one for cooling mode - Q2. Super heat is controlled by the build-in controller and is based on signal showing the evaporating pressure measured by LP transmitter and temperature sensor placed in the common suction line at the compressor console. This ensures a very accurate and efficient performance of the system under all operating conditions.

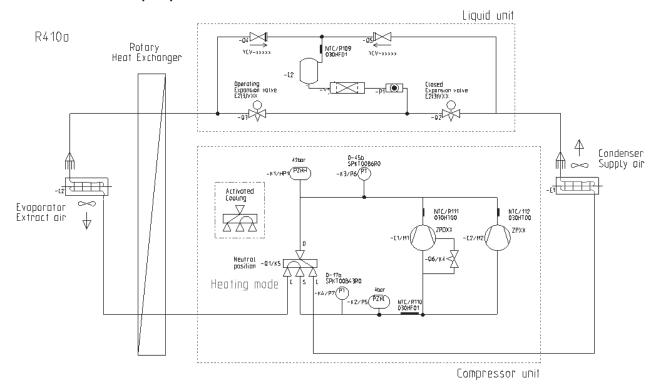
A 4-way valve Q1 changes the function of the system between heating and cooling mode.

The evaporator (condenser in cooling mode) on the DVU-HP unit is placed in the extract air flow after the rotary heat exchanger. This makes it possible to utilize the heat exchanger in booth heating and cooling mode for recovery of energy. This will minimize the power consumption of the compressor system.

A heating element has been installed below the evaporator in the drip tray to prevent ice buildup during heating operation.

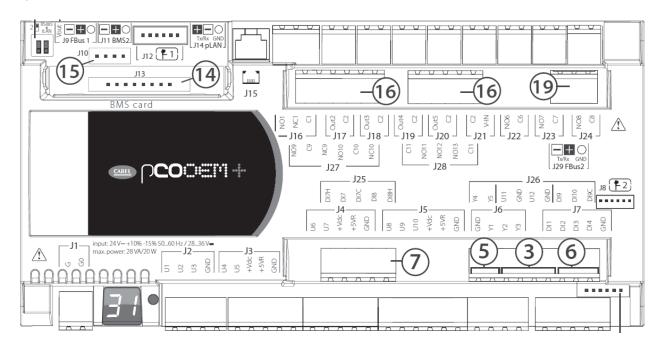
During heating operation, it is necessary to deice the evaporator in the exhaust air when operating at low outdoor temperatures. In the integrated control system, there is an advanced software function to detect the ice build-up. When ice build-up is at a certain level, a deicing cycle is initiated. During this cycle, the refrigeration system will reverse to bring energy to the coil in the exhaust air, to melt the ice. Once the control system detects that ice is gone, the system returns to normal heating operation. A very quick and efficient cycle.

10.1.1 DVU-HP - Heat pump circuit



10.1.2 DVU-HP- Electrical documentation

Wiring diagram for the integrated control system is available in a separate document. At power up, 2-segment LED display will light up with moving dots until controller and display is ready for operation.



10.1.3 Control signals

Signal:	Terminals:	Electrical:
Start (Heat mode)	X5; 18-19	Potential free contact
Cooling demand	X5; 16-17	Potential free contact
Capacity	X5; 10-11	10: gnd. 11: 0-10V _{DC}
Alarm	X5; 25-26	Potential free contact

10.2 DVU-HP-internal controller for the compressor system

Control panel pGD1 placed inside the integrated control cabinet



The control panel has 6 buttons with the following functions

Alarm	Display the list of active alarms Manually reset alarms
O-Prg	Access the service menu
• Esc	Return to the previous screen
- Up - Down	Navigate between the display screens or increase/decrease values
e-Enter	Switch from parameter display to edit Confirm value and return to the parameter list

By flashing red alarm light, there is an active alarm and display is not in alarm view. By permanent red alarm light, there is an active alarm and display is in alarm view

10.3 Background illumination of the display

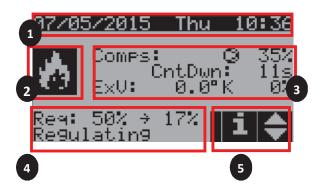
Background illumination of the display switches on automatically when the first push button is activated. The illumination switches off some time after the last activation. By alarm the red alarm button flashes until the alarm is acknowledged.

10.4 Menu - drawing of the menu structure to guide the user

Overview of the menus appears from annex 11.

10.5 The start display, Main menu

The following screen displays an example of the main screen with an active unit, highlighting the fields and icons used:



- 1. Date and Time
- 2. Current unit status:

Off	Unit OFF
***	Summer mode (cooling)
1	Winter mode (heating)
***	Defrosting in progress

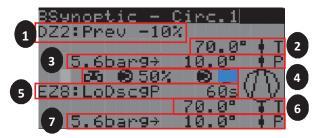
- 3. Devices status
 - a. Compressors in operation and digital capacity. Digital 35% output, fixed off)
 - b. Timer in action, Min on/off time, Min time between starts
 - c. Super Heat and Expansion valve opening
- 4. System capacity request and actual power output
 - a. System status
 - i. System OFF
 - ii. ON by input, but no capacity signal
 - iii. Regulating
 - iv. Pump-Down, and count down
 - v. Defrosting, and count up
 - vi. Manual mode
 - vii. OFF alarm
- 5. Indicates access to the info menu using the DOWN button

10.6 Settings

From the main screen, the DOWN (UP) button can be used to scroll through the status of devices. No password is needed to access these variables.

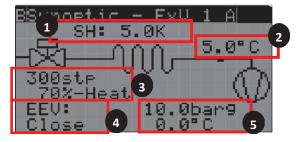
The physical status of inputs, outputs and transmitters are all available in the menus. The individual screens are shown below.

Compressor status:



- 1. Discharge temperature zone and prevent action.
- 2. Discharge temperature
- 3. Condensing pressure and temperature
- 4. Compressors status and digital percentage;
- 5. Envelope zone and time:
 - EZ1:Ok: zone within operating limits
 - EZ2:HiDP: High compression ratio
 - <u>EZ3:HiDscgP</u>: High condensation pressure
 - EZ4:HiCurr: High motor current
 - EZ5:HiSuctP: High suction pressure
 - EZ6:LoDP: Low differential pressure
 - EZ7:LoPRat: Low compression ratio
 - EZ8:LoDscgP: Low condensation pressure
 - EZ9:LoSuctP: Low evaporation pressure
- 6. Suction gas temperature
- 7. Evaporating pressure and temperature

Expansion Valve Overview:



- 1. Super Heat and actual set-point
- 2. Suction gas temperature
- 3. Valve opening mode, percentage and steps;
- 4. Valve status:
 - <u>Close</u>: valve closed
 - Std-by: system stop position
 - Pos: fixed position during sequence
 - <u>Wait</u>: after positioning and in case of change of cooling capacity greater than 10%, the valve to do large movement that can take some seconds. Wait will be displayed during this phase.
 - On: valve in regulation
 - Init: driver initialization
- 5. Evaporating pressure and temperature

Status Information:

Info Press ENTER to check advanced devices info → I/O status → Workin9 hours → Devices in manual → System info

Push Enter to get the following information:

Info Comp.1	- Output -Digital	Í scroll
NO1		- On
NO2 Di	9ital va	$_{ m alve_{ac}}$ Off
Power: Hours:	0000	100.0% 3/030000h

Info – Ou Bompressor	tput 2
N012	0ff
Houns:	0000/030000h arge alott

Info - Output	
Y1-Envelop:	0.0%
Y2-Comp.fbk:	100.0%
Y3-ExV perc.:	0%

Info - Capacity	Input reference
U7	50.2%

<u> Info - Input</u>	
ID1-Alarm reset:	Off
ID2-Coolin9:	Cool
ID3-Defrost:	Ok
ID4-Remote ON:	On

Info - Input Defrost	
Evap.temp.: Filtered: CntDwn: 2990 Defrost status:	0.0°C 0.0°C
Defrost status: Check start	- 5s

	Input	
Suction NA:	Pressure	0.0bar9
Evap.ter	np.:	. 0.0°C
Suction U2:	mp.: temperat	ure 0.0°C

Info - Input	
Dischar9e pressure U5: 27.0	Bar9
Cond.temp.: 745 Dischar9e temperat	6.8°C
U4: 15	7°°C 1.7°°C
	ģ.0°Č

Info - Input	
Dischar9e temper	rature
U11 Comp.2:	0.0°C
U12 Comp.3:	0.0°C
Optional probes	
U8:	0.0°C
W9:	0.0°C
U10:	0.0°C

Informatio	on
NOSTDmCOMM Version: Date:	2.1.009 06/05/15
Bios: 6.27 Boot: 5.00	09/07/04 09/07/04

2048KB
- 1024KB
208ms

```
Info - Dig.In

ID7-Comp.alarm: Ok
ID8-Phase alarm: Ok
ID9-Low press.: Ok
ID10-High press.: Ok
```

10.7 Service

Regardless of the displayed screen, pressing the programming key accesses the password entry screen which allows access to the menu shown below for service level. Enter the password (1111) and push enter. Once the password is entered, it will be maintained for 5 minutes from the last time a key was activated. Then the password will have to be re-entered in order to access the service level again. In the Log-Out menu, you can log-out without waiting 5 minutes.

Service level gives read access to all parameters with the ability to edit some of them. For more information on the parameters that can be changed, see the parameter table. Default password: 1111.



As soon as the password is entered in the log in screen, and function selected, the access level needed to edit the values is shown. As shown in the following screens, S flashing for Service and M for Manufactor:

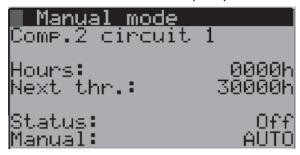
```
Manual mode
Comp.1 circuit 1
Hours: 0001h
Next thr.: 30000h
Status: 100%
Manual: AUTO
```

```
M)ExV
Enable pumpdown: YES
Type: AT STOP
```

10.8 Manual operation

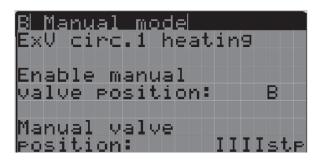
From the menu – Manual mode – it is possible to operate components manually. The technician can control the operation of components manually. This procedure is relevant for the test during the annual maintenance with the control of all safety and control functions or after exchange of components. Menus as follows:

In the first screen above: Compressor 1 status. Actual operating hours. Next threshold of operating hours for service can be set. Current capacity and selection of manual mode.



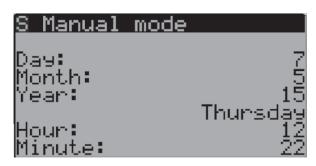
Compressor 2 status. Actual operating hours. Next threshold of operating hours for service can be set. Current status and manual selection.

When operating compressors manually, Super Heat control will still be active as long as set to Auto.

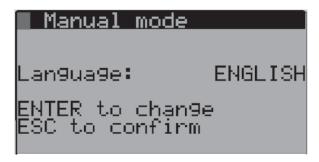


Preliminary

Expansion valves can be operated manual individually. The valve do have 0-480 steps



Date and time



Only English is available

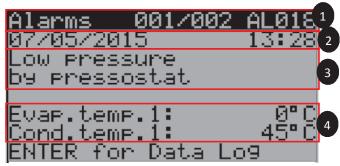
10.8.1 Running hours

This is available in the menu for maintenance.

10.9 Alarm

10.9.1 Alarm

By pushing the Alarm button, you can see any active alarm.



- 1. Alarm 1 of 2 active alarms which has not been reset. Alarm number from list below
- 2. Time and date of alarm
- 3. Alarm type
- 4. Operating conditions at the point of alarm

10.9.2 Alarm Log

By using the enter key you can enter the alarm log. Up to 100 alarms are saved.

10.9.3 Alarm reset

Alarms can be reset manually, automatically or with retries.

- Manual reset: When the alarm condition is no longer present, you must enter alarm menu and acknowledge the alarm by pushing the alarm button. Now the unit can restart.
- Automatic reset: When the alarm condition is gone, the system will automatically restart. Still holding min off time.
- Automatic reset with retries: Retry conditions are checked, if OK, it will be automatic reset mode. If not, it will be manual reset mode.

10.9.4 Alarm list

Code	Description	Reset	Action	Delay
AL001	Probe U1 broken or disconnected	Α	None	10s
AL002	Probe U2 broken or disconnected	Α	Circuit OFF	No
AL003	Probe U4 broken or disconnected	Α	Circuit OFF	10s
AL004	Probe U5 broken or disconnected	Α	Circuit OFF	No
AL005	Probe U6 broken or disconnected	Α	Circuit OFF	10s
AL006	Probe U7 broken or disconnected	Α	None	No
AL007	Probe U8 broken or disconnected	Α	None	10s
AL008	Probe U9 broken or disconnected	Α	None	10s
AL009	Probe U10 broken or disconnected	Α	None	10s
AL010	Probe U11 broken or disconnected	Α	Compressor 2 OFF	10s
AL011	Probe U12 broken or disconnected	Α	Compressor 3 OFF	10s
AL012	Low SH alarm	М	Circuit OFF	180s
AL013	LOP alarm	А	Circuit OFF	180s
AL014	MOP alarm	А	Circuit OFF	180s
AL015	Low suction temp.	Α	Circuit OFF	180s
AL016	High discharge press.	М	Circuit OFF	3 retries
AL017	Low suction pressure	Α	Circuit OFF	3 retries
AL018	Low pressure by pressostat	А	Circuit OFF	3s
AL019	Envelope alarm	Α	Circuit OFF	300s
AL020	Motor phase alarm	Α	Circuit OFF	No
AL021	High pressure by pressostat	М	Circuit OFF	3 retries
AL022	High discharge temp. compressor 1	А	Circuit OFF	60s
AL023	High discharge temp. compressor 2	Α	Compressor 2 OFF	No
AL024	High discharge temp. compressor 3	А	Compressor 3 OFF	No
AL025	Pump-down end for max time circuit 1	Α	None	No
AL026	Maintenance request compressor 1	А	None	Parameter
AL027	Maintenance request compressor 2	Α	None	Parameter
AL028	Maintenance request compressor 3	А	None	Parameter
AL029	Clock alarm	Α	None	No
AL030	Memory expansion damaged	Α	None	No

10.10 Maintenance

General maintenance must be carried out according to national and local regulations by a skilled technician from a certified company.

List of spare parts as well as datasheets from the manufacturers are available on the DVD delivered with the unit.

10.11 DVU-HP- Data

Dimensions, heating and cooling capacity, refrigerant content

DVU-HP	10	15	20	25	30	40	50	60	80
Width in mm	970	1120	1270	1420	1570	1720	2020	2170	2170
Height in mm	970	1120	1270	1420	1570	1720	2020	2240	2540
Length in mm	1420	1420	1420	1420	1570	1570	2320	2460	2460
Weight in kg	190	240	280	375	400	550	700	1000	1200
Power supply – 3 phase + N + Pl	3x400V	+ N + PE							
Pre fuse Amp.	use Amp. 10A 16A 20A 25A 32A 40A 50A								63A
Refrigerant	R410a	R410a	R410a	R410a	R410a	R410a	R410a	R410a	R410a
Refrigerant content in kg	3	4	6	8	10	12	24	26	28
Test pressure, 46,2 bar									
Nominal air volume, m3/s	1.0	1.4	1.9	2.4	2.9	3.6	5.0	5.9	6.7
Cooling capacity, kW	14	18	27	32	37	47	64	78	80

Values based on 50°C condensing temperature and 10° evaporating temperature

Detailed performance data can be found by using design program SystemairCAD

10.12 Data plate

The data plate for the cooling unit is mounted inside the unit section – DVU-HP – behind one of the doors. **An example** of the data plate is shown below.

Inside the unit

DVU-HP-25 Cooling circuit: Control cabinet: Mfg. Year:2015 Supply voltage:3x400VAC+N+PE Serial No.:2500010 Min fuse:25A Fluids:R410a Max fuse:32A Min short circuit level:650A Quantity:7 kg. Compressor:EmmersonZPD61 + ZP61 Max short circuit level:10kA Max working temperature: 65oC Cable colours: Max working temperature:-40oC Protection circuit: Green/yellow Max working pressure:43 bar Fase-VAC:Black Test pressure:47.3 bar Neutral-VAC:Black Max running load:23,6A 24VDC:Gray 10VDC:Gray Analog/digital signal:Grey Systemair A/S Denmark +458738 7500

Outside on the unit



Control cabinet:

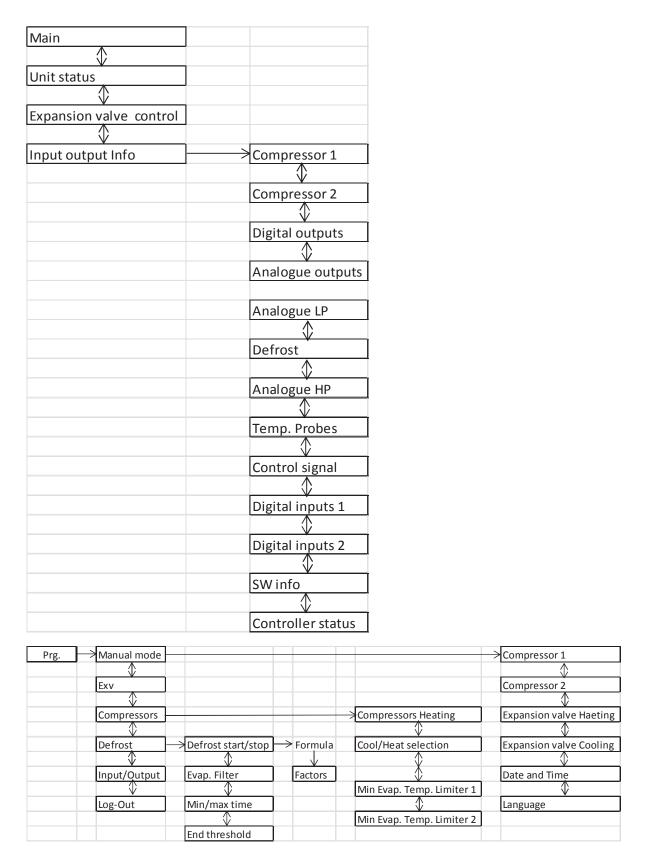
Supply voltage: 3x400VAC+N+PE
Min fuse: 63A
Max fuse: 80A
Min short circuit level: 650A
Max short circuit level: 10kA

Cable colors:

Protection circuit: Green/yellow

Fase-VAC: Black
Neutral-VAC: Black
24VDC: Grey
0VDC: Grey
Analog/digital signal: Grey

Annex 11. Menu for internal controller in the DVU-HP

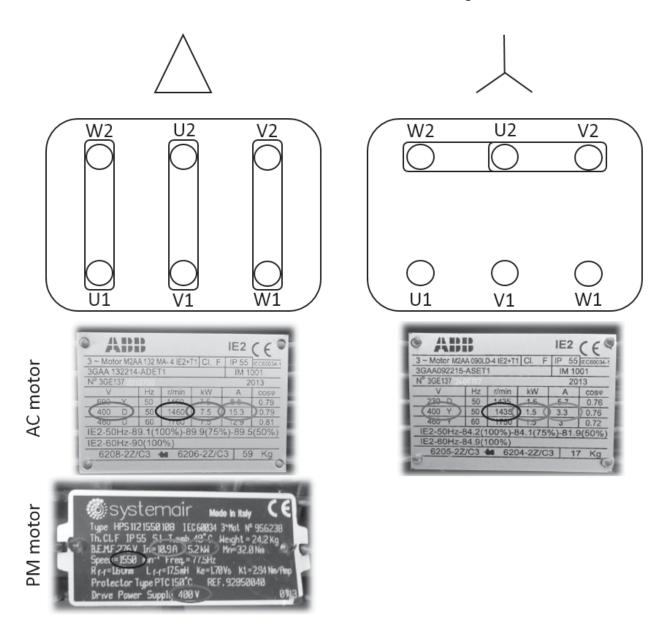




Annex 12. Connection of fan motor and set-up for frekv. conv.

12.1 Connection of fan motor

Delta connection is shown to the left, and star connection is shown to the right.





12.2 Set-up for Danfoss FC101 for DV-units with AC motors SETUP IS DONE IN FACTORY BEFORE DELIVERY

To reload Systemair factory settings from the control panel:

0-50: **LCP Copy:** [2]

Systemair factory set-up is based on Danfoss initialization.

14-22: **Operation mode:** [2] Initialisation (Danfoss Initialisation)

Turn power off and on.

Systemair factory set-up:

0-01: Language selection:

1-03: **Torque characteristic:** Single fan: [3] Auto-Energy optim.

With twin fan set-up: [1] Variable Torque

1-20: **Motor Power:** According to motor plate / order papers

With twin fan set-up total power must be used

1-24: **Motor Current:** According to motor plate / order papers

With twin fan set-up total current must be used

1-25: **Motor Nominal Speed:** According to motor plate / order papers

1-42: Motor Cable Length: 3m 1-50: Motor Magnetisation at zero speed.: 0 %

1-52: **Min. Speed Normal Magnetisation:** 10 Hz

1-73: Flying Start: [0] Disabled

1-90: Motor Thermal Protection: [2] Thermistor trip
 3-15: Reference 1 Source: [2] Analog input AI54
 1-93: Thermistor Source: [1] Analog input AI53

3-03: Maximum Reference: Max. Hz from order papers

3-16 + 3-17: **Reference 2- and 3 Source:** [0] No function

3-41 + 342: **Ramp 1 up and down:** 20 Sec.

4-19: Max. Output Frequency: 90Hz 4-14: Motor Speed High Limit: 90Hz

4-18: **Current limit:** 100 %

5-12: **Terminal 27 Digital input:** [0] No operation

5-40.0: **Function Relay:**[3] Drive ready/remote
5-40.1: **Function Relay:**[3] Drive ready/remote
6-25: **Terminal 54 High Reference:**Max. Hz from order papers

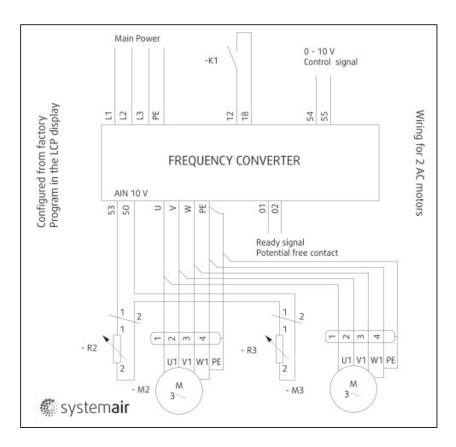
14-03: **Over modulation:** [1] Active

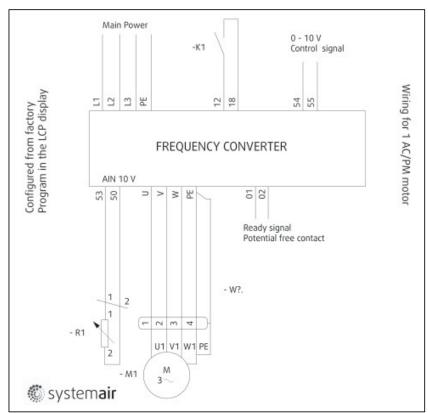
14-20: **Reset Mode:** [2] Automatic reset x 2

0-50: LCP Copy: [1] All to LCP (Copy of Systemair factory settings to panel)

Connections:

0-10V: terminal 54-55
Start: terminal 12-18
Thermistor: terminal 50-53
Drive ready: terminal 1-2







12.3 AC-fan operation without thermistor for Danfoss FC101.

Systemair factory set-up is based on Danfoss initialization.

14-22: **Operation mode:** [2] Initialisation (Danfoss Initialisation)

Turn power off and on.

Systemair factory set-up:

0-01: Language selection:

1-03: **Torque characteristic:** [3] Auto-Energy optim.
1-20: **Motor power:** According to motor plate
1-24: **Motor Current:** According to motor plate
1-25: **Motor Nominal Speed:** According to motor plate

1-29: **Automatic motor adption (AMA):** [1] Kompl.motor adaption to (Turn power off and on.)

1-42: **Motor Cable Length:** Order specific

1-50: Motor Magnetisation at zero speed.: 0 % 1-52: Min. Speed Normal Magnetisation: 10 Hz

1-73: Flying start: [0] Deaktivated

5-40.0: Function Relay: [3] Drive ready/remote

14-03: Over modulation: [1] Active

14-20: Reset Mode: [2] Automatic reset x 2

0-50: LCP Copy: [1] All to LCP (Copy of Systemair factory settings to panel)

Connections:

0-10V: terminal 54-55

Start: terminal 12-18
Drive ready: terminal 1-2
Jumper terminal 12-27



12.4 Set-up Danfoss FC101 for DV-units with PM motors

SETUP IS DONE IN FACTORY BEFORE DELIVERY

To reload Systemair factory settings from the control panel:

0-50: **LCP Copy:** [2

Systemair factory set-up is based on Danfoss initialization.

14-22: **Operation mode:** [2] Initialisation (Danfoss Initialisation)

Turn power off and on.

Systemair factory set-up:

0-01: Language selection:

1-06: Clockwise Direction: [1] Inverse

1-10: Motor Construction: [1] PM, non-salient SPM

1-24: Motor Current: According to motor plate / Schedule

1-25: Motor Nominal Speed: According to motor plate / Schedule

1-26: Motor Cont. Rated torque: According to motor plate / Schedule

1-30: Stator Resistance (Rs): According to motor plate / Schedule 1-37: d-axis inductance (Ld): According to motor plate / Schedule

1-39: Motor Poles: According to motor plate / Schedule 1-40: Back EMF at 1000 RPM: According to motor plate / Schedule

1-42: Motor Cable Length: 3m

1-90: Motor Thermal Protection: [2] Thermistor trip
3-15: Reference 1 Source: [2] Analog input AI54
1-93: Thermistor Source: [1] Analog input AI53

3-03: Maximum Reference: According to motor plate / Schedule

3-16 + 3-17: Reference 2- and 3 Source: [0] No function

3-41 + 3-42: Ramp 1 Up and down: 30 sec.

4-19: Max. Output Frequency: According to motor plate / Schedule 4-14: Motor Speed High Limit: According to motor plate / Schedule

4-18: Current limit: 115 %

5-12: Terminal 27 Digital input: [0] No operation 5-40.0: Function Relay: [3] Drive ready/remote 5-40.1: Function Relay: [3] Drive ready/remote

6-25: Terminal 54 High Reference: According to motor plate / Schedule

14-03: Over modulation: [1] Active

14-20: Reset Mode: [2] Automatic reset x 2

0-50: LCP Copy: [1] All to LCP (Copy of Systemair factory settings to panel)

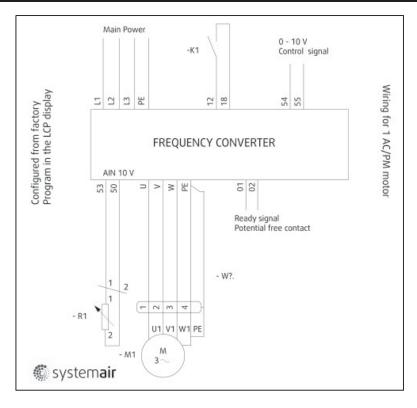
Connections:

0-10V: terminal 54-55
Start: terminal 12-18
Thermistor: terminal 50-53
Drive ready: terminal 1-2



Schedule for PM motor parameters

Menu:	124	125	126	130	137	139	140	303 + 625	414 + 419
	Amp	Motor	Nm						
Motor Type	Name	RPM	Name	Ohm			Bemf @		Max
Number	plate	rated	plate	[Rf-f]	mH [Lf-f]	Poles	1000	Max Hz	motor Hz
HPS 71 3800 18	1,8	3800	2	3,600	13,00	6	67	215	219
HPS 71 3700 28	2,8	3700	3,6	1,580	6,10	6	79	191	204
HPS 71 3300 18	1,8	3300	2,6	5,750	20,50	6	85	170	182
HPS 71 3200 30	3	3200	4,2	1,850	7,25	6	84	161	176
HPS 71 2900 21	2,1	2900	3,3	4,500	14,75	6	95	143	160
HPS 71 2800 40	4	2800	6,14	1,675	6,75	6	95	144	154
HPS 71 2500 29	2,9	2500	5	3,000	11,00	6	105	129	138
HPS 71 2350 38	3,8	2350	7,3	2,300	9,35	6	115	120	129
HPS 90 2650 64	6,4	2650	9,6	1,250	10,75	8	87	182	194
HPS 90 2350 76	7,6	2350	13	0,800	10,00	8	103	159	172
HPS 90 2100 63	6,3	2100	10,5	1,500	14,75	8	101	142	154
HPS 90 2050 100	10	2050	19	0,810	8,75	8	115	140	150
HPS 90 1850 84	8,4	1850	16	1,050	11,50	8	110	127	136
HPS 90 1900 136	13,6	1900	26	0,575	7,25	8	110	127	139
HPS 90 1700 106	11	1700	22	0,575	7,25	8	117	116	125
HPS 112 1550 108	10,9	1550	32	0,750	8,75	6	178	80	85
HPS 112 1700 145	14,5	1700	39	0,465	5,45	6	162	88	94
HPS 112 1350 135	13,5	1350	44	0,490	6,45	6	197	69	74
HPS 112 1500 187	18,7	1500	54	0,295	4,35	6	175	76	83
HPS 112 1000 140	14	1000	51	0,475	7,00	6	242	54	55
HPS 132 1250 199	19,9	1250	69	0,255	7,60	6	210	65	69
HPS 132 1000 202	20,2	1000	77	0,315	9,25	6	230	51	65
HPS 132 1150 300	30	1150	104	0,235	8,00	6	230	58	65
HPS 132 930 273	27,3	930	118	0,280	9,75	6	261	46	65





Annex 13. **Commissioning**

See separate cover with annexes 1, 2, 3, 13 and 14

Annex 14. **Test report**

See separate cover with annexes 1, 2, 3, 13 and 14

Annex 15. **Components**

15.1 DV units delivered in several sections

This model of the DV unit has an integrated control system and depending on the size of the unit, the cabinet is installed on the unit or on the front of the unit. The 2 controllers - Systemair E28–2 port controller and a Systemair E28 expansion - both controllers are mounted in the cabinet, and all electrical connections between cabinet and components in the unit are installed. The control system is configured according to the customer's order – confirmed by the order confirmation - to promote easy start-up on the site. The unit is tested at the factory and all functions are confirmed by a final functional test and test report. The test report is annex 14 for the User Manual. After the final test the unit is divided in sections to facilitate the transport. After reassembly of the unit on the site, the clearly marked cables with sockets must be reconnected in the marked cabinet terminals. Cable strips are preinstalled for installation of the cables between the components in the unit-sections and the cabinet. Cables installed on the unit-sections in the preinstalled strips are protected by metal covers. The covers have been removed before installation of the unit on the final site and must be replaced after installation of the cables. Cables with the mains power supply must be installed in the automatic circuit breakers belonging to fans, cooling compressor unit DVU (if delivered) and cooling compressor unit with rotary heat exchanger – DVU-C (if delivered). All external components must be connected on the site.

External components

External components are Systemair Control Panel, valves, valve motors, pressure transmitters, supply air temperature sensor, sensor for water temperature in the heating coil (if water heating coil was requested) and circulation pump (Systemair does not deliver the pump). Terminals are present in the cabinet for pressure transmitters, if it is a solution for constant pressure in the ducts, and terminals are present in the cabinet for valve motors, circulation pump, supply air temperature sensor and sensor for water temperature in the heating coil, but cables are not installed and not connected to terminals in the cabinet. The Systemair Control Panel with 10 meters of cable is not connected to the controller in the cabinet. All external components delivered are packed in a cardboard box delivered together with the unit.

15.2 DV unit delivered assembled on base frame

This model of the DV unit has an integrated control system and the cabinet mounted inside the unit. The cabinet is always mounted in the unit section with the heat exchanger and the cabinet is always placed at the warm side of the heat exchanger. The intelligent controllers – Systemair E28–2 port controller and a Systemair E28 expansion - both controllers are mounted in the cabinet, and all electrical connections between cabinet and components in the unit are installed. The control system is configured according to the customer's order – confirmed by the order confirmation - to promote easy start-up on the site. The unit is tested at the factory and all functions are confirmed by a final functional test and test report. The test report is annex 14 for the User Manual. The unit is delivered as one assembled section on base frame. Cables with the mains power supply must be installed in the automatic circuit breakers belonging to fans, cooling compressor unit DVU (if delivered) and cooling compressor unit with rotary heat exchanger – DVU-C (if delivered). All external components must be connected on the site.



External components

External components are Systemair Control Panel, valves, valve motors, pressure transmitters, supply air temperature sensor, sensor for water temperature in the heating coil (if water heating coil was requested) and circulation pump (Systemair does not deliver the pump). Terminals are present in the cabinet for pressure transmitters, if it is a solution for constant pressure in the ducts, and terminals are present in the cabinet for valve motors, circulation pump, supply air temperature sensor and sensor for water temperature in the heating coil, but cables are not installed and not connected to terminals in the cabinet. The Systemair Control Panel with 10 meters of cable is not connected to the controller in the cabinet. All external components delivered are packed in a cardboard box delivered together with the unit.

Annex 16. Wiring diagram

See below



Danvent DV Annex 16 - Wiring diagrams



PDF file is listed as follows:

General description 1 - 9

Circuit diagram 10 - 44

Switchboard layout 45 - 49

Terminal matrix 60 - 69

Cable plan 70 - 99



supplier:

Systemair A/S, Denmark Ved Milepælen 7 8361 Hasselager Units with external cabinet:

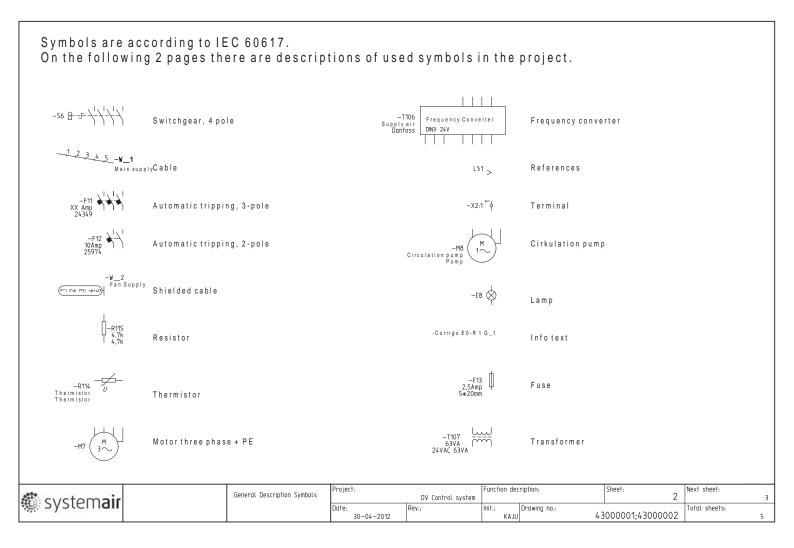
DV 10-40 are placed on top of the unit. DV 50-240 are placed on front of the unit

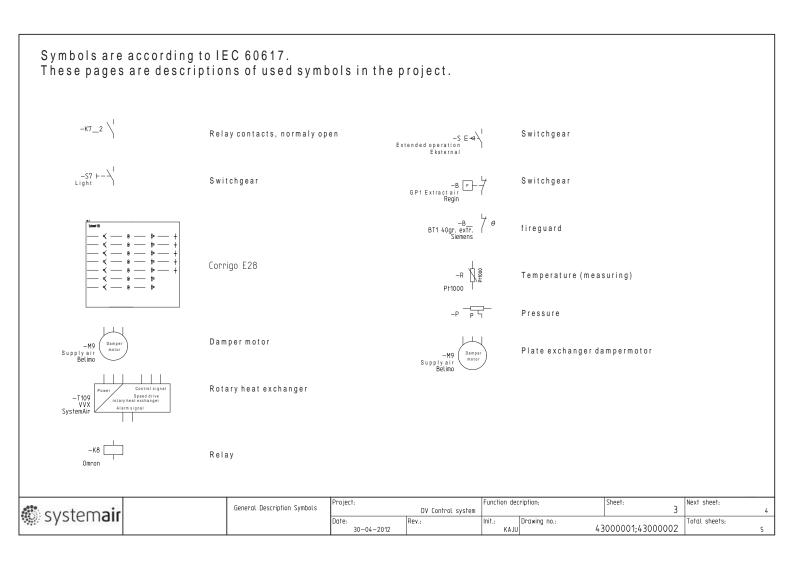
Units with internal cabinet: Cabinet is always inside the unit.

Components according to functions are mark with **

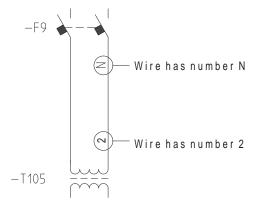
** systemair		General Description Pages Project: DV Control system Func		Function decription:	Sheet:	Next sheet:	2	
system air			Date: 30-04-2012	Rev.:	Init.: Drawing no.: 4	3000001;43000002	Total sheets:	5

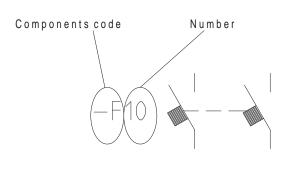
Bilag 16





Labeling of wires Cables are marked with terminal name Components are marked with component codes followed by a number according to IEC 61346-1 Chart 1





			Project:		Function dec	ription:	Sheet:	Next sheet:	
*** cyctomair		General Description Wires		DV Control system			4		5
systemair			Date:	Rev.:	Init.:	Drawing no.:		Total sheets:	\neg
			30-04-2012		KAJU	43	3000001;43000002		5
	•		•	•					

Component codes used in the project

S = switchgear

F = automatic tripping

M = pump / Damper motor / valve motor

R = temperature sensors

T = VLT Converter / transformer

P = lamps

C = controller

B = fire guard / pressure guard / pressure transducer

W = cables

K = relay coils

X = terminal

U = cabinet

Data for the unit

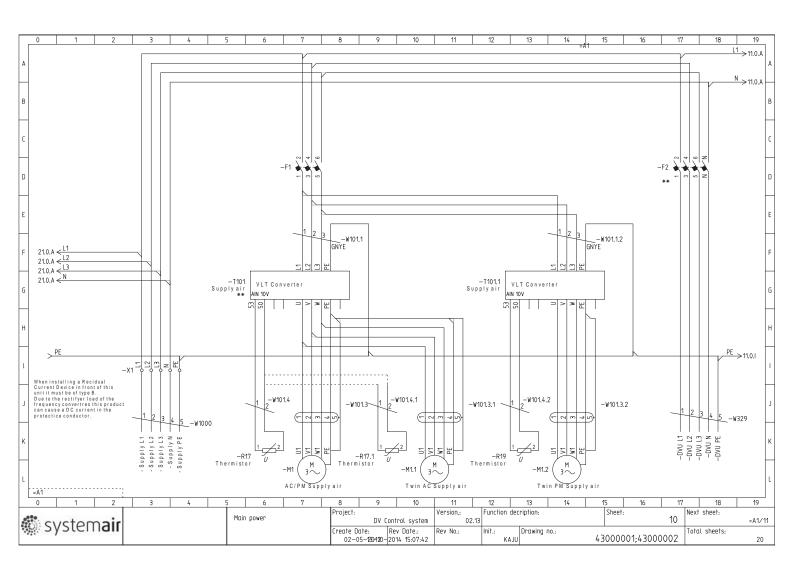
Max load look in order paper

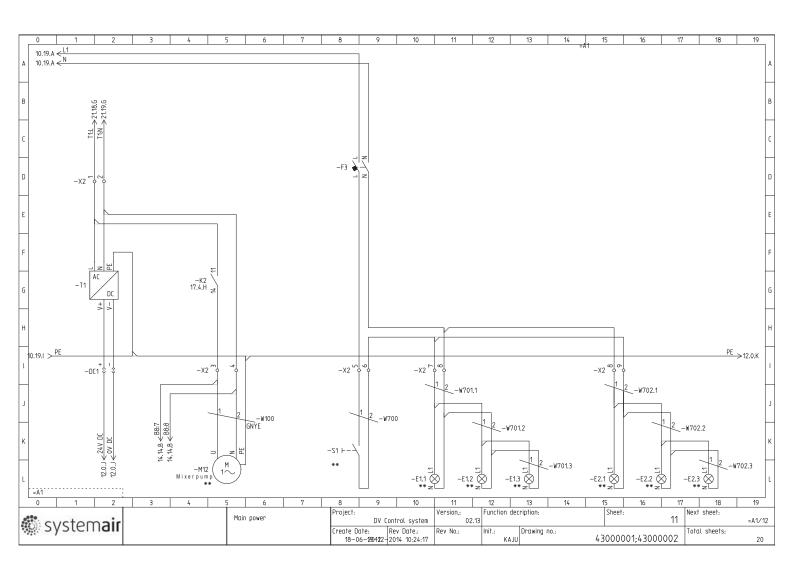
Max pre-fuse look in order paper

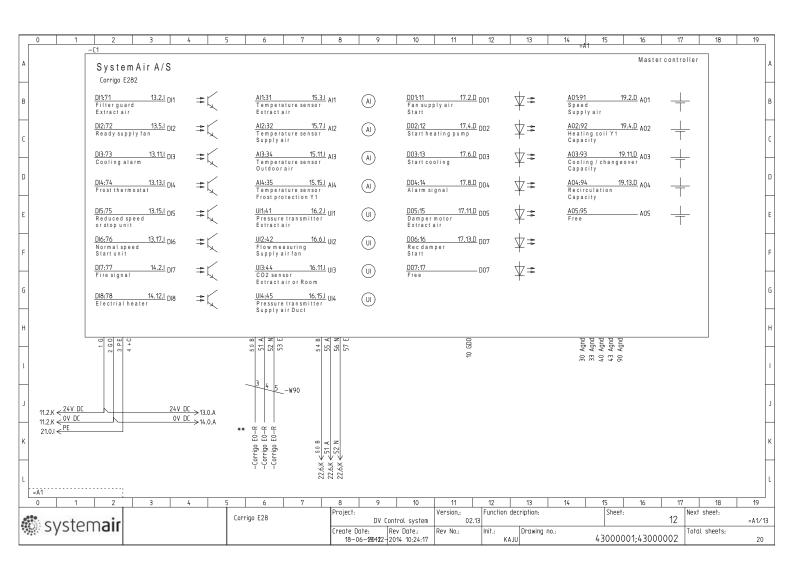
lk max. 16kAmp

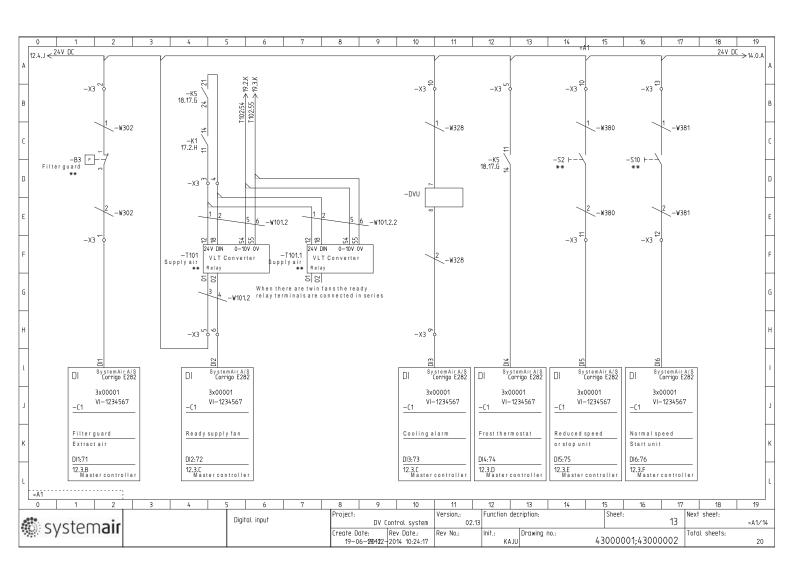
RCD type B

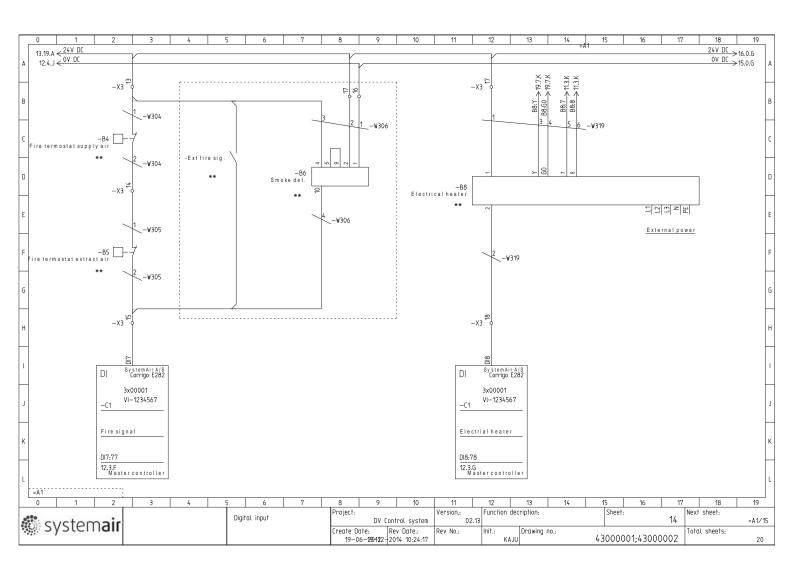
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* cyctomair	General Description		DV Control system			5		
system air		Date:	Rev.:	Init.:	Drawing no.:		Total sheets:	
		30-04-2012		KAJU	4	3000001;43000002	1	5

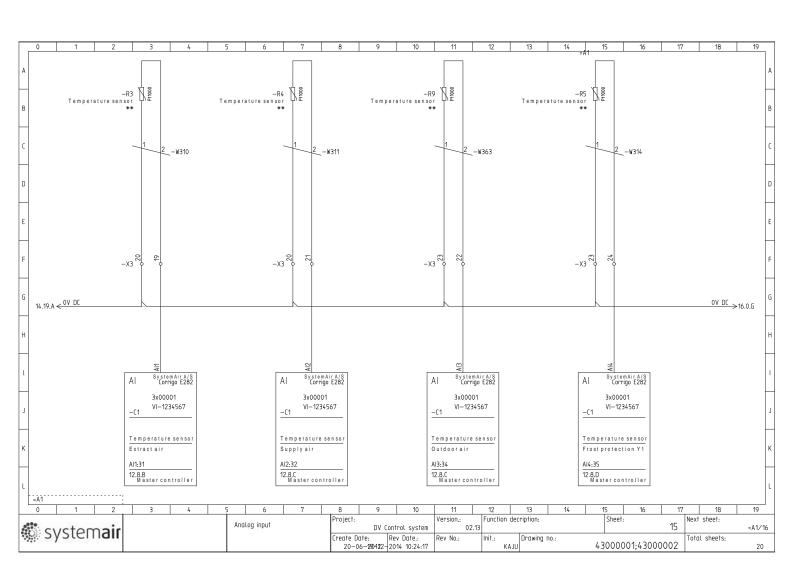


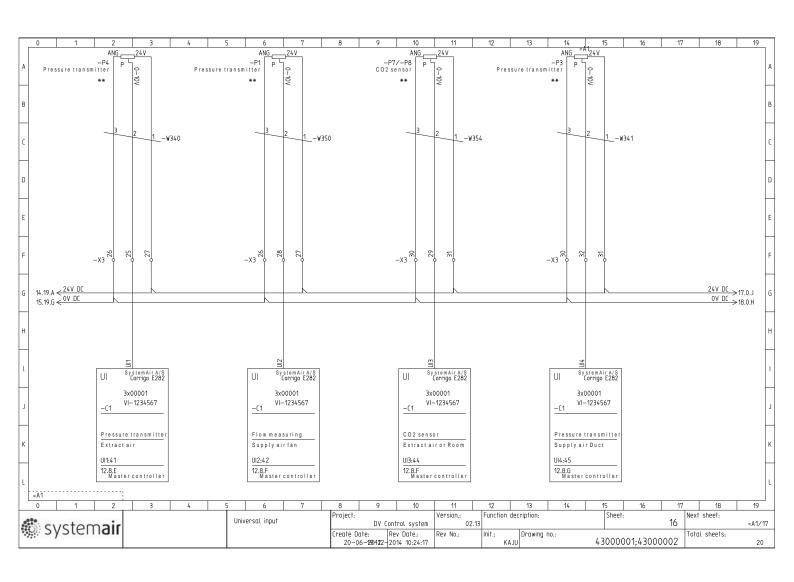


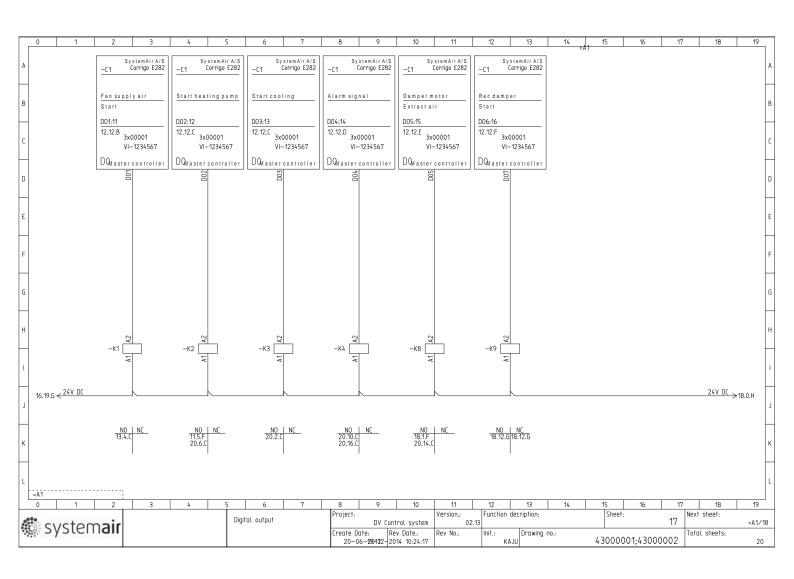


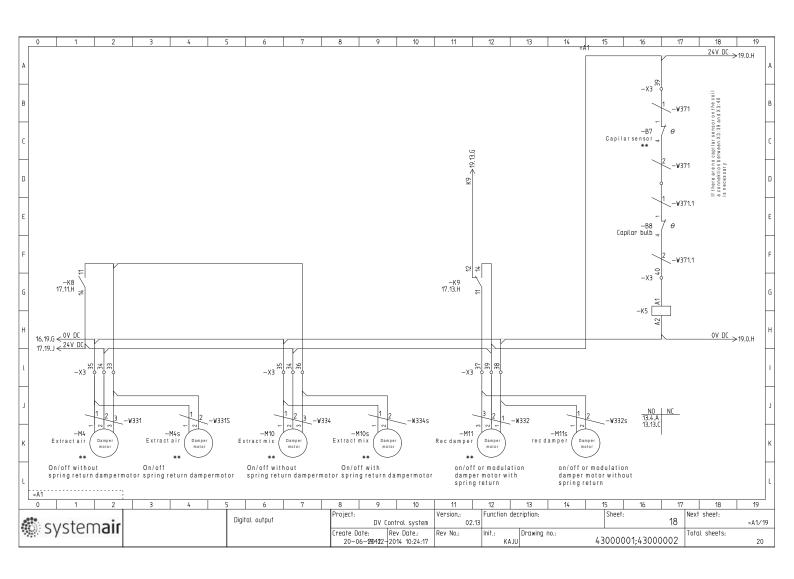


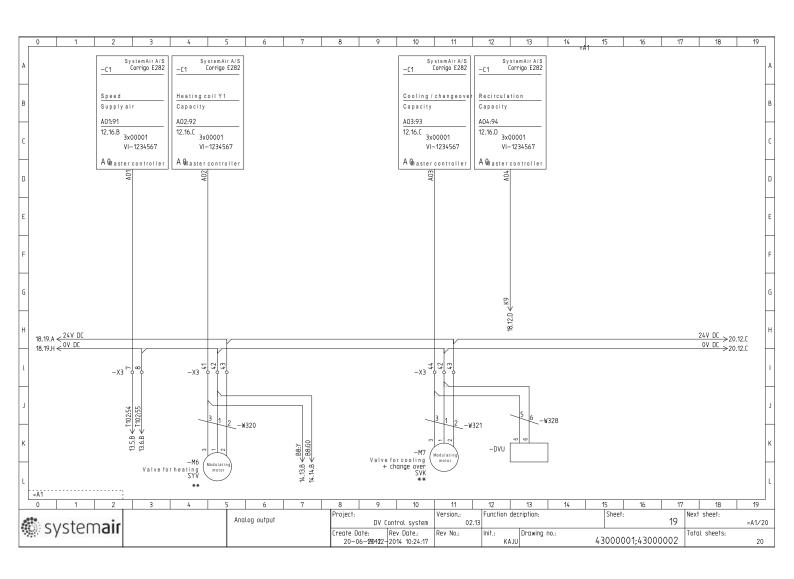


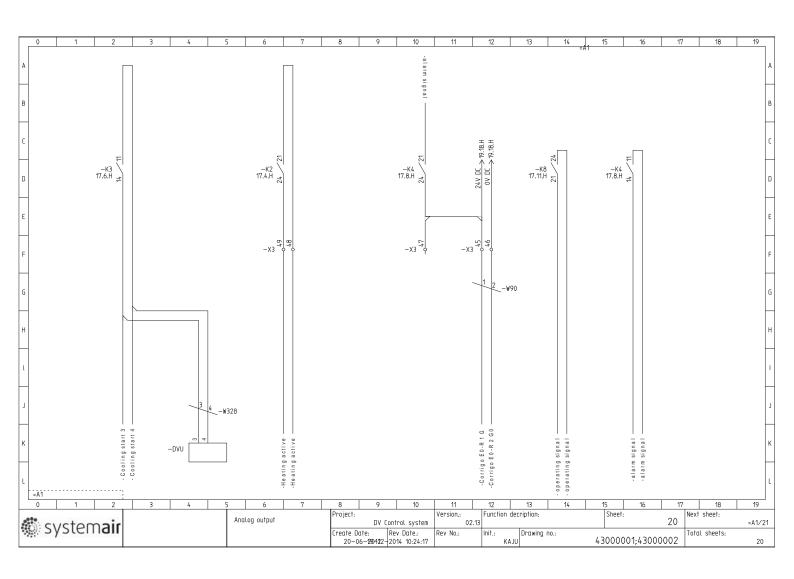


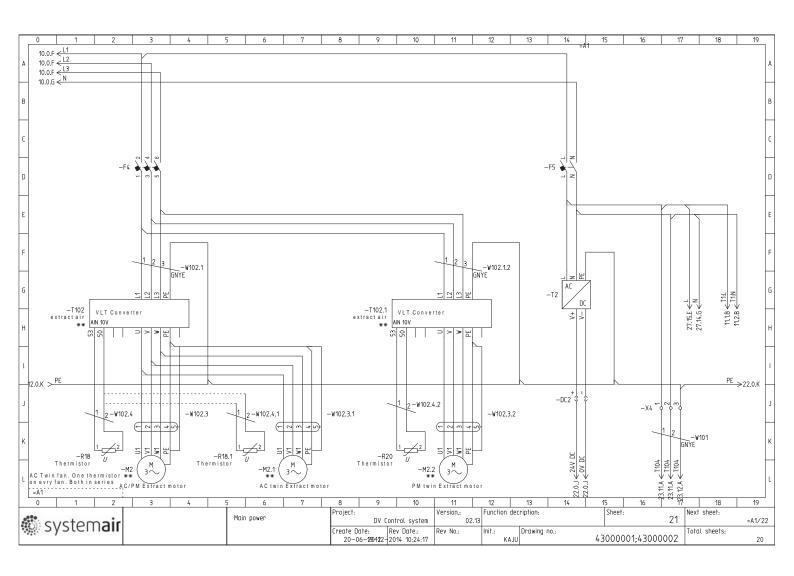


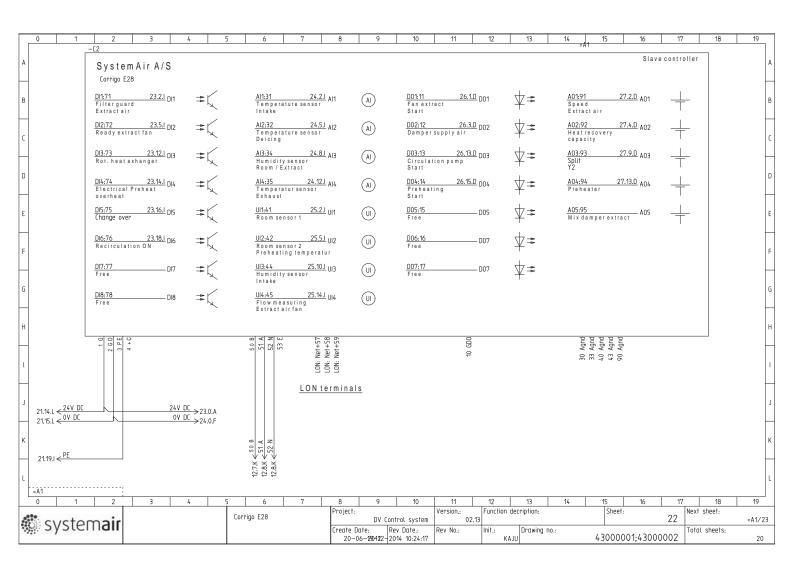


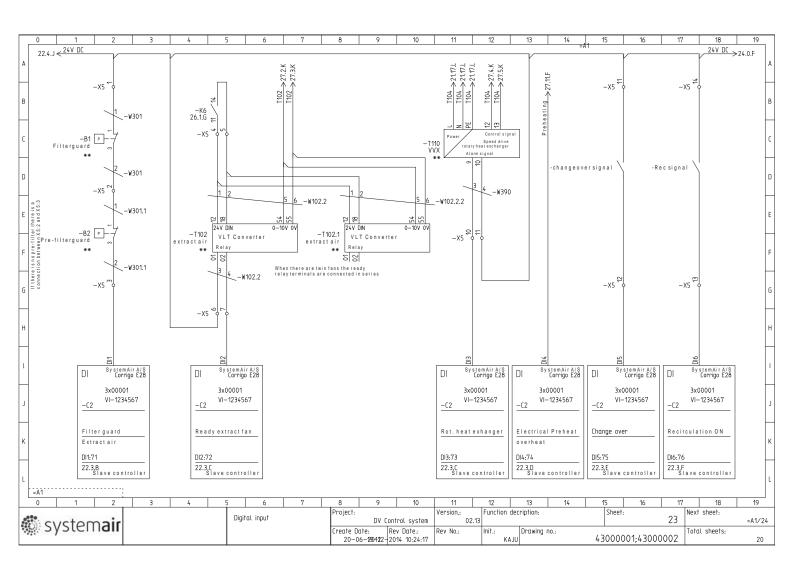


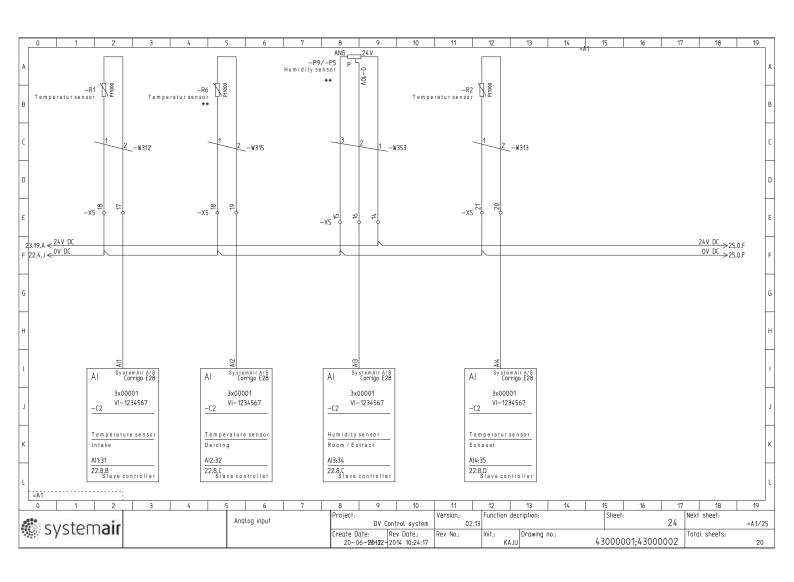


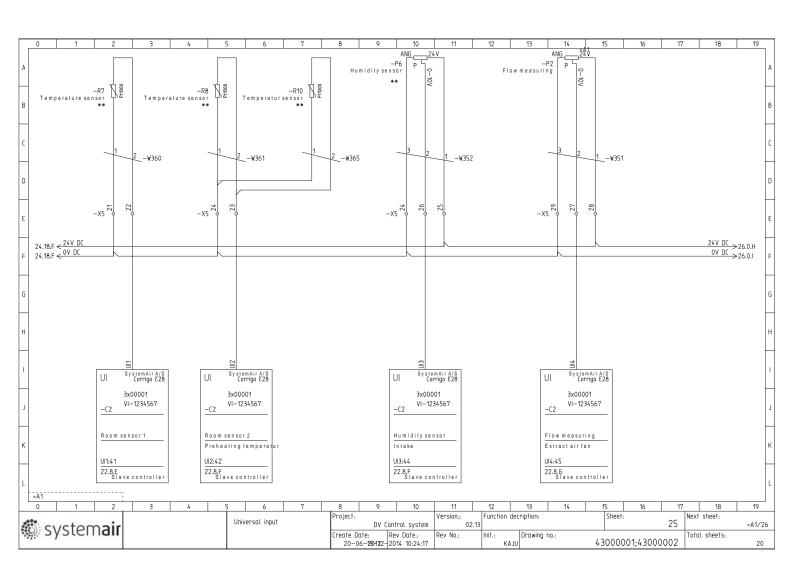


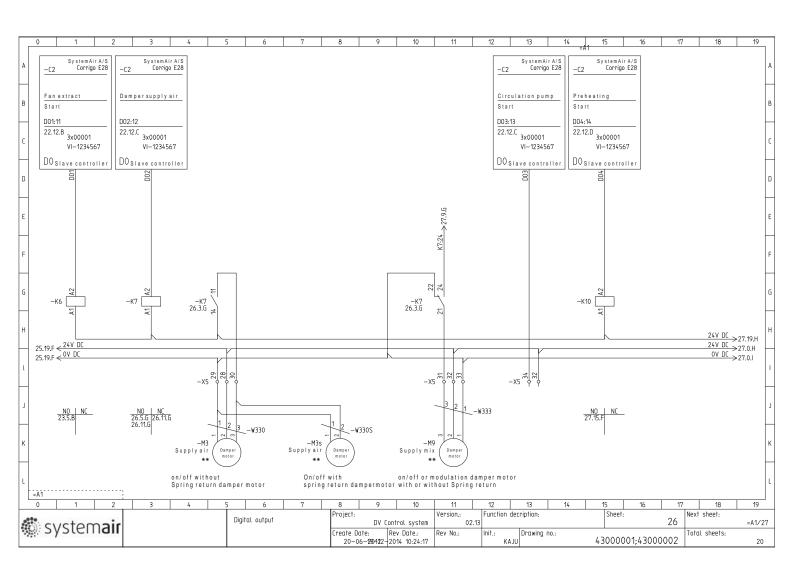


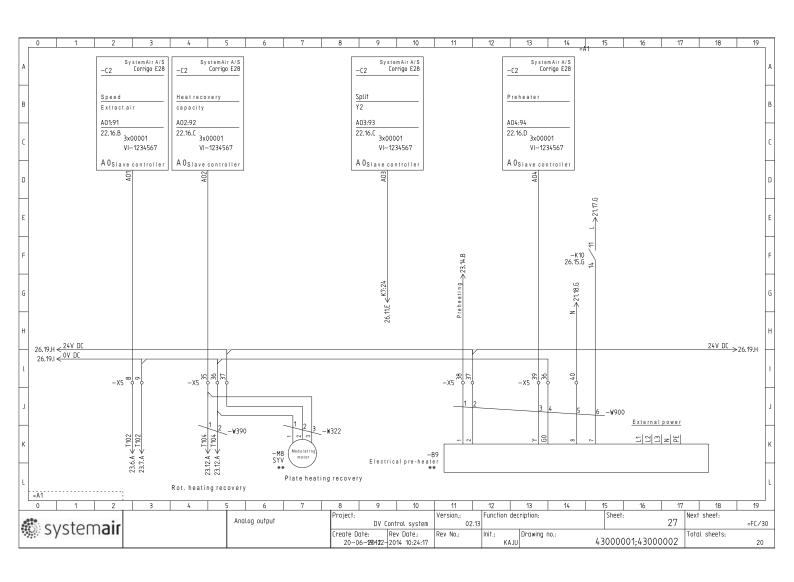


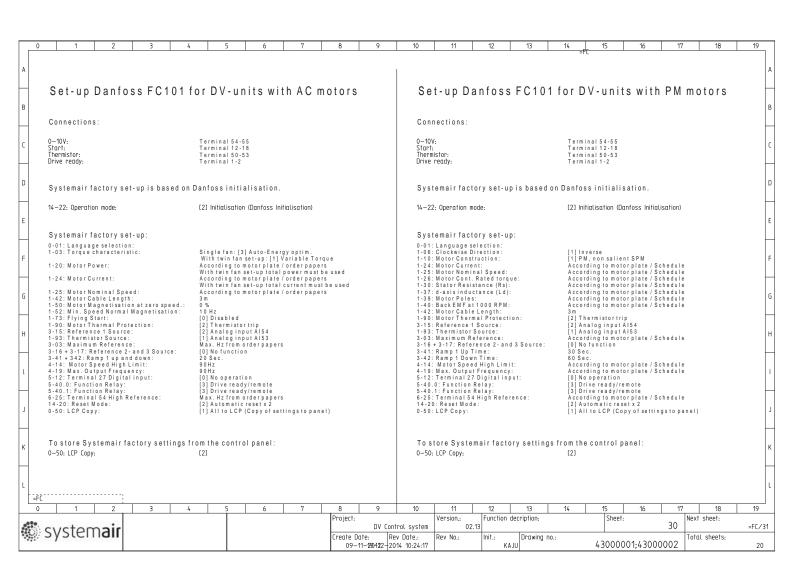




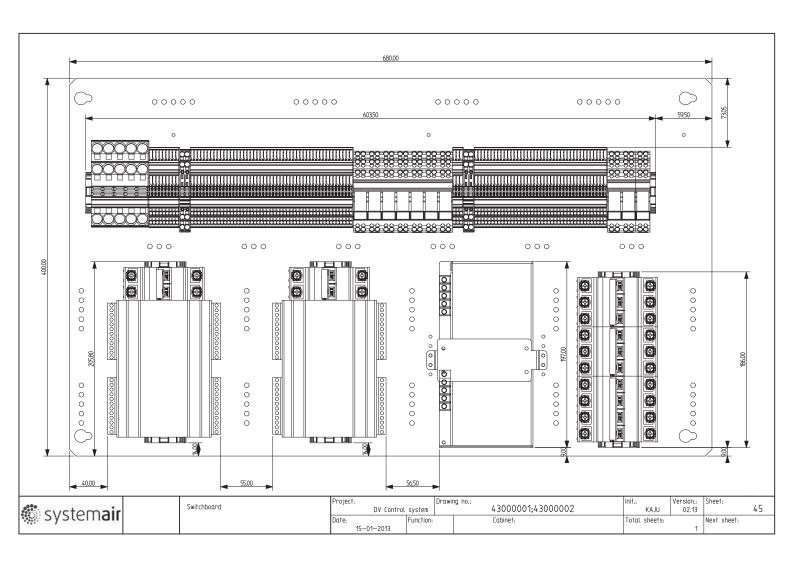








Parameter:	124	125	126	130	137	139	140	341	342	303	625	414	419
	Amp	Motor	Nm										
Motor Type	Name	RPM	Name	Ohm	mH		Bemf @	Ramp	Ramp				
Number	plate	rated	plate	[Rf-f]	[Lf-f]	Poles	1000	up	Down	Max	k Hz	Max m	notor Hz
HPS 71 3800 18	1,8	3800	2	7,20	0,64	6	255	30	30	215	215	219	219
HPS 71 3700 28	2,8	3700	3,6	3,16	0,75	6	291	30	30	191	191	204	204
HPS 71 3300 18	1,8	3300	2,6	11,50	0,81	6	280	30	30	170	170	182	182
HPS 71 3200 30	3	3200	4,2	3,70	0,80	6	268	30	30	161	161	176	176
HPS 71 2900 21	2,1	2900	3,3	9,00	0,91	6	276	30	30	143	143	160	160
HPS 71 2800 40	4	2800	6,1	3,35	0,91	6	267	30	30	144	144	154	154
HPS 71 2500 29	2,9	2500	5	6,00	1,00	6	262	30	30	129	129	138	138
HPS 71 2350 38	3,8	2350	7,3	4,60	1,10	6	271	30	30	120	120	129	129
HPS 90 2650 64	6,4	2650	9,6	2,50	0,83	8	230	30	30	182	182	194	194
HPS 90 2350 76	7,6	2350	13	1,60	0,98	8	241	30	30	159	159	172	172
HPS 90 2100 63	6,3	2100	10,5	3,00	0,96	8	212	30	30	142	142	154	154
HPS 90 2050 100	10	2050	19	1,40	1,10	8	236	30	30	140	140	150	150
HPS 90 1850 84	8,4	1850	16	2,10	1,05	8	203	30	30	127	127	136	136
HPS 90 1900 136	13,6	1900	26	1,15	1,05	8	209	30	30	127	127	139	139
HPS 90 1700 106	11	1700	22	1,15	1,15	8	199	30	30	116	116	125	125
HPS 112 1550 108	10,9	1550	32	1,50	1,70	6	276	30	30	80	80	85	85
HPS 112 1700 145	14,5	1700	39	0,93	1,55	6	276	30	30	88	88	94	94
HPS 112 1350 135	13,5	1350	44	0,98	1,88	6	266	30	30	69	69	74	74
HPS 112 1500 187	18,7	1500	54	0,59	1,67	6	262	30	30	76	76	83	83
HPS 112 1000 140	14	1000	51	0,95	2,10	6	242	30	30	54	54	55	55
HPS 132 1250 199	19,9	1250	69	0,51	2,00	6	262	30	30	65	65	69	69
HPS 132 1000 202	20,2	1000	77	0,63	2,20	6	230	30	30	51	51	65	65
HPS 132 1150 300	30	1150	104	0,47	2,20	6	265	30	30	58	58	65	65
HPS 132 930 273	27,3	930	118	0,56	2,50	6	243	30	30	46	46	65	65
1 2	3	4	5 6		7	8 9) 10	11	12	13 14	15	16 17	18
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		2	Document list						08-10-2014
		3	Document list						08-10-2014
		4	Document list						08-10-2014
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		2	Project cover sheet	General Descr	ription Symbols				08-10-2014 12:56:09
		3	Project cover sheet	General Descr	ription Symbols				08-10-2014 12:56:09
		4	Project cover sheet	General Descr	ription Wires				08-10-2014 12:56:09
		5	Project cover sheet	General Descr	ription				08-10-2014 12:56:09
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		4	Terminal list	=A1-X3	08-10-2014 13:00:36
		5	Terminal list	=A1-X4	08-10-2014 13:00:36
		6	Terminal list	=A1-XS	08-10-2014 13:00:36
		7	Terminal list	=A1-X5	08-10-2014 13:00:36
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		42	Cable-Core list		08-10-2014 13:00:38
		43	Cable-Core list		08-10-2014 13:00:38
		44	Cable—Core list		08-10-2014 13:00:38
		45	Cable-Core list		08-10-2014 13:00:38
		46	Cable-Core list		08-10-2014 13:00:38
		47	Cable—Core list		08-10-2014 13:00:38
		48	Cable-Core list		08-10-2014 13:00:38
		49	Cable-Core list		08-10-2014 13:00:38
		50	Cable-Core list		08-10-2014 13:00:38
		51	Cable-Core list		08-10-2014 13:00:38
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		2	PLC I/O list		08-10-2014 13:00:39
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=A1		64	Terminal Matrix	-X4	08-10-2014 13:00:39
=A1		65	Terminal Matrix	-XS	08-10-2014 13:00:39
=A1		66	Terminal Matrix	-XS	08-10-2014 13:00:39
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		71	Cable plan		08-10-2014 13:00:49
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A1		101	Terminal Plan	-X5				08-10-2014 13:01:14
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			+					
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=A1-F4:4	L2	=A1— Supply L2		1492-J16				10	3.1
=A1-F1:6	L3	=A1— Supply L3		1492-J16				10	3.1
=A1-F2:N	N	=A1— Supply N		1492-J16				10	3.1
=A1PE	PE	=A1— Supply PE		1492-JG16				10	4.1
									+
					-				_
									1
									+
									+
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Systeman			Date: 08—10-	-2014 Rev.:		Init.: Drawing no.:	43000001;43000002	Total sheets:	7

			List of T	erminals	: -X	2			
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=A1-X4:2	2	=A1-T1:N		1492-K2	N			11	2.D
=A1-K2:14	3	=A1-M12:U		1492-K2				11	5.1
=A1-X2:2	4	=A1-M12:N		1492-K2	N			11	5.1
=A1-F3:L	5	=A1-S1		1492-K2				11	8.1
=A1-S1	6	=A1-X2:7		1492-K2				11	9.1
=A1-X2:6	7	=A1-E1.1:L1		1492-K2				11	11.1
=A1-X2:8	8	=A1-E1.1:N		1492-K2				11	11.1
=A1-X2:7	9	=A1-E2.1:N		1492-K2				11	16.1
est out on the	'	=A1-X2	Project:	DV Con	trol system	Function decription:	Sheet: 2	Next sheet:	3
🔅 system air			Date: 08—10—	Rev.:		Init.: Drawing no.:	43000001;43000002	Total sheets:	7

			Listof	Terminal	s: -X	(3			
Connection 1	Terminal	Connection 2		Туре	Commen	t		Sheet	Cell
=A1-B3:3	1	=A1-C1:DI1		1492-K2				13	2.E
=A1-C1:1 G	2	=A1-B3:1		1492-K2				13	2.A
=A1-K1:11	3	=A1-T101:12		1492-K2				13	4.D
=A1-K5:21	4	=A1-T101.1:18		1492-K2				13	5.D
=A1-X3:10	5	=A1-T101:01		1492-K2				13	4.H
=A1-C1:DI2	6	=A1-T101:02		1492-K2				13	5.H
=A1-C1:A01	7	=A1-T101:54		1492-K2				19	2.1
=A1-K5:A2	8	=A1-T101:55		1492-K2				19	3.1
=A1-DVU:8	9	=A1-C1:DI3		1492-K2				13	11.H
=A1-X3:13	10	=A1-S2		1492-K2				13	15.A
=A1-C1:DI5	11	=A1-S2		1492-K2				13	15.F
=A1-C1:DI6	12	=A1-S10		1492-K2				13	17.F
=A1-X3:13	13	=A1-B4		1492-K2				14	2.A
=A1-B5	14	=A1-B4		1492-K2				14	2.D
=A1-C1:DI7	15	=A1-B6:10		1492-K2				14	2.H
=A1-C1:2 G0	16	=A1-B6:1		1492-K2				14	8.B
=A1-X3:17	17	-B8:1		1492-K2				14	12.A
=A1-C1:DI8	18	-B8:2		1492-K2				14	12.H
=A1-C1:Al1	19	=A1-R3		1492-K2				15	3.F
=A1-X3:16	20	=A1-R3		1492-K2				15	3.F
=A1-C1:AI2	21	=A1-R4		1492-K2				15	7.F
=A1-C1:AI3	22	=A1-R9		1492-K2				15	11.F
=A1-X3:23	23	=A1-R9		1492-K2				15	11.F
=A1-C1:AI4	24	=A1-R5		1492-K2				15	15.F
=A1-C1:UI1	25	=A1-P4:0-10V		1492-K2				16	2.F
=A1-X3:23	26	=A1-P4:ANG		1492-K2				16	2.F
=A1-X3:17	27	=A1-P4:24V		1492-K2				16	3.F
=A1-C1:UI2	28	=A1-P1:0-10V		1492-K2				16	6.F
=A1-C1:UI3	29	=A1-P7/-P8:0-10V		1492-K2				16	11.F
=A1-X3:26	30	=A1-P7/-P8:ANG		1492-K2				16	10.F
🔅 system air		=A1-X3	Project: Date:	DV C Rev.: 0-2014	ontrol system	Function decription: Init.: Drawing no.: KAJU	Sheet: 3 43000001;43000002	Next sheet: Total sheets:	7

			List of T	erminals	: -X	(3				
Connection 1	Terminal	Connection 2		Туре	Commen	t			Sheet	Cell
=A1-X3:31	31	=A1-P7/-P8:24V		1492-K2					16	11.F
=A1-C1:UI4	32	=A1-P3:0-10V		1492-K2					16	15.F
=A1-K8:11	33	=A1-M4s:2		5					18	2.1
=A1-K8:14	34	=A1-M4:2		1492-K2					18	2.1
=A1-X3:35	35	=A1-M4:1		1492-K2					18	1.1
=A1-X3:33	36	=A1-M10:3		5					18	7.1
=A1-K9:11	37	=A1-M11:3		1492-K2					18	12.1
=A1-X3:35	38	=A1-M11:1		1492-K2					18	12.1
=A1-K9:14	39	=A1-M11:2		1492-K2					18	12.1
=A1-K5:A1	40	=A1-B8:4		1492-K2					18	17.G
=A1-C1:A02	41	=A1-M6:3		1492-K2					19	4.1
=A1-X3:8	42	-B8:G0		1492-K2					19	5.1
=A1-X3:39	43	=A1-M6:2		1492-K2					19	5.1
=A1-C1:A03	44	=A1-M7:3		1492-K2					19	11.1
=A1-X3:43	45	=A1-Corrigo E0-R 1 G		1492-K2					20	12.F
=A1-X3:42	46	=A1-Corrigo E0-R 2 G0		1492-K2					20	12.F
=A1-X3:45	47			1492-K2					20	10.F
=A1-K2:21	48	=A1—Heating active		1492-K2					20	7.F
=A1-K2:24	49	=A1—Heating active		1492-K2	Extract				20	6.F
=A1-B8:1	50	=A1-B7:4		1492-K2					18	17.D
ö system air		=A1-X3	Project:	DV Con	itrol system	Function decr	ription:	Sheet:	4 Next sheet:	5
3ysteman			Date: 08-10-	2014 Rev.:		Init.: KAJU	Drawing no.:	43000001;430000	02 Total sheets	7

			Listofl	erminal	s: -X	(4			
Connection 1	Terminal	Connection 2		Туре	Commen	t		Sheet	Cell
=A1-X2:1	1	=A1-T110:L		1492-K2				21	17.J
=A1-X2:2	2	=A1-T110:N		1492-K2				21	17. J
=A1PE	3	=A1-T110:PE		1492-K2				21	17.J
<u> </u>									
2000		=A1-X4	Project:	חע ר	ontrol system	Function decription:	Sheet: 5	Next sheet:	6
🔅 system air			Date: 08—10-	Rev.:	5 oc 3,51EIII	Init.: Drawing no.:	43000001;43000002	Total shoots	7

			Listof	Terminals	: -X	5			
Connection 1	Terminal	Connection 2		Туре	Commen	t		Sheet	Cell
=A1-C2:1 G	1	=A1-B1:1		1492-K2				23	2.A
=A1-B1:3	2	=A1-B2:1		1492-K2				23	2.D
=A1-B2:3	3	=A1-C2:DI1		1492-K2				23	2.G
=A1-K6:11	4	=A1-T102.1:12		1492-K2				23	5.0
=A1-K6:14	5	=A1-T102:18		1492-K2				23	5.0
=A1-X5:11	6	=A1-T102:01		1492-K2				23	5.H
=A1-C2:DI2	7	=A1-T102:02		1492-K2				23	5.H
=A1-C2:A01	8	=A1-T102.1:54		1492-K2				27	2.1
=A1-X5:36	9	=A1-T102.1:55		1492-K2				27	3.1
=A1-C2:DI3	10	=A1-T110:9		1492-K2				23	12.F
=A1-X5:11	11	=A1-T110:10		1492-K2				23	12.F
=A1—changeover signal	12	=A1-C2:DI5		1492-K2				23	16.6
=A1—Rec signal	13	=A1-C2:DI6		1492-K2				23	18.G
=A1-X5:14	14	=A1-P9/-P5:24V		1492-K2				24	9.E
=A1-X5:21	15	=A1-P9/-P5:ANG		1492-K2				24	8.E
=A1-C2:AI3	16	=A1-P9/-P5:0-10V		1492-K2				24	8.E
=A1-C2:AI1	17	=A1-R1		1492-K2				24	2.E
=A1-X5:18	18	=A1-R1		1492-K2				24	2.E
=A1-C2:AI2	19	=A1-R6		1492-K2				24	5.E
=A1-C2:AI4	20	=A1-R2		1492-K2				24	12.E
=A1-X5:15	21	=A1-R2		1492-K2				24	12.E
=A1-C2:UI1	22	=A1-R7		1492-K2				25	2.E
=A1-C2:UI2	23	=A1-R8		1492-K2				25	5.E
=A1-X5:24	24	=A1-R8		1492-K2				25	5.E
=A1-X5:14	25	=A1-P6:24V		1492-K2				25	11.E
=A1-C2:UI3	26	=A1-P6:0-10V		1492-K2				25	10.E
=A1-C2:UI4	27	=A1-P2:0-10V		1492-K2				25	14.E
=A1-X5:25	28	=A1-P2:24V		1492-K2				25	15.E
=A1-X5:24	29	=A1-P2:ANG		1492-K2				25	14.E
=A1-K7:11	30	=A1-M3s:2		1492-K2				26	5.1
🔅 system air	,	=A1-X5	Project: Date: 08-10	Rev.:	itrol system	Function decription: Init.: Drawing no.: KAJU	Sheet: 6 43000001;43000002	Next sheet: Total sheets:	7

			Listof	Terminal	s: -X	(5			
Connection 1	Terminal	Connection 2		Туре	Commen	t		Sheet	Cell
=A1-K7:21	31	=A1-M9:3		1492-K2				26	11.1
=A1-X5:32	32			1492-K2				26	13.1
=A1-K7:22	33	=A1-M9:1		1492-K2				26	11.1
=A1-C2:D03	34			1492-K2				26	13.1
=A1-C2:A02	35	=A1-T110:12		1492-K2				27	4.1
=A1-X5:36	36	=A1-T110:13		1492-K2				27	5.1
=A1-X5:37	37	=A1-M8:2		1492-K2				27	5.1
=A1-C2:DI4	38	-B9:1		1492-K2				27	11.1
=A1-C2:A04	39	-B9:Y		1492-K2				27	13.1
=A1-X4:2	40	-B9:8		1492-K2				27	14.1
									+
* system air		=A1-X5	Project:	DV	Control system	Function decription:	Sheet: 7	Next sheet:	
			Date: 08-10			Init.: Drawing no.:	43000001;43000002	Total sheets:	7

-W90 1 =A1-X3:45 =A1-Corrigo E0-R 1 G Remote panel 20 1 -W90 2 =A1-X3:46 =A1-Corrigo E0-R 2 G0 Remote panel 20 1 -W90 3 =A1-C1:50 B =A1-Corrigo E0-R Remote panel 12 -W90 4 =A1-C1:51 A =A1-Corrigo E0-R Remote panel 12 -W90 5 =A1-C1:52 N =A1-Corrigo E0-R Remote panel 12 -W100 1 =A1-X2:3 =A1-M12:U Mixing pump 11 -W100 2 =A1-X2:4 =A1-M12:U Mixing pump 11 -W100 3 =A1PE =A1-M12:PE Mixing pump 11 -W101 1 =A1-X4:1 =A1-T110:L VVX Power 21 1 -W101 2 =A1-X4:2 =A1-T110:L VVX Power 21 1 -W101 3 =A1-X4:3 =A1-T110:PE VVX Power 21 1 -W101 1 =A1-F1:1 =A1-T10:LL VLT Supplyair	Cablename (-) Wire Co		Connection 1	Connection 2	Description	Sheet	Path
W90 3	\ ,	1					
-W90	- W 9 0	2	= A 1 - X 3 : 4 6	=A1-Corrigo E0-R 2 G0	Remote panel	20	12.G
-W90 5 = A1-C1:52 N = A1-Corrigo E0-R Remote panel 12 -W100 1 = A1-X2:3 = A1-M12:U Mixing pump 11 -W100 2 = A1-X2:4 = A1-M12:PE Mixing pump 11 -W100 3 = A1PE = A1-M12:PE Mixing pump 11 -W101 1 = A1-X4:1 = A1-T110:L VVX Power 21 1 -W101 2 = A1-X4:2 = A1-T110:N VVX Power 21 1 -W101 3 = A1-X4:3 = A1-T110:PE VVX Power 21 1 -W101 1 = A1-F1:1 = A1-T10:L1 VLT Supplyair 10 -W101.1 2 = A1-F1:3 = A1-T10:L2 VLT Supplyair 10 -W101.1 3 = A1-F1:5 = A1-T10:PE VLT Supplyair 10 -W101.1 4 = A1PE = A1-T10:PE VLT Supplyair 10 -W101.1 2 = A1-F1:3 = A1-T10:L3 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T10:L1 VLT Supplyair 10 -W101.1 2 = A1-F1:3 = A1-T10:L2 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T10:L1 VLT Supplyair 10 -W101.1 2 = A1-F1:3 = A1-T10:L1 VLT Supplyair 10 -W101.1 2 = A1-F1:3 = A1-T10:L1 VLT Supplyair 10 -W101.1 2 = A1-F1:3 = A1-T10:L1 VLT Supplyair 10 -W101.1 2 = A1-F1:3 = A1-T10:L1:L1 VLT Supplyair 10 -W101.1 2 = A1-F1:3 = A1-T10:L1:L2 VLT Supplyair 10 -W101.1 2 = A1-F1:3 = A1-T10:L1:L2 VLT Supplyair 10 -W101.1 3 = A1-F1:3 = A1-T10:L1:L2 VLT Supplyair 10 -W101.1 2 4 = A1PE = A1-T10:L1:L2 VLT Supplyair 10 -W101.1 3 = A1-F1:5 = A1-T10:L1:L2 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T10:L1:L2 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T10:L1:L2 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T10:L1:L2 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T10:L1:L2 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T10:L1:L2 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T10:L1:L2 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T10:L1:L2 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T10:L1:L2 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T10:L1:L2 VLT Supplyair 10	- W 9 0	3	= A 1 - C 1:50 B	= A 1 - Corrigo E 0 - R	Remote panel	12	6 . J
-W100 1 = A1-X2:3 = A1-M12:U Mixing pump 11 -W100 2 = A1-X2:4 = A1-M12:N Mixing pump 11 -W100 3 = A1PE = A1-M12:PE Mixing pump 11 -W101 1 = A1-X4:1 = A1-T110:L VVX Power 21 1 -W101 2 = A1-X4:2 = A1-T110:N VVX Power 21 1 -W101 3 = A1-X4:3 = A1-T110:PE VVX Power 21 1 -W101 1 = A1-F1:1 = A1-T10:L1 VLT Supplyair 10 -W101.1 1 = A1-F1:3 = A1-T101:L2 VLT Supplyair 10 -W101.1 2 = A1-F1:5 = A1-T101:L3 VLT Supplyair 10 -W101.1 3 = A1-F1:5 = A1-T101:L3 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T101:L1 VLT Supplyair 10 -W101.1.2 1 = A1-F1:1 = A1-T101:L1 VLT Supplyair 10 -W101.1.2 1 = A1-F1:1 = A1-T101:L1 VLT Supplyair 10 -W101.1.2 1 = A1-F1:1 = A1-T101:L1 VLT Supplyair 10 -W101.1.2 2 = A1-F1:3 = A1-T101:L1 VLT Supplyair 10 1 -W101.1.2 3 = A1-F1:5 = A1-T101:L1 VLT Supplyair 10 1 -W101.1.2 4 = A1-F1:5 = A1-T101:L1:L3 VLT Supplyair 10 1	- W 9 0	4	= A 1 - C 1:51 A	= A 1 - Corrigo E 0 - R	Remote panel	12	6 . J
-W100 2 = A1-X2:4 = A1-M12:N Mixing pump 11 -W100 3 = A1PE = A1-M12:PE Mixing pump 11 -W101 1 = A1-X4:1 = A1-T110:L VVX Power 21 1 -W101 2 = A1-X4:2 = A1-T110:N VVX Power 21 1 -W101 3 = A1-X4:3 = A1-T110:PE VVX Power 21 1 -W101.1 1 = A1-F1:1 = A1-F1:1 VLT Supplyair 10 -W101.1 2 = A1-F1:3 = A1-T101:L2 VLT Supplyair 10 -W101.1 3 = A1-F1:5 = A1-T101:L3 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T101:PE VLT Supplyair 10 -W101.1.2 1 = A1-F1:1 = A1-F1:1 VLT Supplyair 10 -W101.1.2 1 = A1-F1:1 = A1-T101:L1 VLT Supplyair 10 -W101.1.2 1 = A1-F1:1 = A1-T101:L1 VLT Supplyair 10 -W101.1.2 1 = A1-F1:1 = A1-T101:L1 VLT Supplyair 10 1 -W101.1.2 2 = A1-F1:3 = A1-T101:L2 VLT Supplyair 10 1 -W101.1.2 4 = A1PE = A1-T101:L1 VLT Supplyair 10 1	- W 9 0	5	= A 1 - C 1:52 N	= A 1 - Corrigo E 0 - R	Remote panel	12	6 . J
-W100 3 = A1PE = A1-M12:PE Mixing pump 11 -W101 1 = A1-X4:1 = A1-T110:L VVX Power 21 1 -W101 2 = A1-X4:2 = A1-T110:N VVX Power 21 1 -W101 3 = A1-X4:3 = A1-T110:PE VVX Power 21 1 -W101.1 1 = A1-F1:1 = A1-T10:L1 VLT Supplyair 10 -W101.1 2 = A1-F1:3 = A1-T10:L2 VLT Supplyair 10 -W101.1 3 = A1-F1:5 = A1-T10:L3 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T101:PE VLT Supplyair 10 -W101.1.2 1 = A1-F1:1 = A1-T101:PE VLT Supplyair 10 -W101.1.2 1 = A1-F1:1 = A1-T101:L1 VLT Supplyair 10 -W101.1.2 2 = A1-F1:3 = A1-T101:L1 VLT Supplyair 10 1 -W101.1.2 3 = A1-F1:3 = A1-T101.1:L2 VLT Supplyair 10 1 -W101.1.2 4 = A1PE = A1-T101.1:L2 VLT Supplyair 10 1	- W 1 0 0	1	= A 1 - X 2 : 3	= A 1 - M 1 2 : U	Mixing pump	11	5 . J
-W101 1 = A1-X4:1 = A1-T110:L VVX Power 21 1 -W101 2 = A1-X4:2 = A1-T110:N VVX Power 21 1 -W101 3 = A1-X4:3 = A1-T110:PE VVX Power 21 1 -W101.1 1 = A1-F1:1 = A1-T101:L1 VLT Supplyair 10 -W101.1 2 = A1-F1:3 = A1-T101:L2 VLT Supplyair 10 -W101.1 3 = A1-F1:5 = A1-T101:L3 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T101:PE VLT Supplyair 10 -W101.1.2 1 = A1-F1:1 = A1-T101:L1 VLT Supplyair 10 -W101.1.2 2 = A1-F1:3 = A1-T101:L1 VLT Supplyair 10 -W101.1.2 3 = A1-F1:3 = A1-T101:L2 VLT Supplyair 10 1 -W101.1.2 4 = A1-F1:3 = A1-T101:L1 VLT Supplyair 10 1 -W101.1.2 4 = A1-F1:5 = A1-T101:L1 VLT Supplyair 10 1	- W 1 0 0	2	= A 1 - X 2 : 4	= A 1 - M 1 2 : N	Mixing pump	11	5 . J
-W101 2 = A1-X4:2 = A1-T110:N VVX Power 21 1 -W101 3 = A1-X4:3 = A1-T110:PE VVX Power 21 1 -W101.1 1 = A1-F1:1 = A1-T101:L1 VLT Supplyair 10 -W101.1 2 = A1-F1:3 = A1-T101:L2 VLT Supplyair 10 -W101.1 3 = A1-F1:5 = A1-T101:L3 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T101:PE VLT Supplyair 10 -W101.1.2 1 = A1-F1:1 = A1-T101.1:L1 VLT Supplyair 10 -W101.1.2 2 = A1-F1:3 = A1-T101.1:L1 VLT Supplyair 10 1 -W101.1.2 2 = A1-F1:3 = A1-T101.1:L2 VLT Supplyair 10 1 -W101.1.2 3 = A1-F1:5 = A1-T101.1:L3 VLT Supplyair 10 1 -W101.1.2 4 = A1PE = A1-T101.1:PE VLT Supplyair 10 1	- W 1 0 0	3	= A 1 P E	= A 1 - M 1 2 : P E	Mixing pump	11	5 . J
-W101 3 = A1-X4:3 = A1-T110:PE VVX Power 21 1 -W101.1 1 = A1-F1:1 = A1-T101:L1 VLT Supplyair 10 -W101.1 2 = A1-F1:3 = A1-T101:L2 VLT Supplyair 10 -W101.1 3 = A1-F1:5 = A1-T101:L3 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T101:PE VLT Supplyair 10 -W101.1.2 1 = A1-F1:1 = A1-T101.1:L1 VLT Supplyair 10 1 -W101.1.2 2 = A1-F1:3 = A1-T101.1:L1 VLT Supplyair 10 1 -W101.1.2 3 = A1-F1:5 = A1-T101.1:L3 VLT Supplyair 10 1 -W101.1.2 4 = A1PE = A1-T101.1:L3 VLT Supplyair 10 1	- W 1 0 1	1	= A 1 - X 4 : 1	= A1-T110:L	VVX Power	21	17.K
-W101.1 1 = A1-F1:1 = A1-T101:L1 VLT Supplyair 10 -W101.1 2 = A1-F1:3 = A1-T101:L2 VLT Supplyair 10 -W101.1 3 = A1-F1:5 = A1-T101:L3 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T101:PE VLT Supplyair 10 -W101.1.2 1 = A1-F1:1 = A1-T101.1:L1 VLT Supplyair 10 1 -W101.1.2 2 = A1-F1:3 = A1-T101.1:L2 VLT Supplyair 10 1 -W101.1.2 3 = A1-F1:5 = A1-T101.1:L3 VLT Supplyair 10 1 -W101.1.2 4 = A1PE = A1-T101.1:PE VLT Supplyair 10 1	- W 1 0 1	2	= A 1 - X 4 : 2	= A 1 - T 1 1 0 : N	VVX Power	21	17.K
-W101.1 2 = A1-F1:3 = A1-T101:L2 VLT Supplyair 10 -W101.1 3 = A1-F1:5 = A1-T101:L3 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T101:PE VLT Supplyair 10 -W101.1.2 1 = A1-F1:1 = A1-T101.1:L1 VLT Supplyair 10 1 -W101.1.2 2 = A1-F1:3 = A1-T101.1:L2 VLT Supplyair 10 1 -W101.1.2 3 = A1-F1:5 = A1-T101.1:L3 VLT Supplyair 10 1 -W101.1.2 4 = A1PE = A1-T101.1:PE VLT Supplyair 10 1	- W 1 0 1	3	= A 1 - X 4 : 3	= A1-T110:PE	VVX Power	21	17.K
-W101.1 3 = A1-F1:5 = A1-T101:L3 VLT Supplyair 10 -W101.1 4 = A1PE = A1-T101:PE VLT Supplyair 10 -W101.1.2 1 = A1-F1:1 = A1-T101.1:L1 VLT Supplyair 10 1 -W101.1.2 2 = A1-F1:3 = A1-T101.1:L2 VLT Supplyair 10 1 -W101.1.2 3 = A1-F1:5 = A1-T101.1:L3 VLT Supplyair 10 1 -W101.1.2 4 = A1PE = A1-T101.1:PE VLT Supplyair 10 1	- W 1 0 1 . 1	1	= A 1 - F 1 : 1	= A1-T101:L1	VLT Supplyair	10	7.F
-W101.1 4 = A1PE = A1-T101:PE VLT Supplyair 10 -W101.1.2 1 = A1-F1:1 = A1-T101.1:L1 VLT Supplyair 10 1 -W101.1.2 2 = A1-F1:3 = A1-T101.1:L2 VLT Supplyair 10 1 -W101.1.2 3 = A1-F1:5 = A1-T101.1:L3 VLT Supplyair 10 1 -W101.1.2 4 = A1PE = A1-T101.1:PE VLT Supplyair 10 1	-W101.1	2	= A 1 - F 1 : 3	= A 1 - T 1 0 1 : L 2	VLT Supplyair	10	7.F
-W101.1.2 1 = A1-F1:1 = A1-T101.1:L1 VLT Supplyair 10 1 -W101.1.2 2 = A1-F1:3 = A1-T101.1:L2 VLT Supplyair 10 1 -W101.1.2 3 = A1-F1:5 = A1-T101.1:L3 VLT Supplyair 10 1 -W101.1.2 4 = A1PE = A1-T101.1:PE VLT Supplyair 10 1	-W101.1	3	= A 1 - F 1 : 5	= A1-T101:L3	VLT Supplyair	10	7.F
-W101.1.2 2 = A1-F1:3 = A1-T101.1:L2 VLT Supplyair 10 1 -W101.1.2 3 = A1-F1:5 = A1-T101.1:L3 VLT Supplyair 10 1 -W101.1.2 4 = A1PE = A1-T101.1:PE VLT Supplyair 10 1	-W101.1	4	= A 1 P E	= A 1 - T 1 0 1 : P E	VLT Supplyair	10	8.F
-W101.1.2 3 = A1-F1:5 = A1-T101.1:L3 VLT Supplyair 10 1 -W101.1.2 4 = A1PE = A1-T101.1:PE VLT Supplyair 10 1	-W101.1.2	1	= A 1 - F 1 : 1	= A 1 - T 1 0 1 . 1 : L 1	VLT Supplyair	10	14.F
-W101.1.2 4 = A1PE = A1-T101.1:PE VLT Supplyair 10 1	-W101.1.2	2	= A 1 - F 1 : 3	= A1-T101.1:L2	VLT Supplyair	10	14.F
	-W101.1.2	3	= A 1 - F 1 : 5	=A1-T101.1:L3	VLT Supplyair	10	14.F
-W101.2 1 = A1-X3:3 = A1-T101:12 VLT control supply 13	-W101.1.2	4	= A 1 P E	= A 1 - T 1 0 1 . 1 : P E	VLT Supplyair	10	15.F
	-W101.2	1	= A 1 - X 3 : 3	= A1-T101:12	VLT control supply	13	4 . E

			List of Cable Cores			
Cablename (-)	Wire	Connection 1	Connection 2	Description	Sheet	Path
- W 1 0 1 . 2	2	= A 1 - X 3 : 4	= A 1 - T 1 0 1 : 1 8	VLT control supply	13	5 . E
-W101.2	3	= A 1 - X 3 : 5	= A 1 - T 1 0 1 : 0 1	VLT control supply	13	4 . G
-W101.2	4	= A 1 - X 3 : 6	= A 1 - T 1 0 1 : 0 2	VLT control supply	13	5 . G
-W101.2	5	= A 1 - X 3 : 7	= A 1 - T 1 0 1 : 5 4	VLT control supply	13	5 . E
-W101.2	6	= A 1 - X 3 : 8	= A 1 - T 1 0 1 : 5 5	VLT control supply	13	6 . E
-W101.2.2	1	= A 1 - X 3 : 3	= A 1 - T 1 0 1 . 1 : 1 2	VLT control supply	13	7 . E
-W101.2.2	2	= A 1 - X 3 : 4	= A 1 - T 1 0 1 . 1 : 1 8	VLT control supply	13	7 . E
-W101.2.2	5	= A 1 - X 3 : 7	= A 1 - T 1 0 1 . 1 : 5 4	VLT control supply	13	8 . E
-W101.2.2	6	= A 1 - X 3 : 8	= A1-T101.1:55	VLT control supply	13	8 . E
-W101.3	1	= A 1 - T 1 0 1 : U	= A 1 - M 1 : U 1	motor supplyair	10	7 . J
-W101.3	2	= A 1 - T 1 0 1 : V	= A 1 - M 1 : V 1	motorsupplyair	10	7 . J
-W101.3	3	= A 1 - T 1 0 1 : W	= A 1 - M 1 : W 1	motor supplyair	10	7 . J
-W101.3	4	= A 1 - T 1 0 1 : P E	= A 1 - M 1 : P E	motor supplyair	10	8 . J
-W101.3	5	= A 1 - T 1 0 1 : P E	= A 1 - M 1 : P E	motor supplyair	10	8 . J
-W101.3.1	1	= A 1 - T 1 0 1 : U	= A 1 - M 1 . 1 : U 1	motor supplyair	10	10.J
-W101.3.1	2	= A 1 - T 1 0 1 : V	= A 1 - M 1 . 1 : V 1	motor supplyair	10	11.J
-W101.3.1	3	= A 1 - T 1 0 1 : W	= A 1 - M 1 . 1 : W 1	motor supplyair	10	11.J
-W101.3.1	4	= A 1 - T 1 0 1 : P E	= A 1 - M 1 . 1 : P E	motor supplyair	10	11.J
-W101.3.1	5	= A 1 - T 1 0 1 : P E	= A 1 - M 1 . 1 : P E	motor supplyair	10	11.J
-W101.3.2	1	= A 1 - T 1 0 1 . 1 : U	= A 1 - M 1 . 2 : U 1	motorsupplyair	10	14.J
system	air	<u> </u>	Project: DV Control system	nction decription: Sheet: 4	Next sheet:	42

			List of Cable Cores			
Cablename (-)	Wire	Connection 1	Connection 2	Description	Sheet	
-W101.3.2	2	= A 1 - T 1 0 1 . 1 : V	= A 1 - M 1 . 2 : V 1	motor supplyair	10	14.J
-W101.3.2	3	= A 1 - T 1 0 1 . 1 : W	= A 1 - M 1 . 2 : W 1	motor supply air	10	14.J
-W101.3.2	4	= A 1 - T 1 0 1 . 1 : P E	= A 1 - M 1 . 2 : P E	motor supply air	10	15.J
-W101.3.2	5	= A 1 - T 1 0 1 . 1 : P E	= A 1 - M 1 . 2 : P E	motor supply air	10	15.J
-W101.4	1	= A 1 - T 1 0 1 : 5 3	= A 1 - R 17:1	Supply thermistor	10	6 . J
-W101.4	2	= A 1 - T 1 0 1 : 5 0	= A 1 - R 17:2	Supply thermistor	10	6 . J
-W101.4.1	1		= A 1 - R 17.1:1	Supply thermistor	10	9 . J
-W101.4.1	2		= A 1 - R 17.1:2	Supply thermistor	10	9.J
-W101.4.2	1	= A 1 - T 1 0 1 . 1 : 5 3	= A 1 - R 19:1	Supply thermistor	10	13.J
-W101.4.2	2	= A 1 - T 1 0 1 . 1 : 5 0	= A 1 - R 19:2	Supply thermistor	10	13.J
-W102.1	1	= A 1 - F 4 : 1	= A 1 - T 1 0 2 : L 1	VLT extract power	21	3.F
-W102.1	2	= A 1 - F 4 : 3	= A 1 - T 1 0 2 : L 2	VLT extract power	21	3.F
-W102.1	3	= A 1 - F 4 : 5	= A 1 - T 1 0 2 : L 3	VLT extract power	21	3.F
-W102.1	4	= A 1 P E	= A 1 - T 1 0 2 : P E	VLT extract power	21	3.F
-W102.1.2	1	= A 1 - F 4 : 1	= A 1 - T 1 0 2 . 1 : L 1	VLT extract power	21	11.F
-W102.1.2	2	= A 1 - F 4 : 3	= A 1 - T 1 0 2 . 1 : L 2	VLT extract power	21	11.F
-W102.1.2	3	= A 1 - F 4 : 5	= A1-T102.1:L3	VLT extract power	21	11.F
-W102.1.2	4	= A 1 P E	= A 1 - T 1 0 2 . 1 : P E	VLT extract power	21	12.F
-W102.2	1	= A 1 - X 5 : 4	= A 1 - T 1 0 2 : 1 2	VLT control extract	23	5 . D
-W102.2	2	= A 1 - X 5 : 5	= A 1 - T 1 0 2 : 1 8	VLT control extract	23	5 . E
cyctom	air		Project: DV Control system	Function decription: Sheet:	Next sheet:	43
system	all			Init.: Drawing no.: 43000001;43000	Total sheets:	12

			List of Cable Cores			
Cablename (-)	Wire	Connection 1	Connection 2	Description	Sheet	Path
-W102.2	3	= A 1 - X 5 : 6	= A 1 - T 1 0 2 : 0 1	VLT control extract	23	5 . G
-W102.2	4	= A 1 - X 5 : 7	= A 1 - T 1 0 2 : 0 2	VLT control extract	23	5 . G
-W102.2	5	= A 1 - X 5 : 8	= A 1 - T 1 0 2 : 5 4	VLT control extract	23	6 . E
-W102.2	6	= A 1 - X 5 : 9	= A 1 - T 1 0 2 : 5 5	VLT control extract	23	7 . E
-W102.2.2	1	= A 1 - X 5 : 4	= A 1 - T 1 0 2 . 1 : 1 2	VLT control extract	23	8 . D
-W102.2.2	2	= A 1 - X 5 : 5	= A 1 - T 1 0 2 . 1 : 1 8	VLT control extract	23	8 . E
-W102.2.2	5	= A 1 - X 5 : 8	= A 1 - T 1 0 2 . 1 : 5 4	VLT control extract	23	10.E
-W102.2.2	6	= A 1 - X 5 : 9	= A1-T102.1:55	VLT control extract	23	10.E
-W102.3	1	= A 1 - T 1 0 2 : U	= A 1 - M 2 : U 1	motorcable power	21	3 . K
-W102.3	2	= A 1 - T 1 0 2 : V	= A 1 - M 2 : V 1	motorcable power	21	3 . K
-W102.3	3	= A 1 - T 1 0 2 : W	= A 1 - M 2 : W 1	motorcable power	21	3 . K
-W102.3	4	= A 1 - T 1 0 2 : P E	= A 1 - M 2 : P E	motorcable power	21	3 . K
-W102.3	5		= A 1 - M 2 : P E	motorcable power	21	4 . J
-W102.3.1	1	= A 1 - T 1 0 2 : U	= A 1 - M 2 . 1 : U 1	motorcable power	21	6 . K
-W102.3.1	2	= A 1 - T 1 0 2 : V	= A 1 - M 2 . 1 : V 1	motorcable power	21	7 . K
-W102.3.1	3	= A 1 - T 1 0 2 : W	= A 1 - M 2 . 1 : W 1	motorcable power	21	7 . K
-W102.3.1	4	= A 1 - T 1 0 2 : P E	= A 1 - M 2 . 1 : P E	motorcable power	21	7 . K
-W102.3.1	5	= A 1 - T 1 0 2 : P E	= A 1 - M 2 . 1 : P E	motorcable power	21	7 . J
-W102.3.2	1	= A 1 - T 1 0 2 . 1 : U	= A 1 - M 2 . 2 : U 1	motorcable power	21	11.K
-W102.3.2	2	= A 1 - T 1 0 2 . 1 : V	= A 1 - M 2 . 2 : V 1	motorcable power	21	11.K
e cyctom	air		Project: DV Control system	nction decription: Sheet: 4:	Next sheet:	44
system	all			t.: Drawing no.: 43000001;4300000	Total sheets:	12

Cablename (-)	Wire	Connection 1	Connection 2	Description	Sheet	Path
-W102.3.2	3	= A 1 - T 1 0 2 . 1 : W	= A 1 - M 2 . 2 : W 1	motorcable power	21	11.K
-W102.3.2	4	= A 1 - T 1 0 2 . 1 : P E	= A 1 - M 2 . 2 : P E	motorcable power	21	12.K
-W102.3.2	5	= A 1 - T 1 0 2 . 1 : P E	= A 1 - M 2 . 2 : P E	motorcable power	21	12.J
-W102.4	1	= A 1 - T 1 0 2 : 5 3	= A 1 - R 1 8 : 1	Extract thermistor	21	1.J
-W102.4	2	= A 1 - T 1 0 2 : 5 0	= A 1 - R 18:2	Extract thermistor	21	2 . J
-W102.4.1	1		= A 1 - R 1 8 . 1 : 1	Extract thermistor	21	5 . J
-W102.4.1	2		= A 1 - R 1 8 . 1 : 2	Extract thermistor	21	5 . J
-W102.4.2	1	= A 1 - T 1 0 2 . 1 : 5 3	= A 1 - R 2 0 : 1	Extract thermistor	21	10.J
-W102.4.2	2	= A 1 - T 1 0 2 . 1 : 5 0	= A 1 - R 2 0 : 2	Extract thermistor	21	10.J
- W 3 0 1	1	= A 1 - X 5 : 1	= A 1 - B 1 : 1	Filterguard supply	23	2 . B
- W 3 0 1	2	= A 1 - X 5 : 2	= A 1 - B 1 : 3	Filterguard supply	23	2 . D
-W301.1	1	= A 1 - X 5 : 2	= A 1 - B 2 : 1	Pre-filterguard supply	23	2 . E
-W301.1	2	= A 1 - X 5 : 3	= A 1 - B 2 : 3	Pre-filterguard supply	23	2.F
- W 3 0 2	1	= A 1 - X 3 : 2	= A 1 - B 3 : 1	Filterguard Extract	13	2 . C
- W 3 0 2	2	= A 1 - X 3 : 1	= A 1 - B 3 : 3	Filterguard Extract	13	2 . E
- W 3 0 4	1	= A 1 - X 3 : 1 3	= A 1 - B 4	Fire termostat supply air	14	2 . B
- W 3 0 4	2	= A 1 - X 3 : 1 4	= A 1 - B 4	Fire termostat supply air	14	2 . D
- W 3 0 5	1	= A 1 - X 3 : 1 4	= A 1 - B 5	Fire termostat extract air	14	2 . E
- W 3 0 5	2	= A 1 - X 3 : 1 5	= A 1 - B 5	Fire termostat extract air	14	2 . G
- W 3 0 6	1	= A 1 - X 3 : 1 6	= A 1 - B 6 : 1	Smokedetector	14	8 . C

0.11		1.0	List of Cable Cores	15		
Cablename (-)	Wire	Connection 1	Connection 2	Description	Sheet	Path
-W306	2	= A 1 - X 3 : 1 7	= A 1 - B 6 : 2	Smokedetector	1 4	8 . C
-W306	3	= A 1 - X 3 : 1 3	= A 1 - B 6 : 4	Smokedetector	14	7 . C
- W 3 0 6	4	= A 1 - X 3 : 1 5	= A 1 - B 6 : 1 0	Smokedetector	14	7 . E
- W 3 1 0	1	= A 1 - X 3 : 2 0	= A 1 - R 3	Temperatur sensor extract	15	3 . C
-W310	2	= A 1 - X 3 : 1 9	= A 1 - R 3	Temperatur sensor extract	15	3 . C
- W 3 1 1	1	= A 1 - X 3 : 2 0	= A 1 - R 4	Temperatur sensor supply ai	r 15	7 . C
-W311	2	= A 1 - X 3 : 2 1	= A 1 - R 4	Temperatur sensor supply ai	r 15	7 . C
- W 3 1 2	1	= A 1 - X 5 : 1 8	= A 1 - R 1	Temperatur sensor intake	24	2 . C
- W 3 1 2	2	= A 1 - X 5 : 1 7	= A 1 - R 1	Temperatur sensor intake	24	2 . C
- W 3 1 3	1	= A 1 - X 5 : 2 1	= A 1 - R 2	Temperatur sensor exhaust	24	12.C
-W313	2	= A 1 - X 5 : 2 0	= A 1 - R 2	Temperatur sensor exhaust	24	12.C
- W 3 1 4	1	= A 1 - X 3 : 2 3	= A 1 - R 5	Frost protection heating coil	15	15.C
- W 3 1 4	2	= A 1 - X 3 : 2 4	= A 1 - R 5	Frost protection heating coil	15	15.C
- W 3 1 5	1	= A 1 - X 5 : 1 8	= A 1 - R 6	Deicing for plate heat	24	5 . C
- W 3 1 5	2	= A 1 - X 5 : 1 9	= A 1 - R 6	Deicing for plate heat	24	5 . C
- W 3 1 9	1	= A 1 - X 3 : 1 7	-B8:1	Electrical heating coil	14	12.B
- W 3 1 9	2	= A 1 - X 3 : 1 8	- B 8 : 2	Electrical heating coil	1 4	12.F
- W 3 1 9	3	= A 1 - X 3 : 4 1	- B 8 : Y	Electrical heating coil	1 4	13.C
- W 3 1 9	4	= A 1 - X 3 : 4 2	- B 8 : G O	Electrical heating coil	1 4	14.C
- W 3 1 9	5	= A 1 - X 2 : 3	- B 8:7	Electrical heating coil	1 4	14.C
system	-:-		Project: DV Control system	Function decription: Sheet: Ne:	t sheet:	46

-W320 2 = A1-X3:43 = A1-M6:2 Heating valve 19 5.8 -W320 3 = A1-X3:41 = A1-M6:3 Heating valve 19 4W321 1 = A1-X3:42 = A1-M7:1 Cooling valve 19 11.8 -W321 2 = A1-X3:43 = A1-M7:2 Cooling valve 19 11.8 -W321 3 = A1-X3:44 = A1-M7:3 Cooling valve 19 11.8 -W322 1 = A1-X5:36 = A1-M8:1 Bypass plate heating 27 7.8 -W322 2 = A1-X5:37 = A1-M8:2 Bypass plate heating 27 7.8 -W322 3 = A1-X5:35 = A1-M8:3 Bypass plate heating 27 7.8 -W322 3 = A1-X5:35 = A1-M8:3 Bypass plate heating 27 7.8 -W322 3 = A1-X5:35 = A1-M8:3 Bypass plate heating 27 7.8 -W328 1 = A1-X3:10 = A1-DVU:7 DVU Control 13 11.6 -W328 2 = A1-X3:9 = A1-DVU:8 DVU Control 20 4W328 3 = A1-K3:14 = A1-DVU:3 DVU Control 20 4W328 4 = A1-X3:44 = A1-DVU:5 DVU Control 19 13W328 5 = A1-X3:44 = A1-DVU:6 DVU Control 19 13W328 6 = A1-X3:42 = A1-DVU:6 DVU Control 19 13W329 1 = A1-F2:1 = A1-DVU:1 DVU supply 10 17W329 2 = A1-F2:3 = A1-DVU:2 DVU supply 10 17W329 3 = A1-F2:5 = A1-DVU:2 DVU supply 10 18.	Cablename (-)	Wire	Connection 1	C	onnection 2	Description	Sheet	Path
-W320 2 = A1-X3:43 = A1-M6:2 Heating valve 19 5.8 -W320 3 = A1-X3:41 = A1-M6:3 Heating valve 19 4W321 1 = A1-X3:42 = A1-M7:1 Cooling valve 19 11.8 -W321 2 = A1-X3:43 = A1-M7:2 Cooling valve 19 11.8 -W321 3 = A1-X3:44 = A1-M7:3 Cooling valve 19 11.8 -W322 1 = A1-X5:36 = A1-M8:1 Bypass plate heating 27 7.8 -W322 2 = A1-X5:37 = A1-M8:2 Bypass plate heating 27 7.8 -W322 3 = A1-X5:35 = A1-M8:3 Bypass plate heating 27 7.8 -W322 3 = A1-X5:35 = A1-M8:3 Bypass plate heating 27 7.8 -W322 3 = A1-X5:35 = A1-M8:3 Bypass plate heating 27 7.8 -W328 1 = A1-X3:10 = A1-DVU:7 DVU Control 13 11.6 -W328 2 = A1-X3:9 = A1-DVU:8 DVU Control 20 4W328 3 = A1-K3:14 = A1-DVU:3 DVU Control 20 4W328 4 = A1-X3:44 = A1-DVU:5 DVU Control 19 13W328 5 = A1-X3:42 = A1-DVU:6 DVU Control 19 13W329 1 = A1-F2:1 = A1-DVU:1 DVU supply 10 17W329 2 = A1-F2:3 = A1-DVU:2 DVU supply 10 17W329 3 = A1-F2:5 = A1-DVU:2 DVU supply 10 18.	-W319	6	= A 1 - X 2 : 4	-	B8:8	Electrical heating coil	14	14.C
-W320 3 = A1-X3:41 = A1-M6:3 Heating valve 19 4W321 1 = A1-X3:42 = A1-M7:1 Cooling valve 19 11W321 2 = A1-X3:43 = A1-M7:2 Cooling valve 19 11W321 3 = A1-X3:44 = A1-M7:3 Cooling valve 19 11W322 1 = A1-X5:36 = A1-M8:1 Bypass plate heating 27 7W322 2 = A1-X5:37 = A1-M8:2 Bypass plate heating 27 7W322 3 = A1-X5:35 = A1-M8:3 Bypass plate heating 27 7W322 3 = A1-X5:35 = A1-M8:3 Bypass plate heating 27 7W328 1 = A1-X3:10 = A1-DVU:7 DVU Control 13 11W328 2 = A1-X3:9 = A1-DVU:8 DVU Control 20 4W328 3 = A1-K3:14 = A1-DVU:3 DVU Control 20 4W328 4 = A1-K3:11 = A1-DVU:4 DVU Control 20 4W328 5 = A1-X3:44 = A1-DVU:5 DVU Control 19 13W328 6 = A1-X3:42 = A1-DVU:6 DVU Control 19 13W329 1 = A1-F2:1 = A1-DVU L1 DVU supply 10 17W329 2 = A1-F2:3 = A1-DVU L2 DVU supply 10 18.	- W 3 2 0	1	= A 1 - X 3 : 4 2	=	A 1 - M 6 : 1	Heating valve	19	5 . J
-W321 1 = A1-X3:42 = A1-M7:1 Cooling valve 19 11.8 -W321 2 = A1-X3:43 = A1-M7:2 Cooling valve 19 11.8 -W321 3 = A1-X3:44 = A1-M7:3 Cooling valve 19 11.8 -W322 1 = A1-X5:36 = A1-M8:1 Bypass plate heating 27 7.8 -W322 2 = A1-X5:37 = A1-M8:2 Bypass plate heating 27 7.8 -W322 3 = A1-X5:35 = A1-M8:3 Bypass plate heating 27 7.8 -W322 3 = A1-X5:35 = A1-M8:3 Bypass plate heating 27 7.8 -W322 3 = A1-X5:35 = A1-M8:3 Bypass plate heating 27 7.8 -W328 1 = A1-X3:10 = A1-DVU:7 DVU Control 13 11.6 -W328 2 = A1-X3:9 = A1-DVU:8 DVU Control 20 4.8 -W328 3 = A1-K3:14 = A1-DVU:3 DVU Control 20 4.8 -W328 4 = A1-K3:11 = A1-DVU:4 DVU Control 20 4.8 -W328 5 = A1-X3:44 = A1-DVU:5 DVU Control 19 13.8 -W328 6 = A1-X3:42 = A1-DVU:5 DVU Control 19 13.8 -W329 1 = A1-F2:1 = A1-DVU L1 DVU supply 10 17.8 -W329 2 = A1-F2:3 = A1-DVU L2 DVU supply 10 17.8	- W 3 2 0	2	= A 1 - X 3 : 4 3	=	A 1 - M 6 : 2	Heating valve	19	5 . K
-W321 2 = A1-X3:43 = A1-M7:2 Cooling valve 19 11.P -W321 3 = A1-X3:44 = A1-M7:3 Cooling valve 19 11.P -W322 1 = A1-X5:36 = A1-M8:1 Bypass plate heating 27 7.P -W322 2 = A1-X5:37 = A1-M8:2 Bypass plate heating 27 7.P -W322 3 = A1-X5:35 = A1-M8:3 Bypass plate heating 27 7.P -W328 1 = A1-X3:10 = A1-DVU:7 DVU Control 13 11.C -W328 2 = A1-X3:9 = A1-DVU:8 DVU Control 13 11.C -W328 3 = A1-K3:14 = A1-DVU:8 DVU Control 20 4.C -W328 4 = A1-K3:14 = A1-DVU:4 DVU Control 20 4.C -W328 5 = A1-X3:44 = A1-DVU:5 DVU Control 19 13.C -W328 6 = A1-X3:42 = A1-DVU:5 DVU Control 19 13.C -W329 1 = A1-F2:1 = A1-DVU:1 DVU Supply 10 17.C -W329 3 = A1-F2:3 = A1-DVU:1 DVU Supply 10 17.C -W329 3 = A1-F2:5 = A1-DVU:1 DVU Supply 10 18.C	- W 3 2 0	3	= A 1 - X 3 : 4 1	=	A 1 - M 6 : 3	Heating valve	19	4 . J
-W321 3 = A1-X3:44 = A1-M7:3 Cooling valve 19 11W322 1 = A1-X5:36 = A1-M8:1 Bypass plate heating 27 7W322 2 = A1-X5:37 = A1-M8:2 Bypass plate heating 27 7W322 3 = A1-X5:35 = A1-M8:3 Bypass plate heating 27 7W328 1 = A1-X3:10 = A1-DVU:7 DVU Control 13 11W328 2 = A1-X3:9 = A1-DVU:8 DVU Control 13 11W328 3 = A1-K3:14 = A1-DVU:8 DVU Control 20 4W328 4 = A1-K3:11 = A1-DVU:4 DVU Control 20 4W328 5 = A1-X3:44 = A1-DVU:5 DVU Control 19 13W328 6 = A1-X3:42 = A1-DVU:6 DVU Control 19 13W329 1 = A1-F2:1 = A1-DVU:1 DVU supply 10 17W329 2 = A1-F2:3 = A1-DVU L2 DVU supply 10 17W329 3 = A1-F2:5 = A1-DVU L3 DVU supply 10 18.	- W 3 2 1	1	= A 1 - X 3 : 4 2	=	A 1 - M 7 : 1	Cooling valve	19	11.J
-W322 1 = A1-X5:36 = A1-M8:1 Bypass plate heating 27 7.8 -W322 2 = A1-X5:37 = A1-M8:2 Bypass plate heating 27 7.8 -W322 3 = A1-X5:35 = A1-M8:3 Bypass plate heating 27 7.8 -W328 1 = A1-X3:10 = A1-DVU:7 DVU Control 13 11.6 -W328 2 = A1-X3:9 = A1-DVU:8 DVU Control 13 11.6 -W328 3 = A1-K3:14 = A1-DVU:3 DVU Control 20 4.6 -W328 4 = A1-K3:11 = A1-DVU:4 DVU Control 20 4.6 -W328 5 = A1-X3:44 = A1-DVU:5 DVU Control 19 13.6 -W328 6 = A1-X3:42 = A1-DVU:6 DVU Control 19 13.6 -W329 1 = A1-F2:1 = A1-DVU:1 DVU supply 10 17.6 -W329 2 = A1-F2:3 = A1-DVU L2 DVU supply 10 17.6 -W329 3 = A1-F2:5 = A1-DVU L3 DVU supply 10 18.6	- W 3 2 1	2	= A 1 - X 3 : 4 3	=	A 1 - M 7 : 2	Cooling valve	19	11.K
-W322 2 = A1-X5:37 = A1-M8:2 Bypass plate heating 27 7.8 -W322 3 = A1-X5:35 = A1-M8:3 Bypass plate heating 27 7.8 -W328 1 = A1-X3:10 = A1-DVU:7 DVU Control 13 11.6 -W328 2 = A1-X3:9 = A1-DVU:8 DVU Control 13 11.6 -W328 3 = A1-K3:14 = A1-DVU:3 DVU Control 20 4.6 -W328 4 = A1-K3:11 = A1-DVU:4 DVU Control 20 4.6 -W328 5 = A1-X3:44 = A1-DVU:5 DVU Control 19 13.6 -W328 6 = A1-X3:42 = A1-DVU:6 DVU Control 19 13.6 -W329 1 = A1-F2:1 = A1-DVU L1 DVU supply 10 17.6 -W329 2 = A1-F2:3 = A1-DVU L2 DVU supply 10 17.6 -W329 3 = A1-F2:5 = A1-DVU L3 DVU supply 10 18.6	- W 3 2 1	3	= A 1 - X 3 : 4 4	=	A 1 - M 7 : 3	Cooling valve	19	11.J
-W322 3 = A1-X5:35 = A1-M8:3 Bypass plate heating 27 7.8 -W328 1 = A1-X3:10 = A1-DVU:7 DVU Control 13 11.6 -W328 2 = A1-X3:9 = A1-DVU:8 DVU Control 20 4.5 -W328 3 = A1-K3:14 = A1-DVU:3 DVU Control 20 4.5 -W328 4 = A1-K3:11 = A1-DVU:4 DVU Control 20 4.5 -W328 5 = A1-X3:44 = A1-DVU:5 DVU Control 19 13.5 -W328 6 = A1-X3:42 = A1-DVU:6 DVU Control 19 13.5 -W329 1 = A1-F2:1 = A1-DVU L1 DVU supply 10 17.5 -W329 2 = A1-F2:3 = A1-DVU L2 DVU supply 10 17.5 -W329 3 = A1-F2:5 = A1-DVU L3 DVU supply 10 18.5	- W 3 2 2	1	= A 1 - X 5 : 3 6	=	A 1 - M 8 : 1	Bypass plate heating	27	7 . K
-W328 1 = A1-X3:10 = A1-DVU:7 DVU Control 13 11.6 -W328 2 = A1-X3:9 = A1-DVU:8 DVU Control 20 4.5 -W328 3 = A1-K3:14 = A1-DVU:3 DVU Control 20 4.5 -W328 4 = A1-K3:11 = A1-DVU:4 DVU Control 20 4.5 -W328 5 = A1-X3:44 = A1-DVU:5 DVU Control 19 13.5 -W328 6 = A1-X3:42 = A1-DVU:6 DVU Control 19 13.5 -W329 1 = A1-F2:1 = A1-DVU L1 DVU supply 10 17.5 -W329 2 = A1-F2:3 = A1-DVU L2 DVU supply 10 17.5 -W329 3 = A1-F2:5 = A1-DVU L3 DVU supply 10 18.5	- W 3 2 2	2	= A 1 - X 5 : 3 7	=	A 1 - M 8 : 2	Bypass plate heating	27	7 . K
-W328 2 = A1-X3:9 = A1-DVU:8 DVU Control 13 11.F -W328 3 = A1-K3:14 = A1-DVU:3 DVU Control 20 4.x -W328 4 = A1-K3:11 = A1-DVU:4 DVU Control 20 4.x -W328 5 = A1-X3:44 = A1-DVU:5 DVU Control 19 13.x -W328 6 = A1-X3:42 = A1-DVU:6 DVU Control 19 13.x -W329 1 = A1-F2:1 = A1-DVU L1 DVU supply 10 17.x -W329 2 = A1-F2:3 = A1-DVU L2 DVU supply 10 17.x -W329 3 = A1-F2:5 = A1-DVU L3 DVU supply 10 18.x	- W 3 2 2	3	= A 1 - X 5 : 3 5	=	A 1 - M 8 : 3	Bypass plate heating	27	7 . K
-W328 3 = A1-K3:14 = A1-DVU:3 DVU Control 20 4.x -W328 4 = A1-K3:11 = A1-DVU:4 DVU Control 20 4.x -W328 5 = A1-X3:44 = A1-DVU:5 DVU Control 19 13.x -W328 6 = A1-X3:42 = A1-DVU:6 DVU Control 19 13.x -W329 1 = A1-F2:1 = A1-DVU L1 DVU supply 10 17.x -W329 2 = A1-F2:3 = A1-DVU L2 DVU supply 10 17.x -W329 3 = A1-F2:5 = A1-DVU L3 DVU supply 10 18.x	-W328	1	= A 1 - X 3 : 1 0	=	A 1 - D V U : 7	DVU Control	13	11.C
-W328 4 = A1-K3:11 = A1-DVU:4 DVU Control 20 4.x -W328 5 = A1-X3:44 = A1-DVU:5 DVU Control 19 13.x -W328 6 = A1-X3:42 = A1-DVU:6 DVU Control 19 13.x -W329 1 = A1-F2:1 = A1-DVU L1 DVU supply 10 17.x -W329 2 = A1-F2:3 = A1-DVU L2 DVU supply 10 17.x -W329 3 = A1-F2:5 = A1-DVU L3 DVU supply 10 18.x	- W 3 2 8	2	= A 1 - X 3 : 9	=	: A 1 - D V U : 8	DVU Control	13	11.F
-W328 5 = A1-X3:44 = A1-DVU:5 DVU Control 19 13W328 6 = A1-X3:42 = A1-DVU:6 DVU Control 19 13W329 1 = A1-F2:1 = A1-DVU L1 DVU supply 10 17W329 2 = A1-F2:3 = A1-DVU L2 DVU supply 10 17W329 3 = A1-F2:5 = A1-DVU L3 DVU supply 10 18	-W328	3	= A 1 - K 3 : 1 4	=	: A 1 - D V U : 3	DVU Control	20	4 . J
-W328 6 = A1-X3:42 = A1-DVU:6 DVU Control 19 13W329 1 = A1-F2:1 = A1-DVU L1 DVU supply 10 17W329 2 = A1-F2:3 = A1-DVU L2 DVU supply 10 17W329 3 = A1-F2:5 = A1-DVU L3 DVU supply 10 18	- W 3 2 8	4	= A 1 - K 3:11	=	: A 1 - D V U : 4	DVU Control	20	4 . J
-W329 1 =A1-F2:1 =A1-DVUL1 DVU supply 10 17.\(\text{.}\) -W329 2 =A1-F2:3 =A1-DVUL2 DVU supply 10 17.\(\text{.}\) -W329 3 =A1-F2:5 =A1-DVUL3 DVU supply 10 18.\(\text{.}\)	-W328	5	= A 1 - X 3 : 4 4	=	A 1 - D V U : 5	DVU Control	19	13.J
-W329 2 =A1-F2:3 =A1-DVU L2 DVU supply 10 17W329 3 =A1-F2:5 =A1-DVU L3 DVU supply 10 18	-W328	6	= A 1 - X 3 : 4 2	=	A 1 - D V U : 6	DVU Control	19	13.J
-W329 3 =A1-F2:5 =A1-DVUL3 DVU supply 10 18.	-W329	1	= A 1 - F 2 : 1	=	A1-DVU L1	DVU supply	10	17.J
	-W329	2	= A 1 - F 2 : 3	=	: A 1 - D V U L 2	DVU supply	10	17.J
-W329 4 = A1-F2:N = A1-DVUN DVU supply 10 18.	- W 3 2 9	3	= A 1 - F 2 : 5	=	A 1 - D V U L 3	DVU supply	10	18.J
	-W329	4	= A 1 - F 2 : N	=	: A 1 - D V U N	DVU supply	10	18.J

Cablename (-)	Wire	Connection 1		Connection 2		Description	Sheet	Path
-W329	5	= A 1 P E		= A 1 - D V U P E		DVU supply	10	18.J
- W 3 3 0	1	= A 1 - X 5 : 2 9		= A 1 - M 3 : 1		Supply air damper on/off	26	5 . K
- W 3 3 0	2	= A 1 - X 5 : 2 8		= A 1 - M 3 : 2		Supply air damper on/off	26	5 . K
-W330	3	= A 1 - X 5 : 3 0		= A 1 - M 3 : 3		Supply air damper on/off	26	5 . K
-W330S	1	= A 1 - X 5 : 2 9		= A 1 - M 3 s : 1		Supply air damper springreturn	26	8 . K
-W330S	2	= A 1 - X 5 : 3 0		= A 1 - M 3 s : 2		Supply air damper springreturn	26	8 . K
- W 3 3 1	1	= A 1 - X 3 : 3 5		= A 1 - M 4 : 1		Extract air damper on/off	18	1.J
- W 3 3 1	2	= A 1 - X 3 : 3 4		= A 1 - M 4 : 2		Extract air damper on/off	18	2 . J
- W 3 3 1	3	= A 1 - X 3 : 3 3		= A 1 - M 4 : 3		Extract air damper on/off	18	2 . J
-W331S	1	= A 1 - X 3 : 3 5		= A 1 - M 4 s : 1		Extract air damper spring	18	4 . J
-W331S	2	= A 1 - X 3 : 3 3		= A 1 - M 4 s : 2		Extract air damper spring	18	4 . J
- W 3 3 2	1	= A 1 - X 3 : 3 8		= A 1 - M 1 1 : 1		Rec mix damper	18	12.J
-W332	2	= A 1 - X 3 : 3 9		= A 1 - M 1 1 : 2		Rec mix damper	18	12.J
- W 3 3 2	3	= A 1 - X 3 : 3 7		= A 1 - M 1 1 : 3		Rec mix damper	18	12.J
-W332s	1	= A 1 - X 3 : 3 8		= A 1 - M 1 1 s : 1			18	14.J
-W332s	2	= A 1 - X 3 : 3 7		= A 1 - M 1 1 s : 2			18	15.J
-W333	1	= A 1 - X 5 : 3 3		= A 1 - M 9 : 1		Supply air mix damper	26	11.J
-W333	2	= A 1 - X 5 : 3 2		= A 1 - M 9 : 2		Supply air mix damper	26	11.J
- W 3 3 3	3	= A 1 - X 5 : 3 1		= A 1 - M 9 : 3		Supply air mix damper	26	11.J
- W 3 3 4	1	= A 1 - X 3 : 3 5		= A 1 - M 1 0 : 1		mix extract damper on/off	18	6 . J
system	•		Project:	DV Control system	nction decription:	Sheet: Next sh	eet:	

Cablename (-)	Wire	Connection 1	Connection 2	Description	Sheet	Path
- W 3 3 4	2	= A 1 - X 3 : 3 4	= A 1 - M 1 0 : 2	mix extract damper on/off	18	7.J
- W 3 3 4	3	= A 1 - X 3 : 3 6	= A 1 - M 1 0 : 3	mix extract damper on/off	18	7 . J
-W334s	1	= A 1 - X 3 : 3 5	= A 1 - M 1 0 s : 1	Mix extract damper spring	18	9 . J
- W 3 3 4 s	2	= A 1 - X 3 : 3 6	= A 1 - M 1 0 s : 2	Mix extract damper spring	18	9 . J
- W 3 4 0	1	= A 1 - X 3 : 2 7	= A 1 - P 4 : 2 4 V	Pressure extract air external	16	3 . C
- W 3 4 0	2	= A 1 - X 3 : 2 5	= A 1 - P 4 : 0 - 1 0 V	Pressure extract air external	16	2 . C
- W 3 4 0	3	= A 1 - X 3 : 2 6	= A 1 - P 4 : A N G	Pressure extract air external	16	2 . C
- W 3 4 1	1	= A 1 - X 3 : 3 1	= A 1 - P 3 : 2 4 V	Pressure supply external	16	15.C
- W 3 4 1	2	= A 1 - X 3 : 3 2	= A 1 - P 3 : 0 - 1 0 V	Pressure supply external	16	15.C
- W 3 4 1	3	= A 1 - X 3 : 3 0	= A 1 - P 3 : A N G	Pressure supply external	16	14.C
- W 3 5 0	1	= A 1 - X 3 : 2 7	= A 1 - P 1 : 2 4 V	Flow measuring supply	16	7 . C
- W 3 5 0	2	= A 1 - X 3 : 2 8	= A 1 - P 1 : 0 - 1 0 V	Flow measuring supply	16	6 . C
- W 3 5 0	3	= A 1 - X 3 : 2 6	= A 1 - P 1 : A N G	Flow measuring supply	16	6 . C
- W 3 5 1	1	= A 1 - X 5 : 2 8	= A 1 - P 2 : 2 4 V	Flow measuring extract	2.5	15.C
- W 3 5 1	2	= A 1 - X 5 : 2 7	= A 1 - P 2 : 0 - 1 0 V	Flow measuring extract	2.5	14.C
- W 3 5 1	3	= A 1 - X 5 : 2 9	= A 1 - P 2 : A N G	Flow measuring extract	2.5	14.C
- W 3 5 2	1	= A 1 - X 5 : 2 5	= A 1 - P 6 : 2 4 V	Humidity sensor supplyair	25	11.C
- W 3 5 2	2	= A 1 - X 5 : 2 6	= A 1 - P 6 : 0 - 1 0 V	Humidity sensor supplyair	25	10.C
- W 3 5 2	3	= A 1 - X 5 : 2 4	= A 1 - P 6 : A N G	Humidity sensor supplyair	25	10.C
- W 3 5 3	1	= A 1 - X 5 : 1 4	= A 1 - P 9 / - P 5 : 2 4 V	Humidity sensor external	24	9 . C
system	nie		Project: DV Control system	nction decription: Sheet: Next	sheet:	49

Cablename (-)	Wire	Connection 1	Connection 2	Description	Sheet	Pat
-W353	2	= A 1 - X 5 : 1 6	= A 1 - P 9 / - P 5 : 0 - 1 0 V	Humidity sensor external	2 4	8 . C
- W 3 5 3	3	= A 1 - X 5 : 1 5	= A 1 - P 9 / - P 5 : A N G	Humidity sensor external	2 4	8 . C
- W 3 5 4	1	= A 1 - X 3 : 3 1	= A 1 - P 7 / - P 8 : 2 4 V	CO2 Sensor	16	11.C
- W 3 5 4	2	= A 1 - X 3 : 2 9	= A 1 - P 7 / - P 8 : 0 - 1 0 V	CO2 Sensor	16	11.C
- W 3 5 4	3	= A 1 - X 3 : 3 0	= A 1 - P 7 / - P 8 : A N G	CO2 Sensor	16	10.C
-W360	1	= A 1 - X 5 : 2 1	= A 1 - R 7	Room sensor no.1	25	2 . C
-W360	2	= A 1 - X 5 : 2 2	= A 1 - R 7	Room sensor no.1	25	2 . C
- W 3 6 1	1	= A 1 - X 5 : 2 4	= A 1 - R 8	Room sensor no.2	25	5 . C
- W 3 6 1	2	= A 1 - X 5 : 2 3	= A 1 - R 8	Room sensor no.2	25	5 . C
-W363	1	= A 1 - X 3 : 2 3	= A 1 - R 9	Outdoor sensor	15	11.C
-W363	2	= A 1 - X 3 : 2 2	= A 1 - R 9	Outdoorsensor	15	11.C
- W 3 6 5	1	= A 1 - R 1 0	= A 1 - X 5 : 2 4	Pre-heat temperatur sensor	25	7 . C
- W 3 6 5	2	= A 1 - R 1 0	= A 1 - X 5 : 2 3	Pre-heat temperatur sensor	25	8 . C
- W 3 7 1	1	= A 1 - X 3 : 3 9	= A 1 - B 7 : 1	Capilarsensor	18	17.B
- W 3 7 1	2	= A 1 - X 3 : 5 0	= A 1 - B 7 : 4	Capilarsensor	18	17.D
-W371.1	1	= A 1 - B 8 : 1	= A 1 - X 3 : 5 0	Capilarsensor bulb	18	17.E
-W371.1	2	= A 1 - X 3 : 4 0	= A 1 - B 8 : 4	Capilarsensor bulb	18	17.F
- W 3 8 0	1	= A 1 - X 3 : 1 0	= A 1 - S 2	Reduced speed	13	15.C
-W380	2	= A 1 - X 3 : 1 1	= A 1 - S 2	Reduced speed	13	15.E
- W 3 8 1	1	= A 1 - X 3 : 1 3	= A 1 - S 1 0	Normalspeed	13	17.C

			List of Cable Cores			
Cablename (-)	Wire	Connection 1	Connection 2	Description	Sheet	Pati
- W 3 8 1	2	= A 1 - X 3:12	= A 1 - S 1 0	Normalspeed	13	17.E
-W390	1	= A 1 - X 5 : 3 5	= A 1 - T 1 1 0 : 1 2	Rot. heat recovery	27	4 . K
- W 3 9 0	2	= A 1 - X 5 : 3 6	= A 1 - T 1 1 0 : 1 3	Rot. heat recovery	27	5 . K
- W 3 9 0	3	= A 1 - X 5 : 1 0	= A 1 - T 1 1 0 : 9	Rot. heat recovery	23	12.D
-W390	4	= A 1 - X 5 : 1 1	= A 1 - T 1 1 0 : 1 0	Rot. heat recovery	23	12.D
- W 7 0 0	1	= A 1 - X 2 : 5	= A 1 - S 1	Lightswitch	11	8 . J
- W 7 0 0	2	= A 1 - X 2 : 6	= A 1 - S 1	Lightswitch	11	9 . J
-W701.1	1	= A 1 - X 2 : 7	= A 1 - E 1 . 1 : L 1	Light P20	11	11.J
-W701.1	2	= A 1 - X 2 : 8	= A 1 - E 1 . 1 : N	Light P20	11	11.J
-W701.2	1	= A 1 - E 1 . 1 : L 1	= A 1 - E 1 . 2 : L 1	Light P20	11	12.K
-W701.2	2	= A 1 - E 1 . 1 : N	= A 1 - E 1 . 2 : N	Light P20	11	12.K
-W701.3	1	= A 1 - E 1 . 2 : L 1	= A 1 - E 1 . 3 : L 1	Light P20	11	13.L
-W701.3	2	= A 1 - E 1 . 2 : N	= A 1 - E 1 . 3 : N	Light P20	11	13.L
-W702.1	1	= A 1 - X 2 : 8	= A 1 - E 2 . 1 : L 1	Light P21	11	15.J
-W702.1	2	= A 1 - X 2 : 9	= A 1 - E 2 . 1 : N	Light P21	11	16.J
-W702.2	1	= A 1 - E 2 . 1 : L 1	= A 1 - E 2 . 2 : L 1		11	17.K
-W702.2	2	= A 1 - E 2 . 1 : N	= A 1 - E 2 . 2 : N		11	17.K
-W702.3	1	= A 1 - E 2 . 2 : L 1	= A 1 - E 2 . 3 : L 1		11	18.L
-W702.3	2	= A 1 - E 2 . 2 : N	= A 1 - E 2 . 3 : N		11	18.L
- W 9 0 0	1	= A 1 - X 5 : 3 8	-B9:1	Pre-heating	27	11.J
cyctom	air		Project: DV Control system	Function decription: Sheet:	Next sheet:	5
system	all		Date: Rev.:	Init.: Drawing no.: 4300001;430000	Total sheets:	12

			List	of Cable Cores					
Cablename (-)	Wire	Connection 1		Connection 2		Description		Sheet	Pa
-W900	2	= A 1 - X 5 : 3 7		-B9:2		Pre-heating		27	12.
- W 9 0 0	3	= A 1 - X 5 : 3 9		-B9:Y		Pre-heating		27	13.5
- W 9 0 0	4	= A 1 - X 5 : 3 6		-B9:G0		Pre-heating		27	14.
- W 9 0 0	5	= A 1 - X 5 : 4 0		-B9:8		Pre-heating		27	14.
- W 9 0 0	6	= A 1 - K 1 0 : 1 4		-B9:7		Pre-heating		27	15.
- W 1 0 0 0	1	= A 1 - X 1 : L 1		= A1 - Supply L1		Main supply		10	3
- W 1 0 0 0	2	= A 1 - X 1 : L 2		=A1-Supply L2		Main supply		10	3.
- W 1 0 0 0	3	= A 1 - X 1 : L 3		= A1 - Supply L3		Main supply		10	3.
- W 1 0 0 0	4	= A 1 - X 1 : N		= A 1 - Supply N		Main supply		10	3 . ł
- W 1 0 0 0	5	= A 1 - X 1 : P E		=A1-Supply PE		Main supply		10	4 . I
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system	air		Project:	DV Control system	Function decription	Sheet:	51 Next s	heet:	

						List of PLC	/0						
Function (=)	Location (+)	PLC (-)	Operand	Symbol Adress	Comm	ent	Con. No.	MODBUS	BACKnet	Connection		Sheet	Cell
=A1		-C1	Al1:31	Temperature sensor	Extract	air	Al1	3x00001	VI-1234567	=A1-X3:19		15	3.1
=A1		-C1	AI2:32	Temperature sensor	Supply	air	AI2	3x00001	VI-1234567	=A1-X3:21		15	7.1
=A1		-C1	AI3:34	Temperature sensor	Outdoor	air	AI3	3x00001	VI-1234567	=A1-X3:22		15	11,1
=A1		-C1	AI4:35	Temperature sensor	Frost p	rotection Y1	AI4	3x00001	VI-1234567	=A1-X3:24		15	15.1
=A1		-C1	A01:91	Speed	Supply	air	A01	3x00001	VI-1234567	=A1-X3:7		19	2.D
=A1		-C1	A02:92	Heating coil Y1	Capacity	/	A02	3x00001	VI-1234567	=A1-X3:41		19	4.D
=A1		-C1	A03:93	Cooling / changeover	Capacity	1	A03	3x00001	VI-1234567	=A1-X3:44		19	11.D
=A1		-C1	A04:94	Recirculation	Capacity	/	A04	3x00001	VI-1234567	=A1-K9:12		19	13.D
=A1		-C1	DI1:71	Filter guard	Extract	air	DI1	3x00001	VI-1234567	=A1-X3:1		13	2.1
=A1		-C1	DI2:72	Ready supply fan			DI2	3x00001	VI-1234567	=A1-X3:6		13	5.1
=A1		-C1	DI3:73	Cooling alarm			DI3	3x00001	VI-1234567	=A1-X3:9		13	11.1
=A1		-C1	DI4:74	Frost thermostat			DI4	3x00001	VI-1234567	=A1-K5:14		13	13.1
=A1		-C1	DI5:75	Reduced speed	or stop	unit	DI5	3x00001	VI-1234567	=A1-X3:11		13	15.1
=A1		-C1	DI6:76	Normal speed	Start u	nit	DI6	3x00001	VI-1234567	=A1-X3:12		13	17.1
=A1		-C1	DI7:77	Fire signal			DI7	3x00001	VI-1234567	=A1-X3:15		14	2.1
=A1		-C1	DI8:78	Electrial heater			DI8	3x00001	VI-1234567	=A1-X3:18		14	12.1
=A1		-C1	D01:11	Fan supply air	Start		D01	3x00001	VI-1234567	=A1-K1:A2		17	2.D
=A1		-C1	D02:12	Start heating pump			D02	3x00001	VI-1234567	=A1-K2:A2		17	4.D
=A1		-C1	D03:13	Start cooling			D03	3x00001	VI-1234567	=A1-K3:A2		17	6.D
=A1		-C1	D04:14	Alarm signal			D04	3x00001	VI-1234567	=A1-K4:A2		17	8.D
=A1		-C1	D05:15	Damper motor	Extract	air	D05	3x00001	VI-1234567	=A1-K8:A2		17	11.D
=A1		-C1	D06:16	Rec damper	Start		D07	3x00001	VI-1234567	=A1-K9:A2		17	13.D
=A1		-C1	UI1:41	Pressure transmitter	Extract	air	UI1	3x00001	VI-1234567	=A1-X3:25		16	2.1
=A1		-C1	UI2:42	Flow measuring	Supply	air fan	UI2	3x00001	VI-1234567	=A1-X3:28		16	6.1
=A1		-C1	UI3:44	CO2 sensor	Extract	air or Room	UI3	3x00001	VI-1234567	=A1-X3:29		16	11.1
=A1		-C1	UI4:45	Pressure transmitter	Supply	air Duct	UI4	3x00001	VI-1234567	=A1-X3:32		16	15.1
=A1		-02	AI1:31	Temperature sensor	Intake		Al1	3x00001	VI-1234567	=A1-X5:17		24	2.1
=A1		-C2	AI2:32	Temperature sensor	Deicing		AI2	3x00001	VI-1234567	=A1-X5:19		24	5.1
=A1		-C2	AI3:34	Humidity sensor	Room /	Extract	AI3	3x00001	VI-1234567	=A1-X5:16		24	8.1
=A1		-C2	AI4:35	Temperatur sensor	Exhaust		AI4	3x00001	VI-1234567	=A1-X5:20		24	12.1
SVS	tem air						Control system	Function decri	ption: Irawing no.:	Sheet:	1 Next :	sheet:	2
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Function (=)	Location (+)	PLC (-)	Operand	Symbol	Adress	Comm	ent		Con. No.	MODBUS	BACKnet	Connec	tion		Sheet	Cell
=A1		-C2	A01:91	Speed		Extract	air		A01	3x00001	VI-1234567	=A1-X5:8			27	2.D
=A1		-C2	A02:92	Heat recov	reny	capacity			A02	3x00001	VI-1234567	=A1-X5:35	i		27	4.D
=A1		-C2	A03:93	Split		Y2			A03	3x00001	VI-1234567	=A1-K7:24			27	9.D
=A1		-C2	A04:94	Preheater					A04	3x00001	VI-1234567	=A1-X5:39)		27	13.D
=A1		-C2	DI1:71	Filter guar	rd .	Extract	air		DI1	3x00001	VI-1234567	=A1-X5:3			23	2.1
=A1		-C2	DI2:72	Ready extr	ract fan				DI2	3x00001	VI-1234567	=A1-X5:7			23	5.1
=A1		-C2	DI3:73	Rot. heat e	exhanger				DI3	3x00001	VI-1234567	=A1-X5:10	ı		23	12.1
=A1		-C2	DI4:74	Electrical	Preheat	overhea	†		DI4	3x00001	VI-1234567	=A1-X5:38	3		23	14.1
=A1		-C2	DI5:75	Change ove	≘r				DI5	3x00001	VI-1234567	=A1-X5:12	!		23	16.1
=A1		-C2	DI6:76	Recirculation	on ON				DI6	3x00001	VI-1234567	=A1-X5:13			23	18.1
=A1		-C2	D01:11	Fan extrac	it .	Start			D01	3x00001	VI-1234567	=A1-K6:A	2		26	1.D
=A1		-C2	D02:12	Damper su	pply air				D02	3x00001	VI-1234567	=A1-K7:A:	2		26	3.D
=A1		-C2	D03:13	Circulation	pump	Start			D03	3x00001	VI-1234567	=A1-X5:34	,		26	13.D
=A1		-C2	D04:14	Preheating		Start			D04	3x00001	VI-1234567	=A1-K10:A	12		26	15.D
=A1		-C2	UI1:41	Room sens	or 1				UI1	3x00001	VI-1234567	=A1-X5:22	2		25	2.1
=A1		-C2	UI2:42	Room sens	or 2	Preheati	ng temperatur		UI2	3x00001	VI-1234567	=A1-X5:23	3		25	5.1
=A1		-C2	UI3:44	Humidity se	ensor	Intake			UI3	3x00001	VI-1234567	=A1-X5:26	5		25	10.1
=A1		-C2	UI4:45	Flow measu	uring	Extract	air fan		UI4	3x00001	VI-1234567	=A1-X5:21	7		25	14.1
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0000							Project:	חע רי	ntrol system	Function decri	ption:		Sheet:	2 Next s	sheet:	
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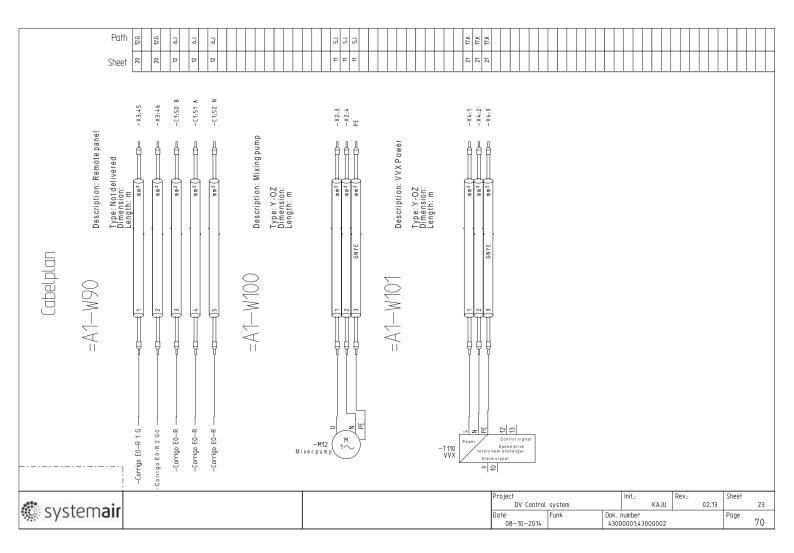
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Fire termostat supply air		=A1-W30			\Box		\sqcap		\sqcap	\top	\sqcap	T	\Box	T	T	1	T	\Box	2	\sqcap	T	\top	\top	Т	П	T	П			\sqcap		П	T	\top	一	\top	\Box	\top	\Box	d	\exists
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Frost protection heating		=A1-W31		+	+	\vdash	+	+	+	+	+	+	H		+	+	+	+	+	+	+	+	+	+	H	+	Н	+	1 2	\vdash	+	Н	+	+	\vdash	+	+	+	+	\vdash	\dashv
Electrical heating coil		=A1-W31		+	+	\vdash	+	+	+	+	+	+	\forall	+	+	\vdash	+	+	+	+	+	1	+	2	H	+	H	+	+-	\vdash	+	Н	+	+	\vdash	+	+	+	+	\vdash	+
DVU Control		=A1-W32		+	+	\vdash	+	+	+	+	+	+	+	1	+	+	+	+	+	+	+	+ '	+	+	\vdash	+	\forall	+	+	\vdash	+	+	+	+	\vdash	+	+	+	+	\vdash	+
Pressure extract air ext	ernal Y-0Z	=A1-W3		+	+	\vdash	+	+	+	+	+	+	+	+	+	+	+	+	+	+	+	+	+	+	\vdash	+	+	+	+	12	3	1	+	+	+	+	+	+	+	\vdash	+
	Y-0Z	=A1-W39		+	+	\vdash	+	+	+	+	+	+	+	+	+	+	+	+	+	+	+	+	+	+	\vdash	+	+	+	+	4) :	,	1	-	+	+	+	+	+	\vdash	+
Flow measuring supply	1-02			+	+	\vdash	+	+	+	+	+	+	+	+	+	\vdash	+	+	+	+	+	+	+	+	Н	+	2	4	+	\vdash	+	4	+	4	+	+	++	+	+	\vdash	+
Outdoor sensor	Y-0Z	=A1-W36 =A1-W38		+	+	\vdash	+	+	+	+	+	+	\Box	+	2	\vdash	+	+	+	+	+	+	+	+	\vdash	+	+4	-	+	\vdash	+	+	+	+	\vdash	+	++	+	+	\vdash	+
Reduced speed	1-02			+	+	\vdash	+	+	+	+	+	+	+1	\vdash	2 2	+	+	1	+	+	+	+	+	+	Н	+	\mathbb{H}	+	+	\vdash	+	\vdash	+	+-	+	+	++	+	+	\vdash	+
Normal speed	0.111.1	=A1-W38	0 1	ш	\perp	ш			ш		ш				1 2	ш		1 1		1		abl	<u> </u>		Ш	\perp	Ш			Ш		Ш			Щ	—	ш		ш	Щ	_
Note	Cabletype	Cable name						_										-	_		(aul	c					_												_	_
syster	n air								-X3) ject	:			D۷	Cont	trol	systi			wing 1 4		000	01;				Re	ev.: 02.13	3	it.:	K	A Jl
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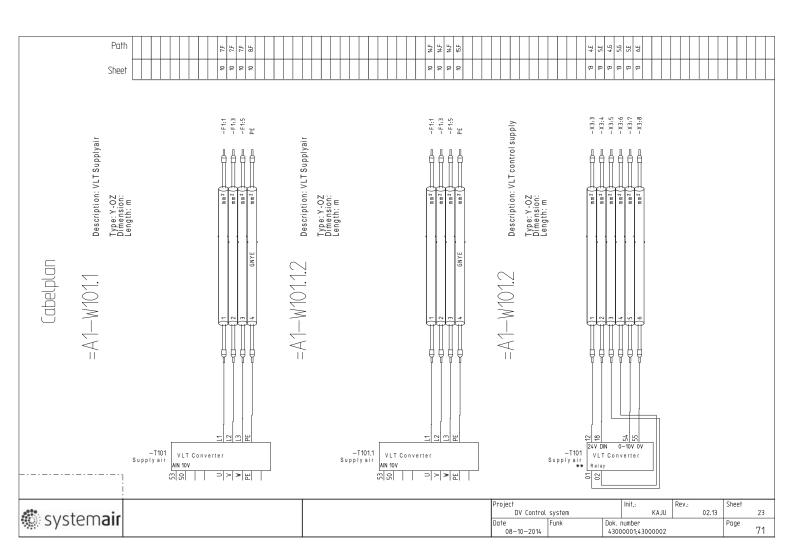
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	Cable type	e	Cable			-				-		_		_		_					-		Cabl	e		_				_			_		_		_	—			
Capilarsensor bulb			=A1-W3	71.1		+	+	_	Н		Н	+	Н	+	+	_		_	Н	+		\mathbf{H}	_		+	_	+	-	\mathbf{H}	+	1	\vdash	+		-	Н	_	++	+	+	+1
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×			. <u>.</u>		Connection 2	-C1:UI3		-K1:A1	-C1:UI4	-K8:11	:	-K8:14					-K9:11	-K5.A2		-K9:14 -K9:14	–K5:A1	-C1:A02					-C1:A03	-K4:24		-K2:21 -K2:24	-B8:1										
lat			Stri		No.	29	2	7.	32	Ξ.	34	7,5			36	37		88	39		07		4.2		43	77		97		æ, o								П		П	
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·					Connection 1	-P7/-P8:0-10V	-P // -P 0: ANG	-P7/-P8:24V -P3:24V	-P3:0-10V	-M4:3 -M4s:2	-M4:2	-M10:2 -M4:1	-M4s:1	-M10:1	-M10:3	-M10s:2	-M11s:2	-M11:1	-M11:2	-87:1	-88:4 -88:Y	-M6:3	-B8:50 -M6:1	-DVU:6	-M6:2	-M7:2		-Corrigo E0-R 1 G -Corrigo E0-R 2 G0	n	-Heating active	-87:4										
Remote panel		Not delivered		=A1-W9	0	П	П	\top	П		П	T	П	\top	П				П		П	П					П	1 2	2	T	П		Т	П		П	T	\Box	T	Π	\top
Electrical heating coil				=A1-W3	19						П		П						П		3	3	4				П		П					П		П		\Box			
Heating valve		Y-0Z		=A1-W3			\Box				Ш						Ш					3	1		2	\perp												Ш			
Cooling valve		Y-0Z		=A1-W3		\perp	$\perp \perp$		Ш		Ш	\perp	Ш	\perp	\perp		\perp		Ш						1	2	3		ш	_	\perp	\perp	\perp			Ш		Ш	_	ш	
DVU Control				=A1-W3		+	+	\perp	\sqcup			+	\square	+	\sqcup	-	\square	_	\sqcup	+	\vdash	\vdash	+	6	\sqcup	- '	5	+	Н	+	\sqcup	\vdash	+	Н	+	\sqcup	\perp	+	+	\sqcup	4
Extract air damper on/of		Y-0Z		=A1-W3		+	+	_	H	3	2	+	1	+	+	_	+	_	\vdash	+		\vdash	_	\vdash	+	-		-	\vdash	+	+	\vdash		Н	-	Н	-	++	+	+	+
Extract air damper spring Rec mix damper		Y-0Z Y-0Z		=A1-W3 =A1-W3		+	+	+	\vdash	2	\vdash	+	H	+	+	+-	3	1	2	+	\vdash	\vdash	+	Н	+	+	+	+	H	+	+			H	+	\vdash	+	\forall	+	\forall	+
iver illix dulliber.		1-02		=A1-W3		+	+	+	H	+	\forall	+	+	+	+	+	2	+	1 4	+	+	H	+	H	+	+	+	+	H	+	+	+	+	H	+	H	+	+	+	\forall	+
mix extract damper on/ot	ff			=A1-W3		+	+	+	H	+	\forall	2	\forall	1	13	+	-	+	\forall	+	+	\forall	+	\vdash	\forall	+	+	_	$^{+}$	+	\forall	+	+	+	+	\forall	+	+	+	\forall	+
Mix extract damper spring				=A1-W3		+	+	+	\forall		\forall	+	\forall	1	1	2	\forall	+	\forall		\vdash	\forall		\vdash	\forall	+	\forall	\top	\forall	+	\forall		+	\vdash	+	\forall	+	+	+	\forall	+
Pressure supply external		Y-0Z		=A1-W3		\top	3	+	2		\forall	$^{+}$	\forall	\top	\Box	Ť	\forall	\top	\forall			\sqcap		\vdash	\top	\top	\forall	\top	\forall	\top	\forall		†	\sqcap	\top	\forall	\top	+	+	\forall	\top
CO2 Sensor		Y-0Z		=A1-W3		2		1	Ħ		П	\top	П	\top	\sqcap		П		П			Ħ			П		П		Ħ	\top	П		\top	Ħ		П		\Box	\top	Ħ	\top
Capilarsensor				=A1-W3	71			I			П	I		I	\Box	I		I		1			I			I		I	o	╧	2		I		I		I	\Box	I	П	\Box
Capilarsensor bulb				=A1-W3	71.1	П					П	\perp	П	\top					П		2	П								\perp	П						Ι	П	I	П	
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systen	n air										-X3									Proje				DV	Cont	rol s	yster		awing		000	001				2	Rev.: 02.	.13	Init.:		A JU
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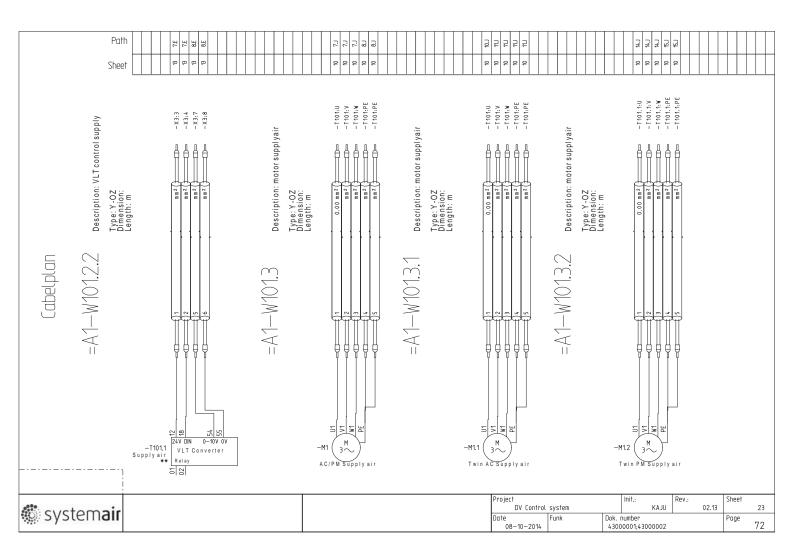
				Path	7.7	-	2	7.7	Т	П	Т	П	Т	П	T	П	Т	П	Т	П		П	Т	Т	П	Τ	П	T	Τ	П	Т	П	Т	П	Т	\Box	П	П	Т	П	٦
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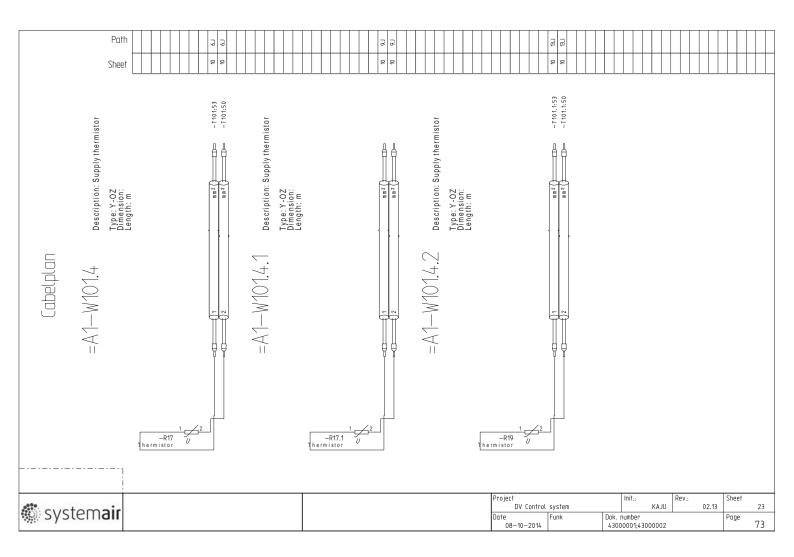
			Pa	th	23 2.B			23 S.C		23 5.6		27 3.1		23.2.E			24 9.E		24 8.E	24 2.E	24 2.E		24.2.E		25 2.E		25 S.E			2570.E 2574.F			25.4.E	\rightarrow	Ze 5.I				П	F	П	Ŧ
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Note	Cabletype	Cable n	ame																				Cab	le																		_
Filterguard supply		=A1-W301			2	Т		П	Т	П	Т	Т	П	Т	Т	П	\neg	П	\top	П	Т	Т	1	П	Т	Т	П		П	\neg	П	П	\top	П	Т	П	Т	\top		\top		\top
Pre-filterguard supply		=A1-W301			1	2	+	H		H	+	+	\vdash	+	+		-	\vdash	+	\vdash	+	+		+	+	+	\vdash	+	H	+	+	\vdash	+	+		+		+	Н	+	\vdash	+
TTE-Intergual a supply		-11-#301	. 1		+	1		H		H	+	+	H	+	+			H	+			H		H	+	+				+	+		+	H	+	+	+	+	H	+	H	+
Terminal Matrix		Terminal Strip:	-X5	Term. No. Connection 2	1 0	0 3 -82:3		25		o 7 –C2:DI2		6	Ş	0 10 -C2:DI3			7, 7		či 95	O 17 –C2:Al1		19	7 20		O 22 –C2:Ul1		24		25	0 26 –C2:UI3	28		29		30		0 0		0 0		0	
Ter				Connection 1	-B1:1	-C2:D11	-T102:12 -T102:1:12	-1102:18	-1102.1:18	-1102:02	-1102:54	-1102:55	-1102.1:55	-1110:9	-changeover signal	-C2:DI5	-LZ:UI6 -P9/-P5:24V	-Rec signal	-P9/-P5:ANG -P9/-P5:0-10V	-R1	-R1	-R6	-R2	-R7	-R7	-R8	-R10	-r8 -P6:ANG	-P6:24V	-P6:0-10V -P2:0-10V	-P2:24V	-M3:2	-P2:ANG	-M3s:1	-M3:3	7.001						
VLT control extract		=	A1-W102.2			П	1	2	T	3 4	5	6		$\overline{}$	\top		\top	П	$\overline{}$	П	T	П		П	Т	$\overline{}$	П		П	\neg	Т	П	$\overline{}$			П		$\overline{}$	\Box	〒	\Box	Ŧ
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Filterguard supply			A1-W301	_	1	+	+	Ħ	Ť	\forall	$^{+}$	+	Ť	+	$^{+}$	\vdash	\top	\vdash	+	\vdash	+	+	\top	+	\top	+	\forall	\top	\Box	\top	\top	\vdash	+	\forall	\top	+	\top	+	\vdash	\top	\vdash	$^{+}$
Pre-filterguard supply			A1-W301.1		\vdash	1	+	\forall	+	\forall	\pm	+	\vdash	+	$^{+}$	\vdash		\vdash	+	+	+	\Box	\pm	\forall	+	+	\vdash	+	\Box	+	+	\vdash	+	\forall	$^{+}$	\forall	\pm	+	\vdash	+	\vdash	+
Temperatur sensor intake	P		A1-W312		\vdash	11	\top	\forall	+	\forall	+	+	\vdash	+	+		\top	\vdash	+	2	1	+		+	+	+	\forall	+	\Box	\top	+	\vdash	+	\forall	+	+	+	+	\vdash	+	\vdash	+
Temperatur sensor exhau			A1-W313		\vdash	+	+	H	+	H	+	+	\vdash	+	+		+	\vdash	+	++	+	+	2 .	1	+	+	H	+	H	+	+	H	+	\forall	+	+		+	+	+	\vdash	+
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Supply air damper on/of	f Y-		A1-W330		\vdash	+	+	Ħ	+	H	\pm	+	H	+	+	H	+	H	+	+	+	+	+	\forall	+	+	H	+	H	+	+	2	+	╁┤	3	\forall	+	+	\vdash	+	\vdash	+
Supply air damper spring			A1-W330S		\vdash	+	+	H	+	H	$^{+}$	+	H	+	+	H	+	H	+	+	+	\forall	+	\forall	+	+	\forall	+	H	+	+	H	+	1	_	2	+	+	\vdash	+	\vdash	+
Flow measuring extract	Y-		A1-W351		\vdash	+	+	\forall	+	\forall	+	+	\vdash	+	+	+	+	\vdash	+	+	+	+	+	\forall	+	+	H	+	\vdash	+	2 1	H	3	۲	+	+	+	+	\vdash	+	+	+
tow measuring extract Humidity sensor supplyair			A1-W352		+	+	+	\forall	+	\forall	+	+	+	+	+	+	+	+	+	+	+	+	+	+	+	+	+	3	1	2		\vdash	+	\forall	+	+	+	+	+	+	\vdash	+
Humidity sensor external			A1-W353		+	+	+	\forall	+	\forall	+	+	+	+	+	+	1	+	3 2	,	+	+	+	\forall	+	+	+	+	H	-	+	\forall	+	\forall	+	+	+	+	+	+	+	+
Room sensor no.1	1-		A1-W360		\vdash	+	+	\vdash	+	+	+	+	\vdash	+	+	+	+-'	+	7 4	+	+	+	+	1	2	+	\vdash	+	\vdash	+	+	\vdash	+	\vdash	+	+	+	+	+	+	+	+
Room sensor no.1			A1-W360 A1-W361	-	+	+	+	\vdash	+	+	+	+	Н	+	+	+	+	\vdash	+	+	+	+	+	+	4	2	\vdash	1	\vdash	+	+	Н	+	\vdash	+	+	+	+	+	+	+	+
Room sensor no.z Pre—heat temperatur sen			A1-W361 A1-W365	_	\vdash	+	+	\vdash	+	\vdash	+	+	\vdash	+	+	\vdash	+	\vdash	+	+	+	+	-	+	+	2 2	+	+	\vdash	+	+	\vdash	+	\vdash	+	+	+	+	+	+-	\vdash	+
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syster syster	Cabletype	Cable n	<u>ame</u>							-X5									L	ro jed			Cab			ntrol	sys	tem	Dra	wing	no.: 430	100	001	;43	000	002	2 R	ev.: 02.1	13	nit.:		A JU
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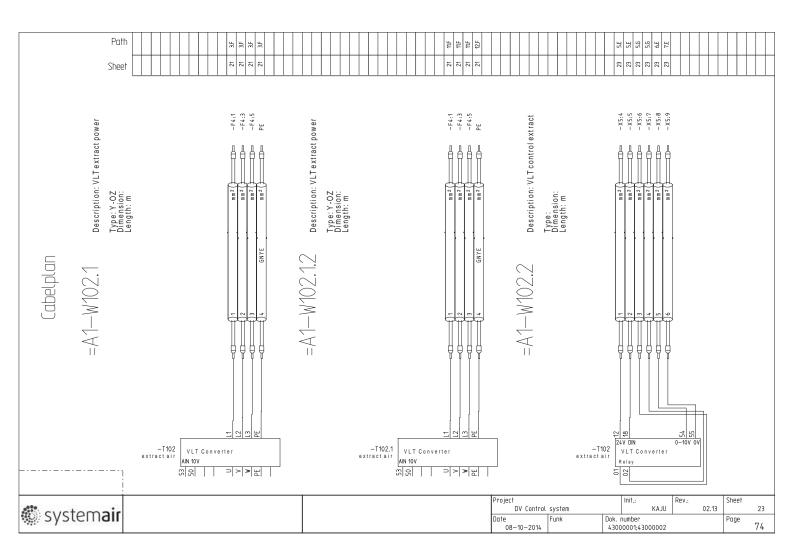
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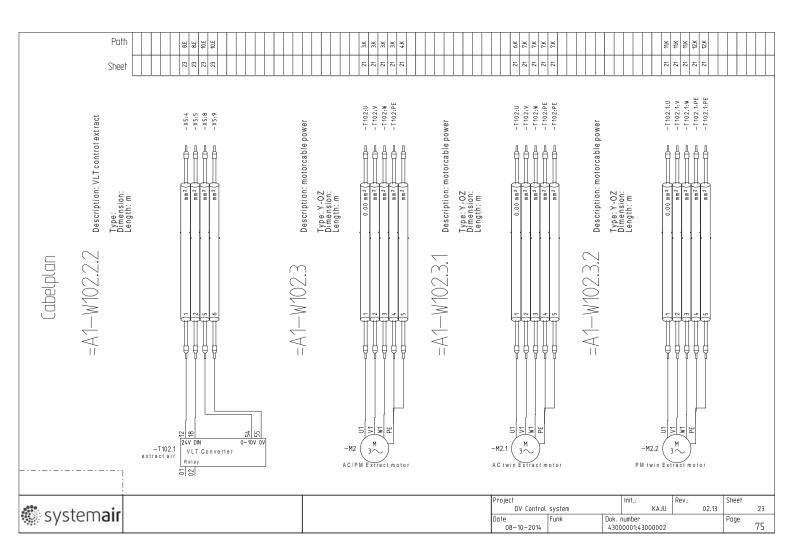


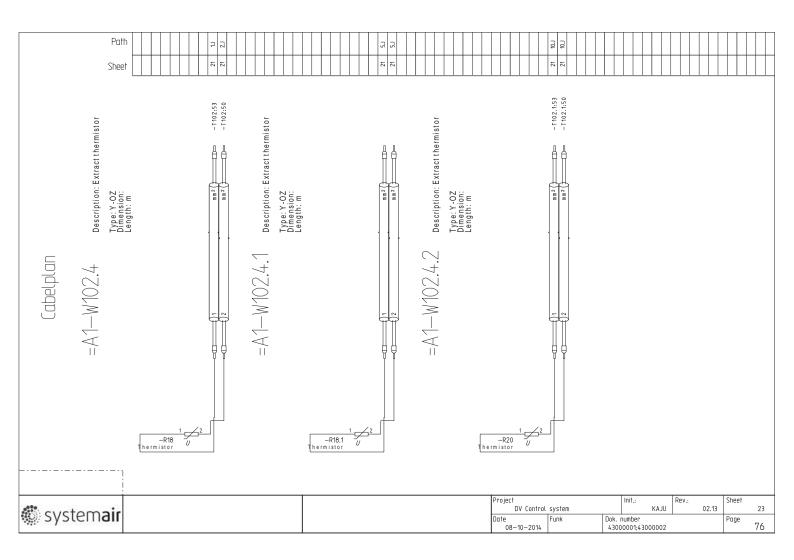


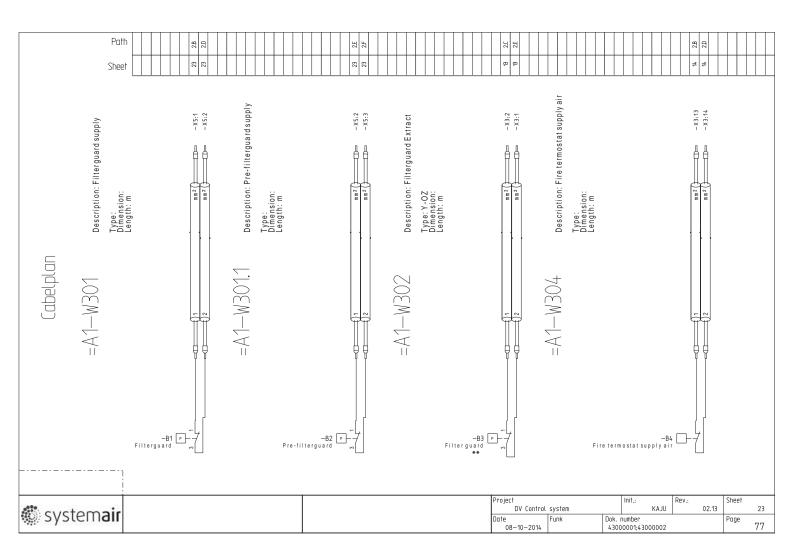


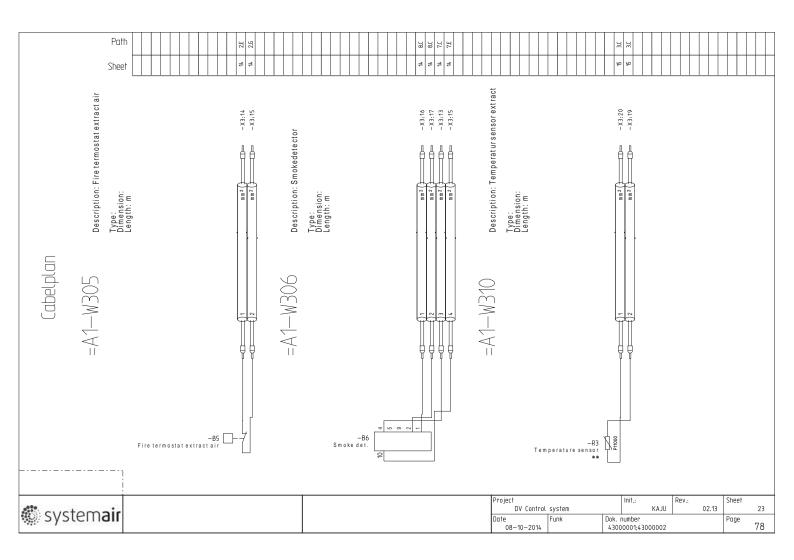


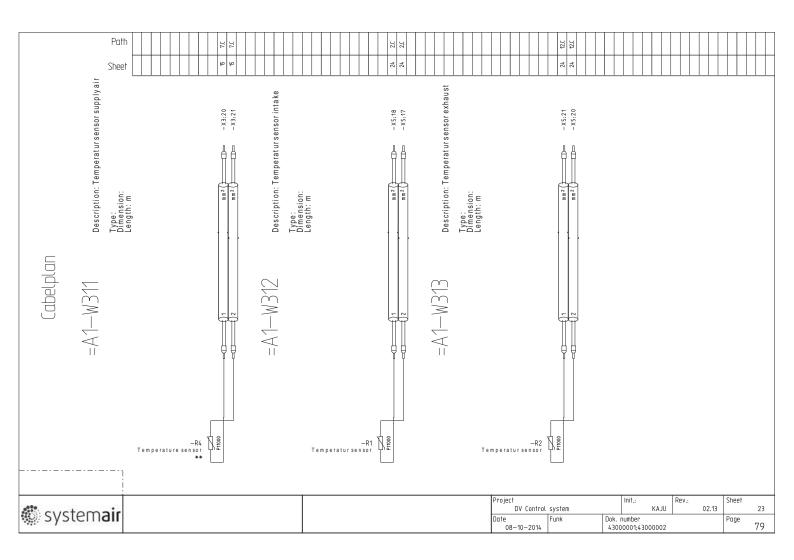


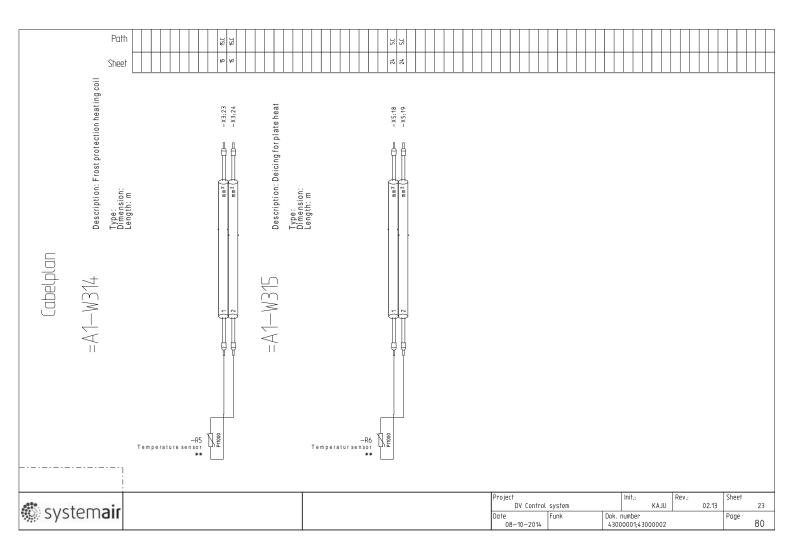


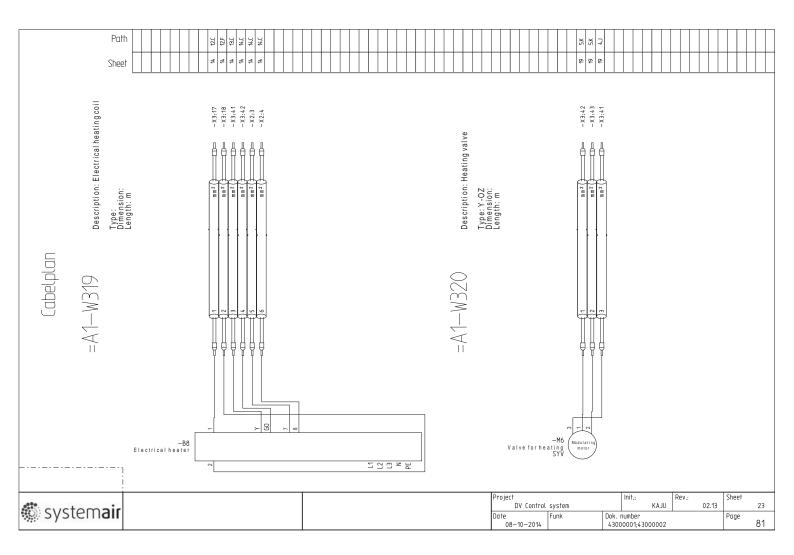


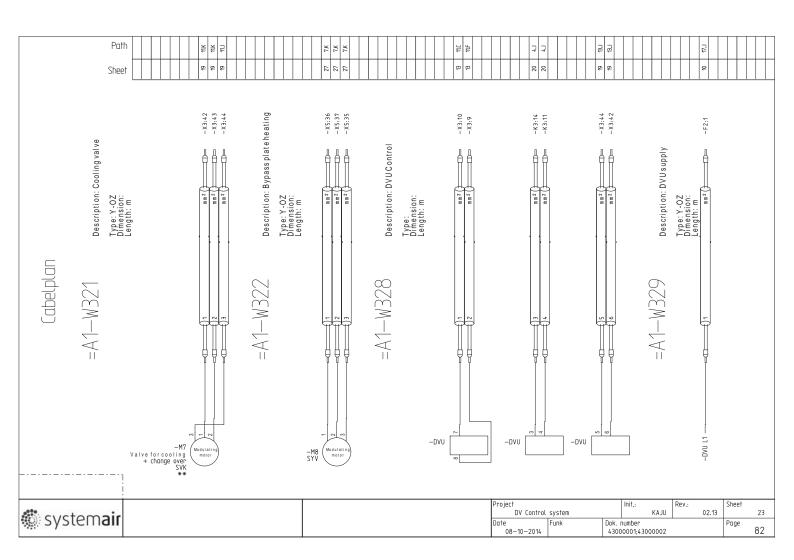


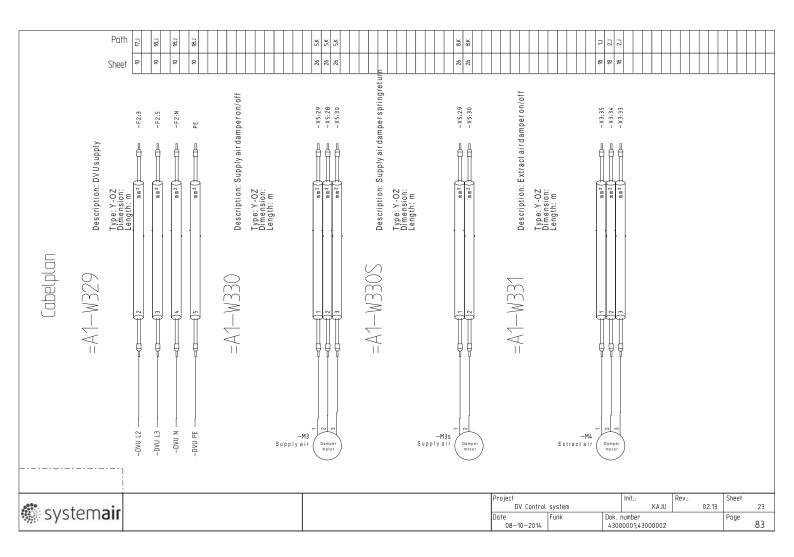


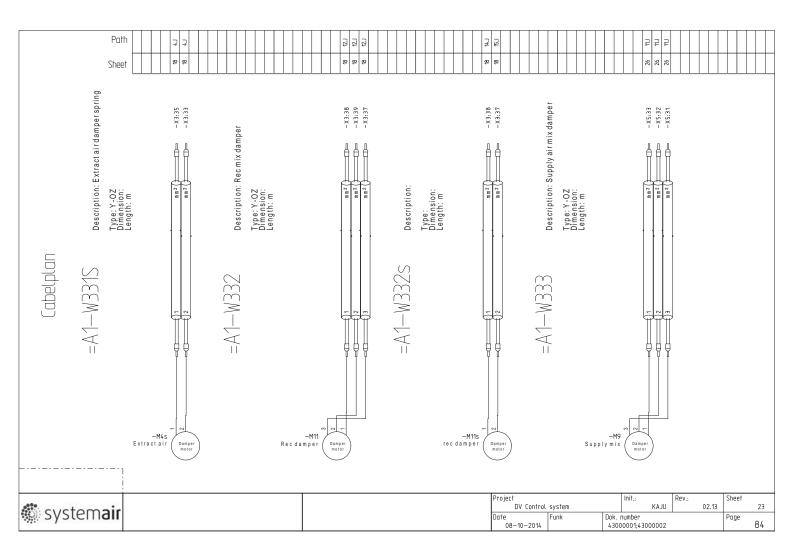


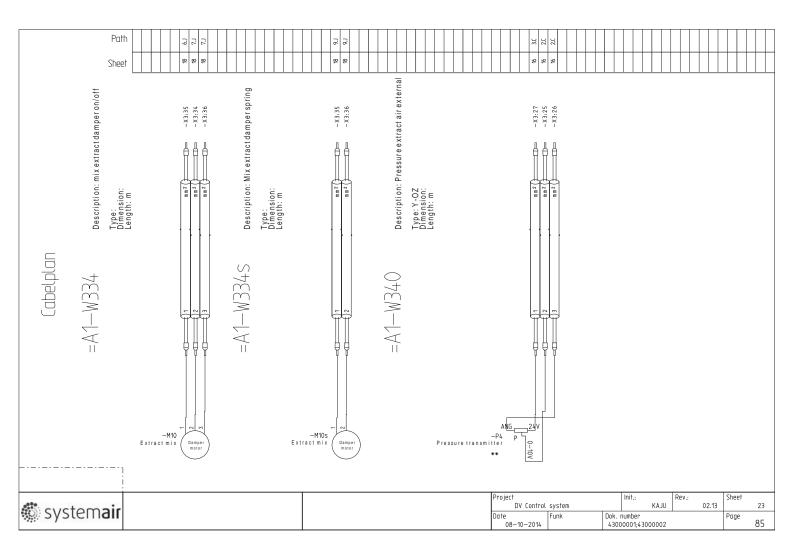


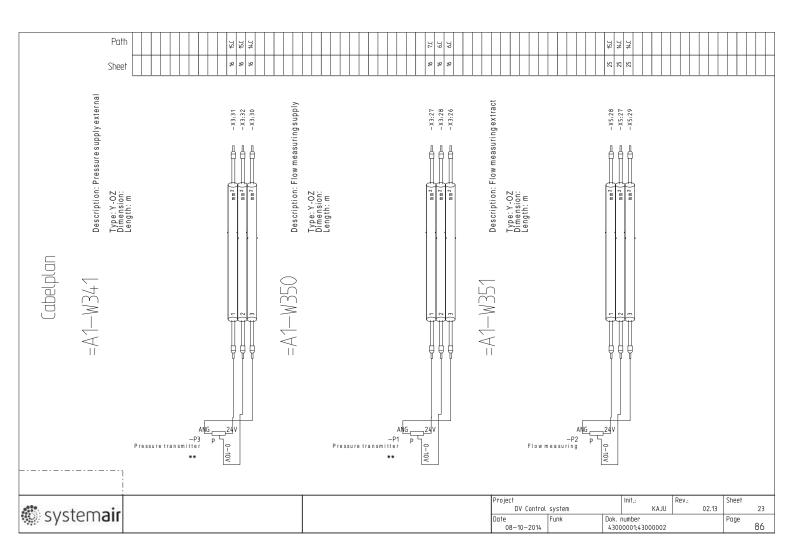


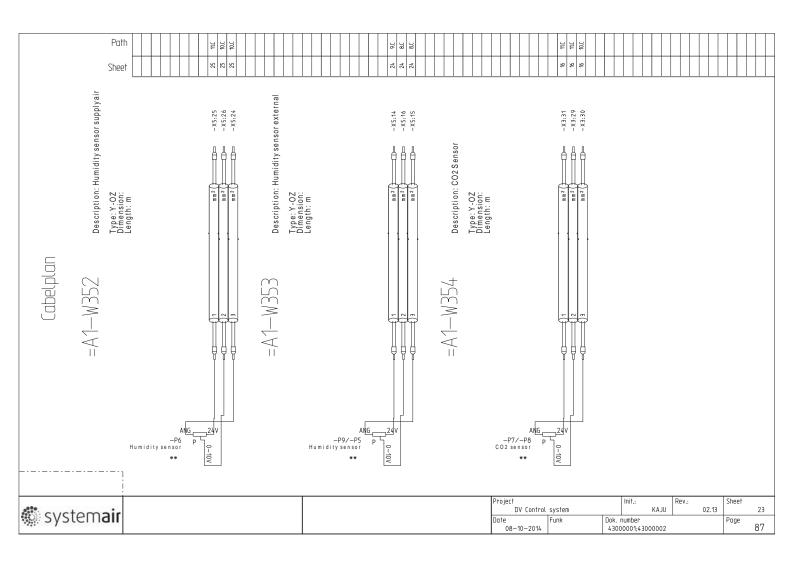


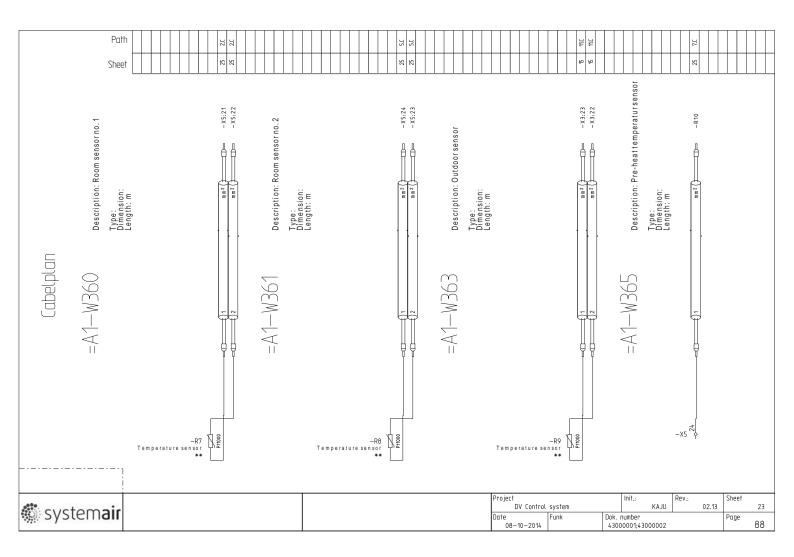


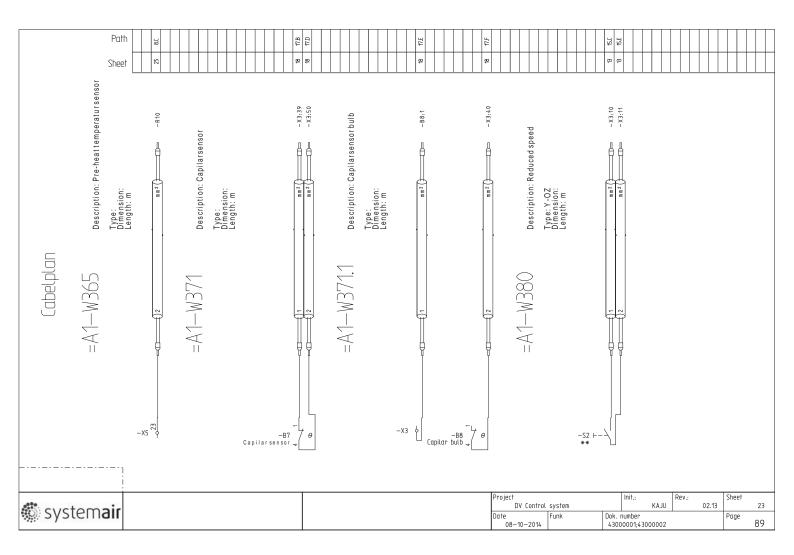


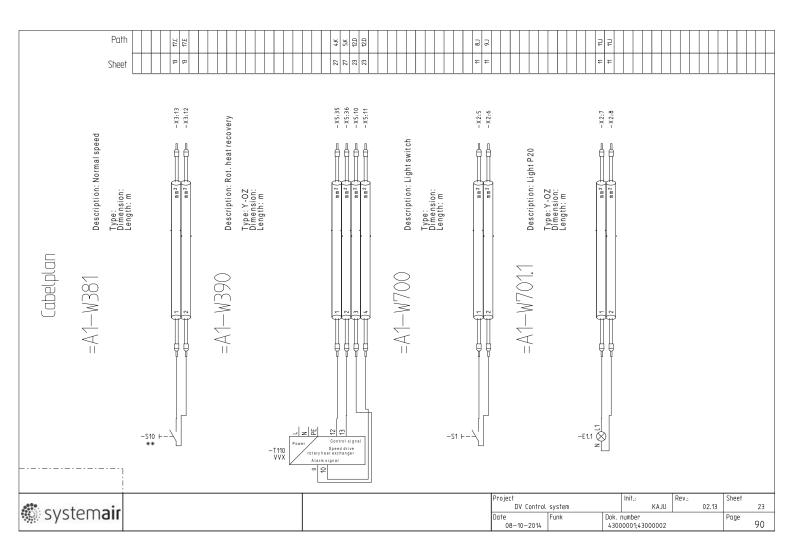


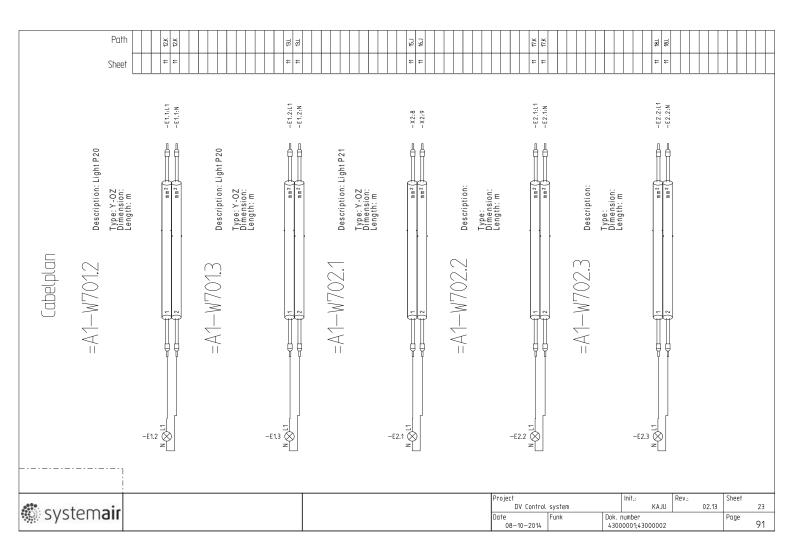


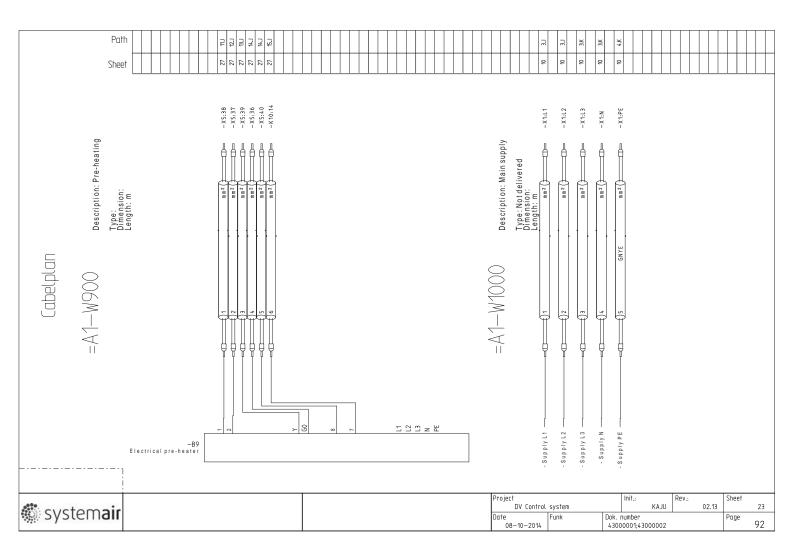




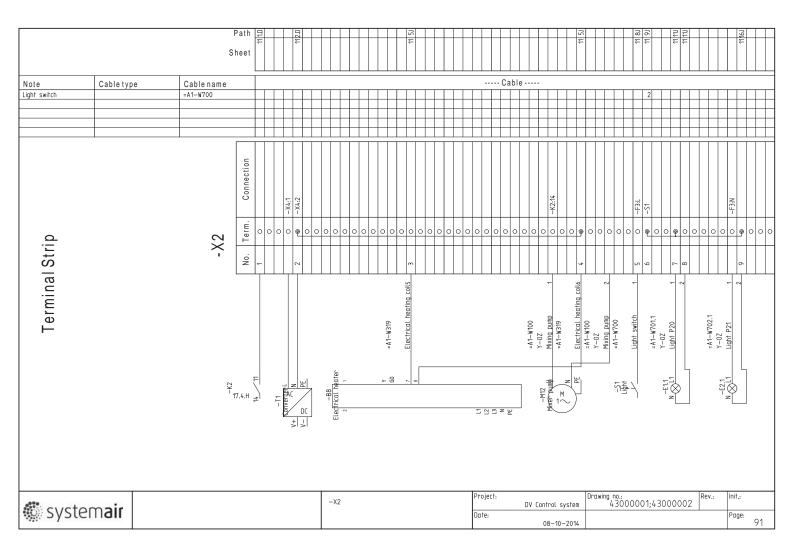


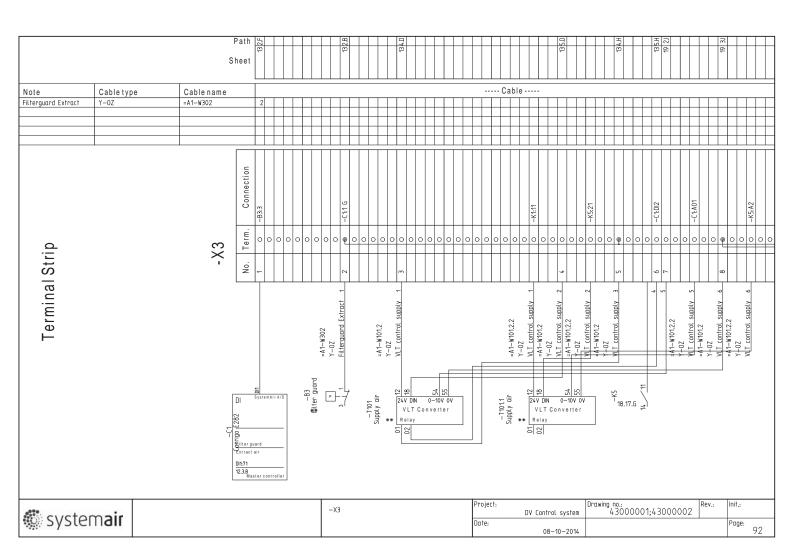


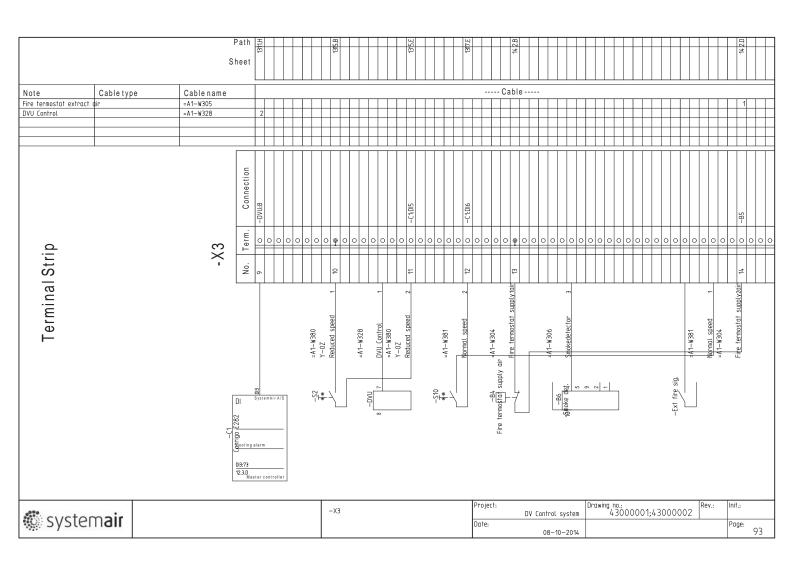


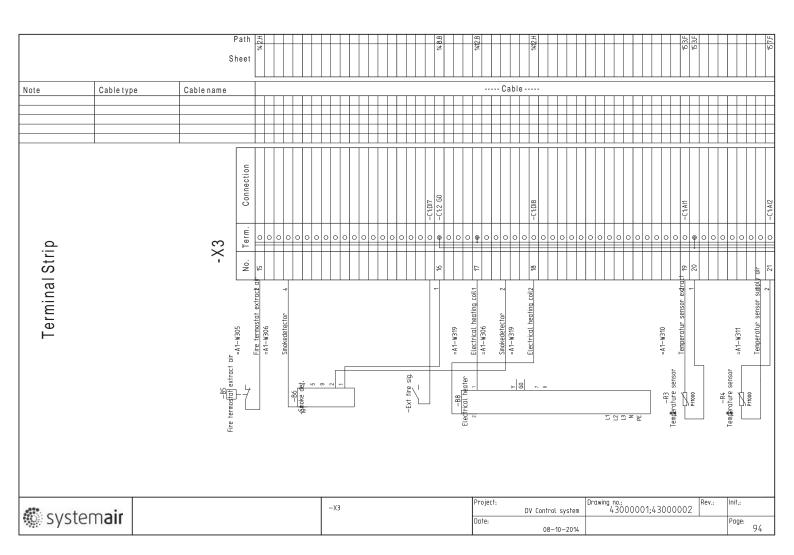


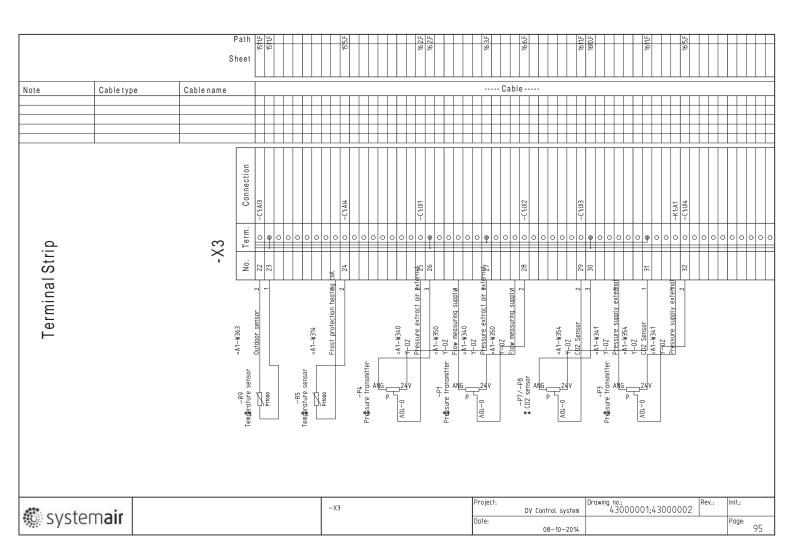
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Note	Cabletype	Cable name		Cable	····· Cable ·····	
Il Strip		× -	<i>-</i>			0000
Terminal Strip		=A1-W1000	Nor delivered Supply L1 Main supply Supply L2 Supply L3	– Supply N		
syster	n air			-X1	DV Control system 43000001;43000002	nit.: Page:

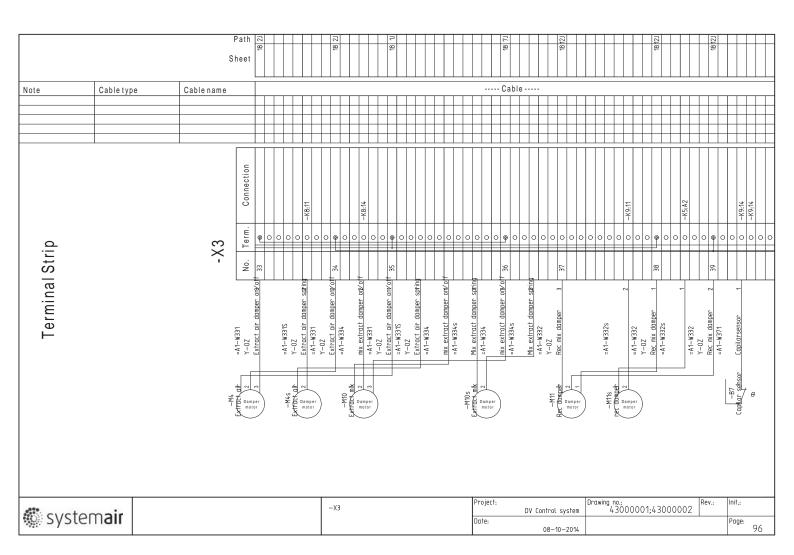




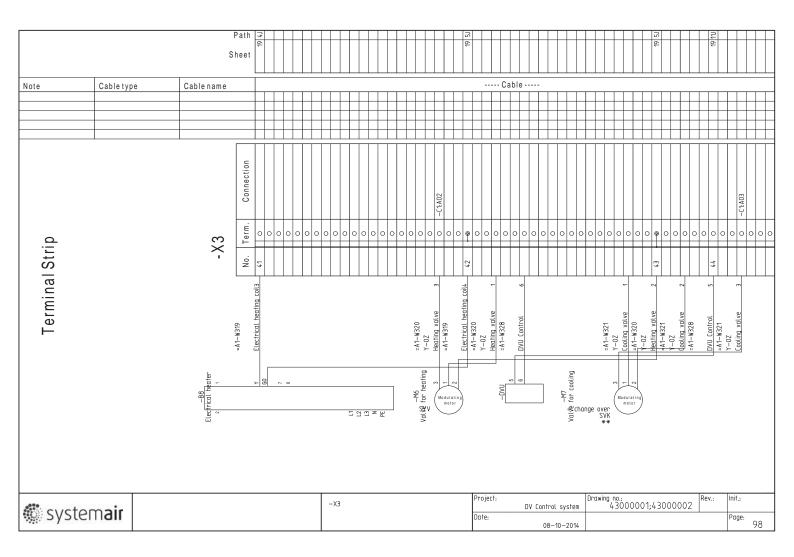




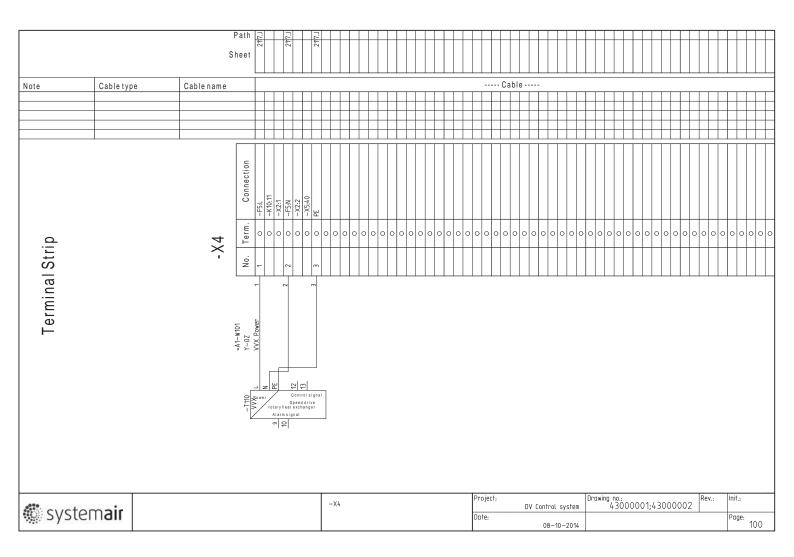


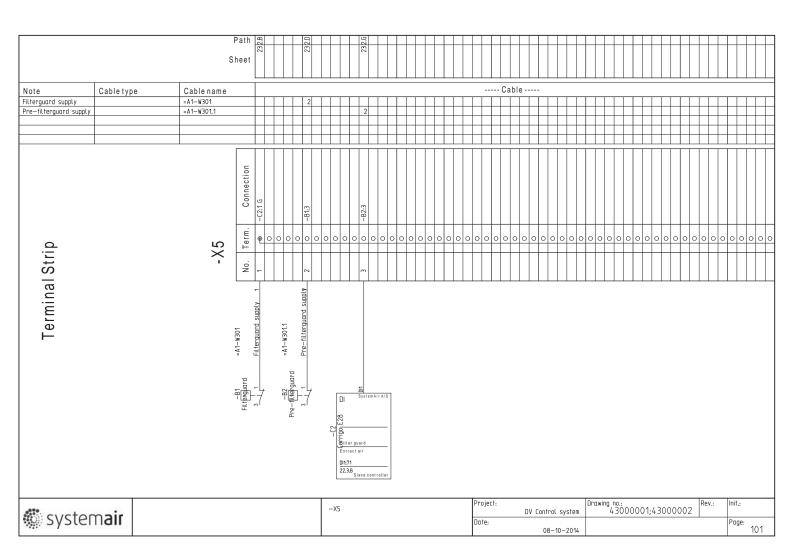


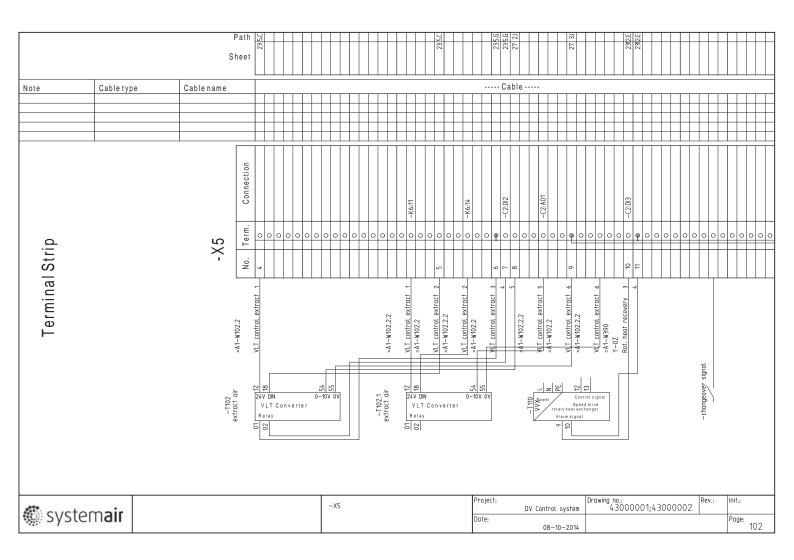
		Path	4.687			
Note	Cable type	Cable name			Cable	
Terminal Strip		-X3 =A1-W3711 No. Term.	0,4			
syste	em air			-X3	Project: DV Control system Date: 08-10-201	Init.: Page:

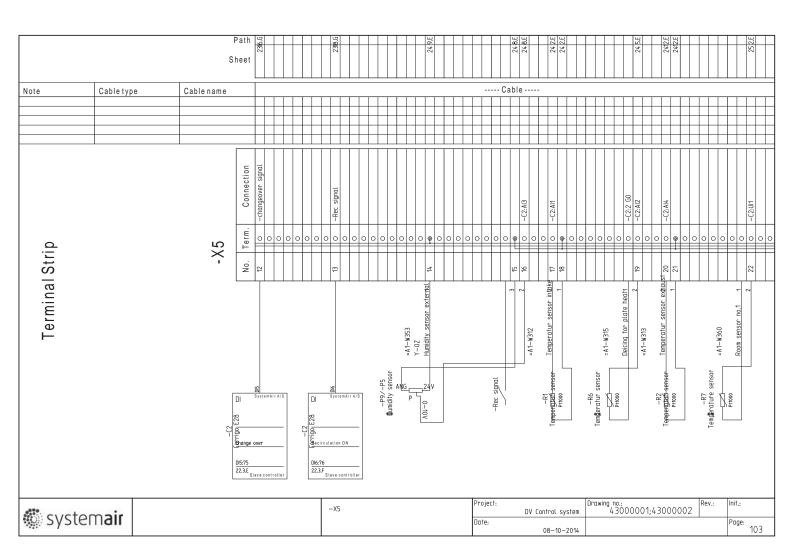


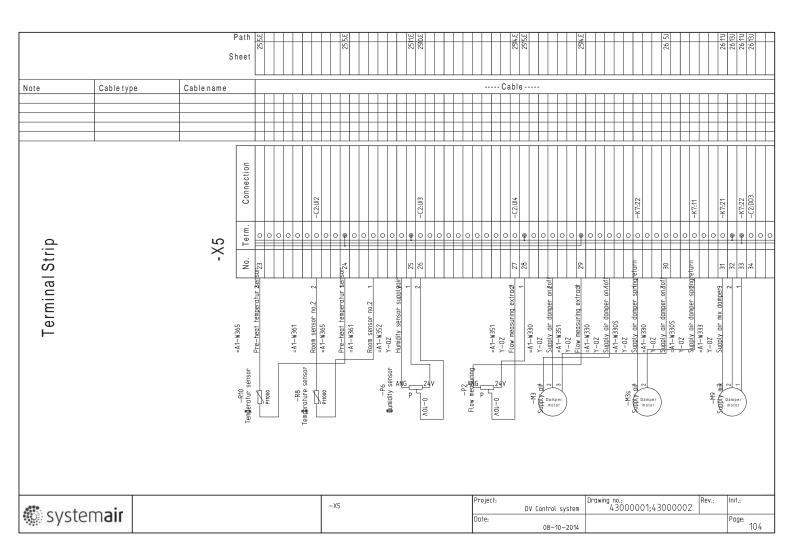
			Path 3700 Sheet	202.F 200.F	20 6.F	187.0													
Note Capilarsensor bulb	Cable type	Cable name =A1-W371.1				1				- Cable									
Terminal Strip		-X3	-A/1-W90 Not detivered No. Term. Connection -Corrigo E0-R 1 G Remote panel 1 45 © -K4.24	0990	64	0000		0000	0000		0000	0000							
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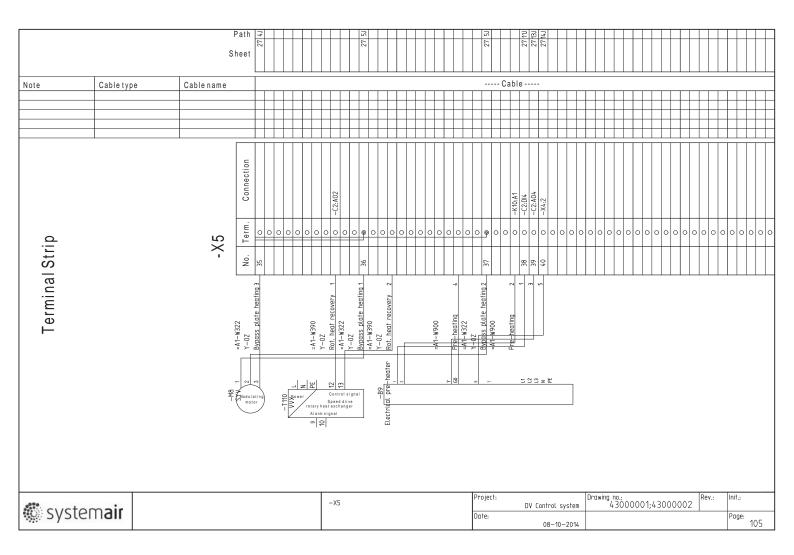














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www.systemair.dk

This manual has part number 90925372